Personal Computer Hardware Reference Library

Technical Reference

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Revised Edition (April 1983)

Changes are periodically made to the information herein; these changes will be incorporated in new editions of this publication.

Products are not stocked at the address below. Requests for copies of this product and for technical information about the system should be made to your authorized IBM Personal Computer dealer.

A Reader's Comment Form is provided at the back of this publication. If this form has been removed, address comments to: IBM Corp., Personal Computer, P.O. Box 1328-C, Boca Raton, Florida 33432. IBM may use or distribute any of the information you supply in any way it believes appropriate without incurring any obligations whatever.

PREFACE

The IBM Personal Computer Technical Reference manual describes the hardware design and provides interface information for the IBM Personal Computer. This publication also has information about the basic input/output system (BIOS) and programming support.

The information in this publication is both introductory and for reference, and is intended for hardware and software designers, programmers, engineers, and interested persons who need to understand the design and operation of the computer.

You should be familiar with the use of the Personal Computer, and you should understand the concepts of computer architecture and programming.

This manual has two sections:

"Section 1: Hardware" describes each functional part of the system. This section also has specifications for power, timing, and interface. Programming considerations are supported by coding tables, command codes, and registers.

"Section 2: ROM BIOS and System Usage" describes the basic input/output system and its use. This section also contains the software interrupt listing, a BIOS memory map, descriptions of vectors with special meanings, and a set of low memory maps. In addition, keyboard encoding and usage is discussed.

The publication has seven appendixes:

Appendix A: ROM BIOS Listings
Appendix B: 8088 Assembly Instruction Set Reference
Appendix C: Of Characters, Keystrokes, and Color
Appendix D: Logic Diagrams
Appendix E: Specifications
Appendix F: Communications
Appendix G: Switch Settings

A glossary and bibliography are included.

Prerequisite Publication:

Guide to Operations for the IBM Personal Computer
Part Number 6025000

Suggested Reading:

BASIC for the IBM Personal Computer
Part Number 6025010

Disk Operating System (DOS) for the IBM Personal Computer
Part Number 6024061

Hardware Maintenance and Service for the IBM Personal Computer
Part Number 6025072

MACRO Assembler for the IBM Personal Computer
Part Number 6024002

Related publications are listed in the bibliography.

TABLE OF CONTENTS

Section 1: Hardware

Section 2: ROM BIOS and System Usage

INDEX TAB LISTING

Hardware

BIOS

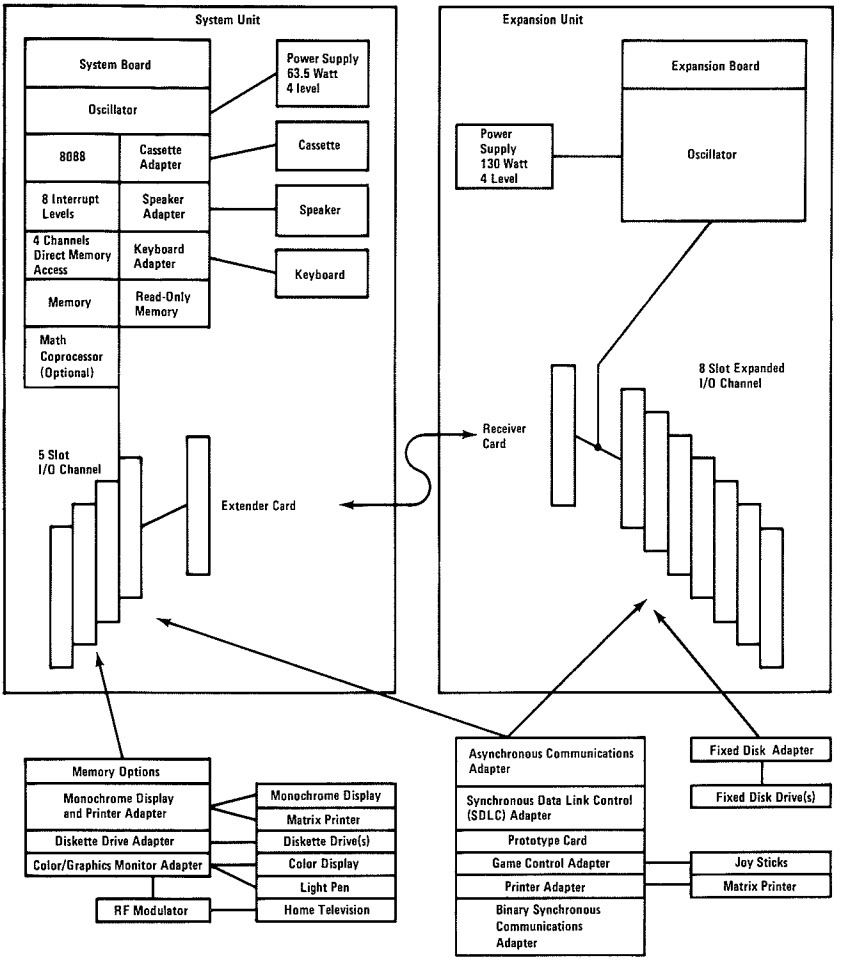
Appendix A

Appendix B

Appendix C

Appendix D

SECTION 1: HARDWARE



System Block Diagram

IBM Personal Computer System Unit

The system unit is the standalone tabletop unit that contains the power supply, the speaker, and the system board.

The system unit contains one of two system boards. One system board supports 16K to 64K of read/write memory. The other system board supports 64K to 256K of read/write memory. Both system boards are functionally identical.

The power supply provides dc voltage to the system board and the internal drive(s).

System Board

The system board fits horizontally in the base of the system unit and is approximately 8-1/2 by 12 inches. It is a multilayer, single-land-per-channel design with ground and internal planes provided. DC power and a signal from the power supply enter the board through two six-pin connectors. Other connectors on the board are for attaching the keyboard, audio cassette, and speaker. Five 62-pin card edge-sockets are also mounted on the board. The I/O channel is bussed across these five I/O slots.

Two dual-in-line package (DIP) switches (two eight-switch packs) are mounted on the board and can be read under program control. The DIP switches provide the system software with information about the installed options, how much storage the system board has, what type of display adapter is installed, what operation modes are desired when power is switched on (color or black-and-white, 80- or 40-character lines), and the number of diskette drives attached.

The system board consists of five functional areas: the processor subsystem and its support elements, the read-only memory (ROM) subsystem, the read/write (R/W) memory subsystem, integrated I/O adapters, and the I/O channel. All are described in this section.

The heart of the system board is the Intel 8088 microprocessor. This processor is an 8-bit external bus version of Intel's 16-bit 8086 processor, and is software-compatible with the 8086. Thus, the 8088 supports 16-bit operations, including multiply and divide, and supports 20 bits of addressing (1 megabyte of storage). It also operates in maximum mode, so a co-processor can be added as a feature. The processor operates at a 4.77 MHz. This frequency, which is derived from a 14.31818-MHz crystal, is divided by 3 for the processor clock, and by 4 to obtain the 3.58-MHz color burst signal required for color televisions.

At the 4.77-MHz clock rate, the 8088 bus cycles are four clocks of 210 ns, or 840 ns. I/O cycles take five 210-ns clocks or 1.05 microseconds.

The processor is supported by a set of high-function support devices providing four channels of 20-bit direct-memory access (DMA), three 16-bit timer-counter channels, and eight prioritized interrupt levels.

Three of the four DMA channels are available on the I/O bus and support high-speed data transfers between I/O devices and memory without processor intervention. The fourth DMA channel is programmed to refresh the system dynamic memory. This is done by programming a channel of the timer-counter device to periodically request a dummy DMA transfer. This action creates a memory-read cycle, which is available to refresh dynamic storage both on the system board and in the system expansion slots. All DMA data transfers, except the refresh channel, take five processor clocks of 210 ns, or 1.05 μs if the processor-ready line is not deactivated. Refresh DMA cycles take four clocks or 840 ns.

The three programmable timer/counters are used by the system as follows: Channel 0 is used as a general-purpose timer providing a constant time base for implementing a time-of-day clock; Channel 1 is used to time and request refresh cycles from the DMA channel; and Channel 2 is used to support the tone generation for the audio speaker. Each channel has a minimum timing resolution of 1.05 us.

Of the eight prioritized levels of interrupt, six are bussed to the system expansion slots for use by feature cards. Two levels are used on the system board. Level 0, the highest priority, is attached to Channel 0 of the timer/counter and provides a periodic interrupt for the time-of-day clock. Level 1 is attached to the keyboard adapter circuits and receives an interrupt for each scan code sent by the keyboard. The non-maskable interrupt (NMI) of the 8088 is used to report memory parity errors.

The system board supports both ROM and R/W memory. It has space for 48K x 8 of ROM or EPROM. Six module sockets are provided, each of which can accept an 8K by 8 byte device. Five of the sockets are populated with 40K bytes of ROM. This ROM contains the cassette BASIC interpreter, cassette operating system, power-on self-test, I/O drivers, dot patterns for 128 characters in graphics mode, and a diskette bootstrap loader. The ROM is packaged in 24-pin modules and has an access time of 250 ns and a cycle time of 375 ns.

The difference between the R/W memory on the two system boards is shown in the following chart.

System Board	Minimum Storage	Maximum Storage	Memory Modules	Soldered (Bank 0)	Pluggable (Bank 1-3)
16/64K	16K	64K	16K by 1 Bit	1 Bank of 9	3 Banks of 9
64/256K	64K	256K	64K by 1 Bit	1 Bank of 9	3 Banks of 9

Memory greater than either system board's maximum is obtained by adding memory cards in the expansion slots. All memory is parity-checked and consists of dynamic 16K by 1 bit or (64K by 1 bit) chips with an access time of 250 ns and a cycle time of 410 ns.

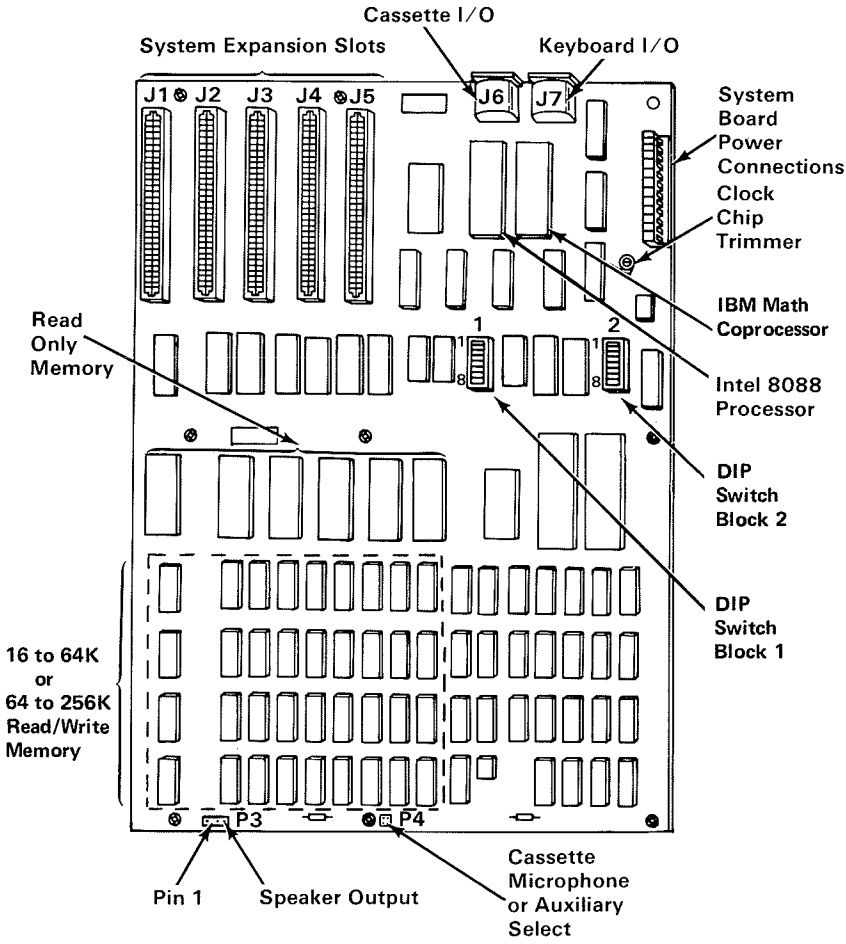
The system board contains circuits for attaching an audio cassette, the keyboard, and the speaker. The cassette adapter allows the attachment of any good quality audio cassette through the earphone output and either the microphone or auxiliary inputs. The system board has a jumper for either input. This interface also provides a cassette motor control line for transport starting and stopping under program control. This interface reads and writes the audio cassette at a data rate of between 1,000 and 2,000 baud. The baud rate is variable and dependent on data content, because a different bit-cell time is used for 0's and 1's. For diagnostic purposes, the tape interface can loop read to write for testing the system board's circuits. The ROM cassette software blocks cassette data and generates a cyclic redundancy check (CRC) to check this data.

The system board contains the adapter circuits for attaching the serial interface from the keyboard. These circuits generate an interrupt to the processor when a complete scan code is received. The interface can request execution of a diagnostic test in the keyboard.

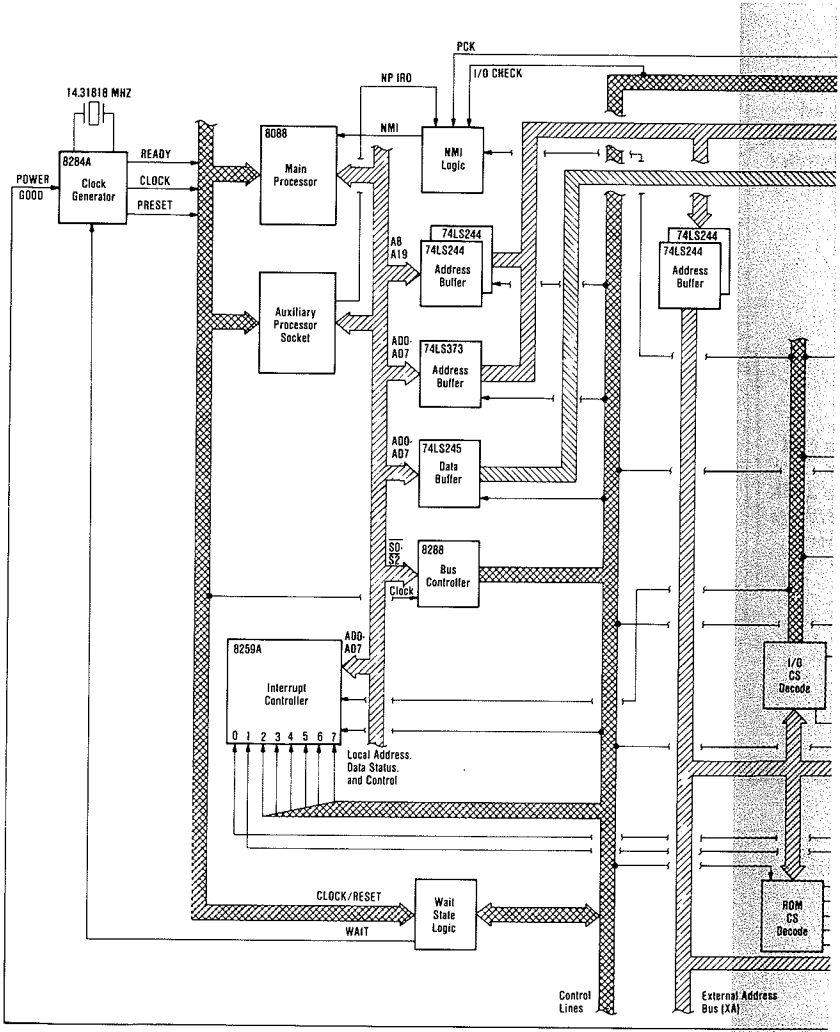
Both the keyboard and cassette interfaces are 5-pin DIN connectors on the system board that extend through the rear panel of the system unit.

The system unit has a 2-1/4 inch audio speaker. The speaker's control circuits and driver are on the system board. The speaker connects through a 2-wire interface that attaches to a 3-pin connector on the system board.

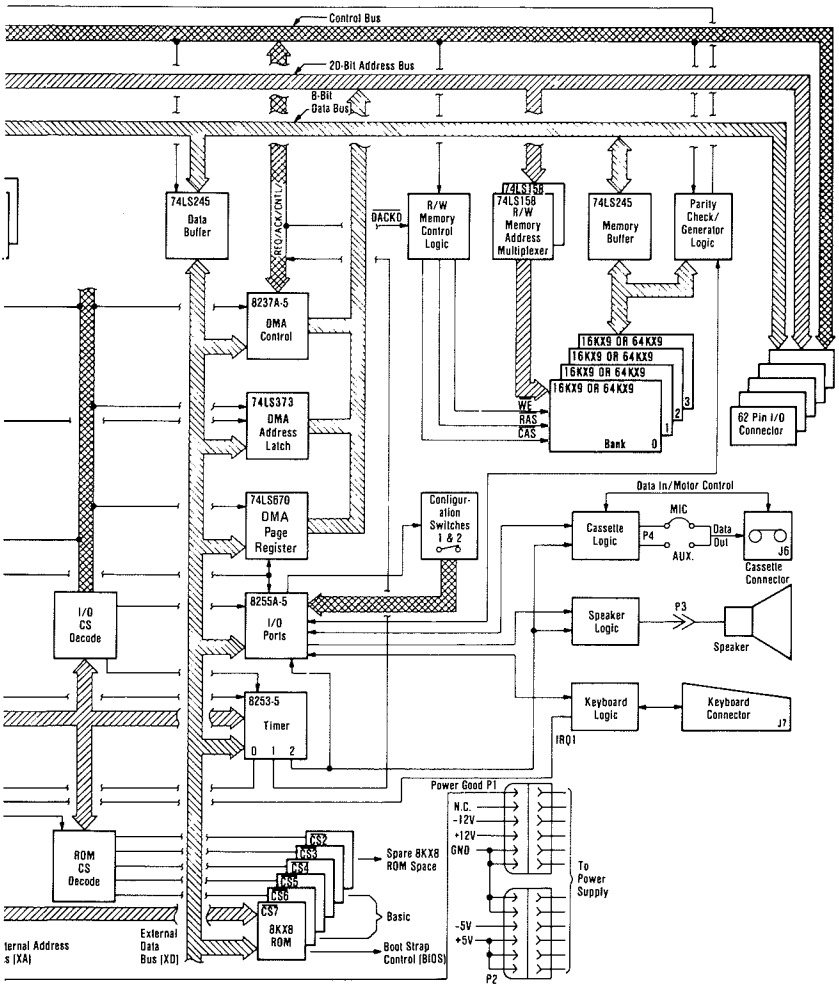
The speaker drive circuit is capable of approximately 1/2 watt of power. The control circuits allow the speaker to be driven three different ways: 1.) a direct program control register bit may be toggled to generate a pulse train; 2.) the output from Channel 2 of the timer counter may be programmed to generate a waveform to the speaker; 3.) the clock input to the timer counter can be modulated with a program-controlled I/O register bit. All three methods may be performed simultaneously.



System Board Component Diagram



System Board Data Flow (Part 1 of 2)



System Board Data Flow (Part 2 of 2)

Hex Range	Usage
000-00F	DMA Chip 8237A-5
020-021	Interrupt 8259A
040-043	Timer 8253-5
060-063	PPI 8255A-5
080-083	DMA Page Registers
0Ax*	NMI Mask Register
0Cx	Reserved
0Ex	Reserved
100-1FF	Not Usable
200-20F	Game Control
210-217	Expansion Unit
220-24F	Reserved
278-27F	Reserved
2F0-2F7	Reserved
2F8-2FF	Asynchronous Communications (Secondary)
300-31F	Prototype Card
320-32F	Fixed Disk
378-37F	Printer
380-38C**	SDLC Communications
380-389**	Binary Synchronous Communications (Secondary)
3A0-3A9	Binary Synchronous Communications (Primary)
3B0-3BF	IBM Monochrome Display/Printer
3C0-3CF	Reserved
3D0-3DF	Color/Graphics
3E0-3F7	Reserved
3F0-3F7	Diskette
3F8-3FF	Asynchronous Communications (Primary)

* At power-on time, the Non Mask Interrupt into the 8088 is masked off. This mask bit can be set and reset through system software as follows:

Set mask: Write hex 80 to I/O Address hex A0 (enable NMI)

Clear mask: Write hex 00 to I/O Address hex A0 (disable NMI)

** SDLC Communications and Secondary Binary Synchronous Communications cannot be used together because their hex addresses overlap.

I/O Address Map

Number	Usage
NMI	Parity
0	Timer
1	Keyboard
2	Reserved
3	Asynchronous Communications (Secondary) SDLC Communications BSC (Secondary)
4	Asynchronous Communications (Primary) SDLC Communications BSC (Primary)
5	Fixed Disk
6	Diskette
7	Printer

8088 Hardware Interrupt Listing

Hex Port Number						
0060	INPUT	PA0	+Keyboard Scan Code	0	IPL 5-1/4 Diskette Drive	(SW1—1)
		1		1	Reserved	(SW1—2)
		2		2	System Board Read/Write Memory Size	*(SW1—3)
		3		3	System Board Read/Write Memory Size	*(SW1—4)
				Or		
		4		4	+Display Type 1	**(SW1—5)
		5		5	+Display Type 2	**(SW1—6)
		6		6	No. of 5-1/4 Drives	***(SW1—7)
		7		7	No. of 5-1/4 Drives	***(SW1—8)
0061	OUTPUT	PB0	+Timer 2 Gate Speaker			
		1	+Speaker Data			
		2	+(Read Read/Write Memory Size) or (Read Spare Key)			
		3	+Cassette Motor Off			
		4	-Enable Read/Write Memory			
		5	-Enable I/O Channel Check			
		6	-Hold Keyboard Clock Low			
		7	-(Enable Keyboard) or + (Clear Keyboard and Enable Sense Switches)			
0062	INPUT	PC0	I/O Read/Write Memory (Sw2—1)	Binary Value X 32K	Or	I/O Read/Write Memory (Sw2—5)
		1	I/O Read/Write Memory (Sw2—2)			
		2	I/O Read/Write Memory (Sw2—3)			
		3	I/O Read/Write Memory (Sw2—4)			
		4	+Cassette Data In			
		5	+Timer Channel 2 Out			
		6	+I/O Channel Check			
		7	+Read/Write Memory Parity Check			

0063 Command/Mode Register

Mode Register Value

Hex 99

7	6	5	4	3	2	1	0
1	0	0	1	1	0	0	1

*

PA3 Sw1—4	PA2 Sw1—3	Amount of Memory Located on System Board
0	0	16K
0	1	32K
1	0	48K
1	1	64 to 256K

**

PA5 Sw1—6	PA4 Sw1—5	Display at Power-Up Mode
0	0	Reserved
0	1	Color 40 X 25 (BW Mode)
1	0	Color 80 X 25 (BW Mode)
1	1	IBM Monochrome (80 X 25)

***

PA7 Sw1—8	PA6 Sw1—7	Number of 5-1/4" Drives in System
0	0	1
0	1	2
1	0	3
1	1	4

Note: A plus (+) indicates a bit value of 1 performs the specified function.
A minus (-) indicates a bit value of 0 performs the specified function.
PA Bit = 0 implies switch "ON." PA bit = 1 implies switch "OFF."

8255A I/O Bit Map

Start Address Decimal	Start Address Hex	Function
0	00000	16 to 64K Read/Write Memory on System Board
16K	04000	
32K	08000	
48K	0C000	
64K	10000	Up to 576K Read/Write Memory in I/O Channel
80K	14000	
96K	18000	
112K	1C000	
128K	20000	
144K	24000	
160K	28000	
176K	2C000	
192K	30000	
208K	34000	
224K	38000	
240K	3C000	
256K	40000	
272K	44000	
288K	48000	
304K	4C000	
320K	50000	
336K	54000	
352K	58000	
368K	5C000	
384K	60000	
400K	64000	
416K	68000	
432K	6C000	
448K	70000	
464K	74000	
480K	78000	
496K	7C000	
512K	80000	
528K	84000	
544K	88000	
560K	8C000	
576K	90000	
592K	94000	
608K	98000	
624K	9C000	

System Memory Map for 16/64K System Board (Part 1 of 2)

Start Address Decimal	Start Address Hex	Function
640K	A0000	128K Reserved
656K	A4000	
672K	A8000	
688K	AC000	
704K	B0000	Monochrome
720K	B4000	
736K	B8000	Color/Graphics
752K	BC000	
768K	C0000	
784K	C4000	
800K	C8000	Fixed Disk Control
816K	CC000	192K Read Only Memory Expansion and Control
832K	D0000	
848K	D4000	
864K	D8000	
880K	DC000	
896K	E0000	
912K	E4000	
928K	E8000	
944K	EC000	
960K	F0000	Reserved
976K	F4000	48K Base System ROM
992K	F8000	
1008K	FC000	

System Memory Map for 16/64K System Board (Part 2 of 2)

Start Address Decimal	Start Address Hex	Function
0	00000	64 to 256K Read/Write Memory on System Board
16K	04000	
32K	08000	
48K	0C000	
64K	10000	
80K	14000	
96K	18000	
112K	1C000	
128K	20000	
144K	24000	
160K	28000	
176K	2C000	
192K	30000	
208K	34000	
224K	38000	
240K	3C000	
256K	40000	Up to 384K Read/Write Memory in I/O Channel Up to 384K in I/O Channel
272K	44000	
288K	48000	
304K	4C000	
320K	50000	
336K	54000	
352K	58000	
368K	5C000	
384K	60000	
400K	64000	
416K	68000	
432K	6C000	
448K	70000	
464K	74000	
480K	78000	
496K	7C000	
512K	80000	
528K	84000	
544K	88000	
560K	8C000	
576K	90000	
592K	94000	
608K	98000	
624K	9C000	

System Memory Map for 64/256K System Board (Part 1 of 2)

Start Address Decimal	Hex	Function
640K	A0000	128K Reserved
656K	A4000	
672K	A8000	
688K	AC000	
704K	B0000	Monochrome
720K	B4000	
736K	B8000	Color/Graphics
752K	BC000	
768K	C0000	
784K	C4000	
800K	C8000	Fixed Disk Control
816K	CC000	192K Read Only Memory Expansion and Control
832K	D0000	
848K	D4000	
864K	D8000	
880K	DC000	
896K	E0000	
912K	E4000	
928K	E8000	
944K	EC000	
960K	F0000	Reserved
976K	F4000	48K Base System ROM
992K	F8000	
1008K	FC000	

System Memory Map for 64/256K System Board (Part 2 of 2)

System Board Switch Settings

All system board switch settings for total system memory, number of diskette drives, and type of display adapter are located in "Appendix G: Switch Settings."

I/O Channel

The I/O channel is an extension of the 8088 microprocessor bus. It is, however, demultiplexed, repowered, and enhanced by the addition of interrupts and direct memory access (DMA) functions.

The I/O channel contains an 8-bit, bidirectional data bus, 20 address lines, 6 levels of interrupt, control lines for memory and I/O read or write, clock and timing lines, 3 channels of DMA control lines, memory refresh timing control lines, a channel-check line, and power and ground for the adapters. Four voltage levels are provided for I/O cards: +5 Vdc, −5 Vdc, +12 Vdc, and −12 Vdc. These functions are provided in a 62-pin connector with 100-mil card tab spacing.

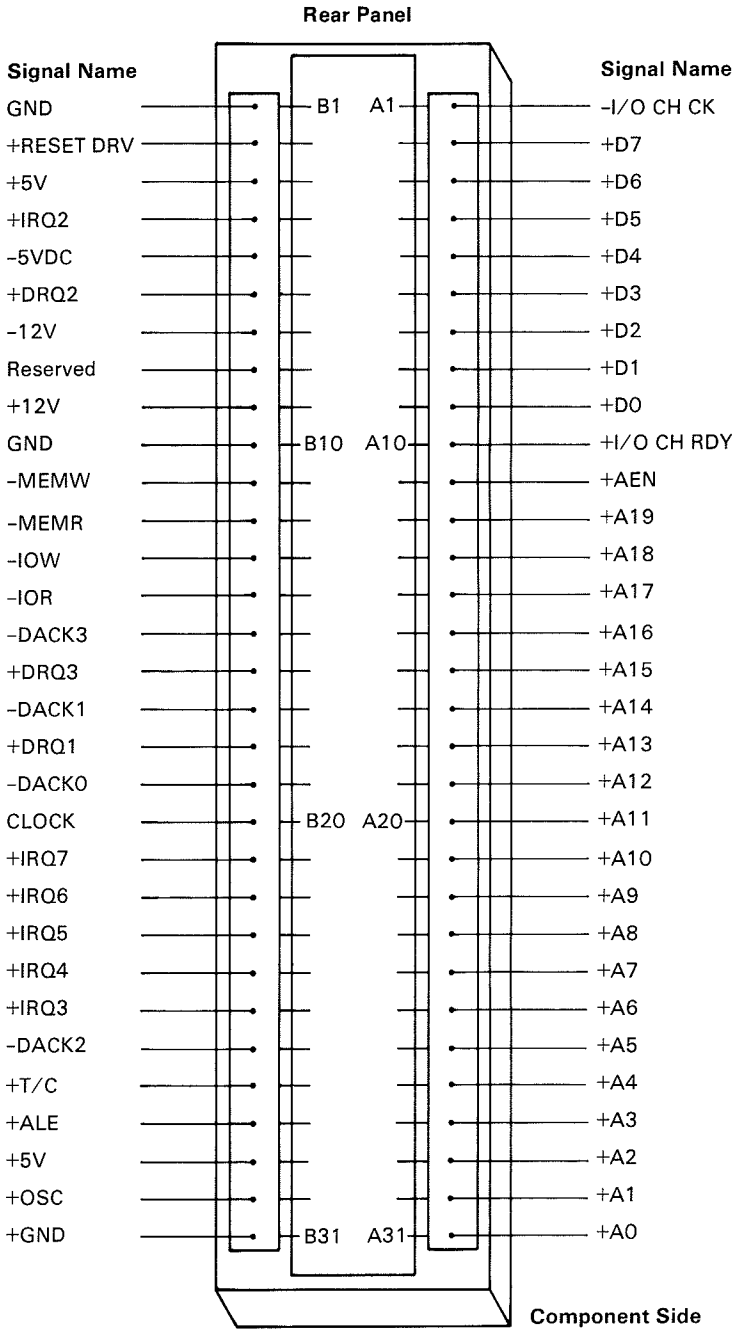
A 'ready' line is available on the I/O channel to allow operation with slow I/O or memory devices. If the channel's ready line is not activated by an addressed device, all processor-generated memory read and write cycles take four 210-ns clock or 840-ns/byte. All processor-generated I/O read and write cycles require five clocks for a cycle time of 1.05 μs/byte. All DMA transfers require five clocks for a cycle time of 1.05 μs/byte. Refresh cycles occur once every 72 clocks (approximately 15 μs) and require four clocks or approximately 7% of the bus bandwidth.

I/O devices are addressed using I/O mapped address space. The channel is designed so that 512 I/O device addresses are available to the I/O channel cards.

A 'channel check' line exists for reporting error conditions to the processor. Activating this line results in a Non-Maskable Interrupt (NMI) to the 8088 processor. Memory expansion options use this line to report parity errors.

The I/O channel is repowered to provide sufficient drive to power all five system unit expansion slots, assuming two low-power Schottky loads per slot. The IBM I/O adapters typically use only one load.

The following pages describe the system board's I/O channel.



I/O Channel Diagram

I/O Channel Description

The following is a description of the IBM Personal Computer I/O Channel. All lines are TTL-compatible.

Signal	I/O	Description
OSC	O	Oscillator: High-speed clock with a 70-ns period (14.31818 MHz). It has a 50% duty cycle.
CLK	O	System clock: It is a divide-by-three of the oscillator and has a period of 210 ns (4.77 MHz). The clock has a 33% duty cycle.
RESET DRV	O	This line is used to reset or initialize system logic upon power-up or during a low line voltage outage. This signal is synchronized to the falling edge of clock and is active high.
A0-A19	O	Address bits 0 to 19: These lines are used to address memory and I/O devices within the system. The 20 address lines allow access of up to 1 megabyte of memory. A0 is the least significant bit (LSB) and A19 is the most significant bit (MSB). These lines are generated by either the processor or DMA controller. They are active high.
D0-D7	I/O	Data Bits 0 to 7: These lines provide data bus bits 0 to 7 for the processor, memory, and I/O devices. D0 is the least significant bit (LSB) and D7 is the most significant bit (MSB). These lines are active high.

Signal	I/O	Description
ALE	O	Address Latch Enable: This line is provided by the 8288 Bus Controller and is used on the system board to latch valid addresses from the processor. It is available to the I/O channel as an indicator of a valid processor address (when used with AEN). Processor addresses are latched with the failing edge of ALE.
$\overline{\text{I/O CH CK}}$	I	-I/O Channel Check: This line provides the processor with parity (error) information on memory or devices in the I/O channel. When this signal is active low, a parity error is indicated.
I/O CH RDY	I	I/O Channel Ready: This line, normally high (ready), is pulled low (not ready) by a memory or I/O device to lengthen I/O or memory cycles. It allows slower devices to attach to the I/O channel with a minimum of difficulty. Any slow device using this line should drive it low immediately upon detecting a valid address and a read or write command. This line should never be held low longer than 10 clock cycles. Machine cycles (I/O or memory) are extended by an integral number of CLK cycles (210 ns).
IRQ2-IRQ7	I	Interrupt Request 2 to 7: These lines are used to signal the processor that an I/O device requires attention. They are prioritized with IRQ2 as the highest priority and IRQ7 as the lowest. An Interrupt Request is generated by raising an IRQ line (low to high) and holding it high until it is acknowledged by the processor (interrupt service routine).

Signal	I/O	Description
$\overline{\text{IOR}}$	O	-I/O Read Command: This command line instructs an I/O device to drive its data onto the data bus. It may be driven by the processor or the DMA controller. This signal is active low.
$\overline{\text{IOW}}$	O	-I/O Write Command: This command line instructs an I/O device to read the data on the data bus. It may be driven by the processor or the DMA controller. This signal is active low.
$\overline{\text{MEMR}}$	O	Memory Read Command: This command line instructs the memory to drive its data onto the data bus. It may be driven by the processor or the DMA controller. This signal is active low.
$\overline{\text{MEMW}}$	O	Memory Write Command: This command line instructs the memory to store the data present on the data bus. It may be driven by the processor or the DMA controller. This signal is active low.
DRQ1-DRQ3	I	DMA Request 1 to 3: These lines are asynchronous channel requests used by peripheral devices to gain DMA service. They are prioritized with DRQ3 being the lowest and DRQ1 being the highest. A request is generated by bringing a DRQ line to an active level (high). A DRQ line must be held high until the corresponding DACK line goes active.
$\overline{\text{DACK0-}}$ $\overline{\text{DACK3}}$	O	-DMA Acknowledge 0 to 3: These lines are used to acknowledge DMA requests (DRQ1-DRQ3) and to refresh system dynamic memory (DACK0). They are active low.

Signal	I/O	Description
AEN	O	Address Enable: This line is used to de-gate the processor and other devices from the I/O channel to allow DMA transfers to take place. When this line is active (high), the DMA controller has control of the address bus, data bus, read command lines (memory and I/O), and the write command lines (memory and I/O).
T/C	O	Terminal Count: This line provides a pulse when the terminal count for any DMA channel is reached. This signal is active high.

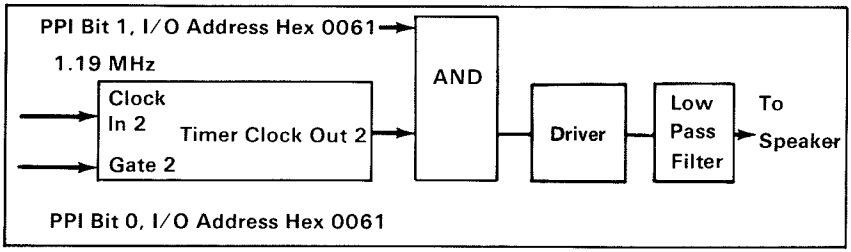
The following voltages are available on the system board I/O channel:

+5 Vdc ±5%, located on 2 connector pins
−5 Vdc ±10%, located on 1 connector pin
+12 Vdc ±5%, located on 1 connector pin
−12 Vdc ±10%, located on 1 connector pin
GND (Ground), located on 3 connector pins

Speaker Interface

The sound system has a small, permanent-magnet, 2-1/4 inch speaker. The speaker can be driven from one or both of two sources:

- An 8255A-5 PPI output bit. The address and bit are defined in the "I/O Address Map."
- A timer clock channel, the output of which is programmable within the functions of the 8253-5 timer when using a 1.19-MHz clock input. The timer gate also is controlled by an 8255A-5 PPI output-port bit. Address and bit assignment are in the "I/O Address Map."



Speaker Drive System Block Diagram

Channel 2 (Tone generation for speaker)	
Gate 2	— Controller by 8255A-5 PPI Bit (See I/O Map)
Clock In 2	— 1.19318 - MHz OSC
Clock Out 2	— Used to drive speaker

Speaker Tone Generation

The speaker connection is a 4-pin Berg connector. See "System Board Component Diagram," earlier in this section, for speaker connection or placement.

Pin	Function
1	Data
2	Key
3	Ground
4	+5 Volts

Speaker Connector

Power Supply

The system power supply is located at the right rear of the system unit. It is designed to be an integral part of the system-unit chassis. Its housing provides support for the rear panel, and its fan furnishes cooling for the whole system.

It supplies the power and reset signal necessary for the operation of the system board, installable options, and the keyboard. It also provides a switched ac socket for the IBM Monochrome Display and two separate connectors for power to the 5-1/4 inch diskette drives.

It is a dc-switching power supply designed for continuous operation at 63.5 watts. It has a fused 120-Vac input and provides four regulated dc output voltages: 7 A of +5 Vdc, 2 A of +12 Vdc, 0.3 A of −5 Vdc, and 0.25 A of −12 Vdc. These outputs are over-voltage, over-current, open-circuit, and short-circuit protected. If a dc overload or over-voltage condition occurs, all dc outputs are shut down as long as the condition exists.

The +5 Vdc powers the logic on the system board and the diskette drives and allows approximately 4 A of +5 Vdc for the adapters in the system-unit expansion slots. The +12 Vdc power level is designed to power the system's dynamic memory and the two internal 5-1/4 inch diskette drive motors. It is assumed that only one drive is active at a time. The −5 Vdc level is designed for dynamic memory bias voltage; it tracks the +5 Vdc and +12 Vdc very quickly at power-on and has a longer decay on power-off than the +5 Vdc and +12 Vdc outputs. The +12 Vdc and −12 Vdc are used for powering the EIA drivers on the communications adapters. All four power levels are bussed across the five system-unit expansion slots.

Operating Characteristics

Input Requirements

The following are the input requirements for the system unit power supply.

Voltage (Vac)			Frequency (Hz)	Current (Amps)
Nominal	Minimum	Maximum	+/- 3Hz	Maximum
120	104	127	60	2.5 at 104 Vac

Vdc Output

The following are the dc outputs for the system unit power supply.

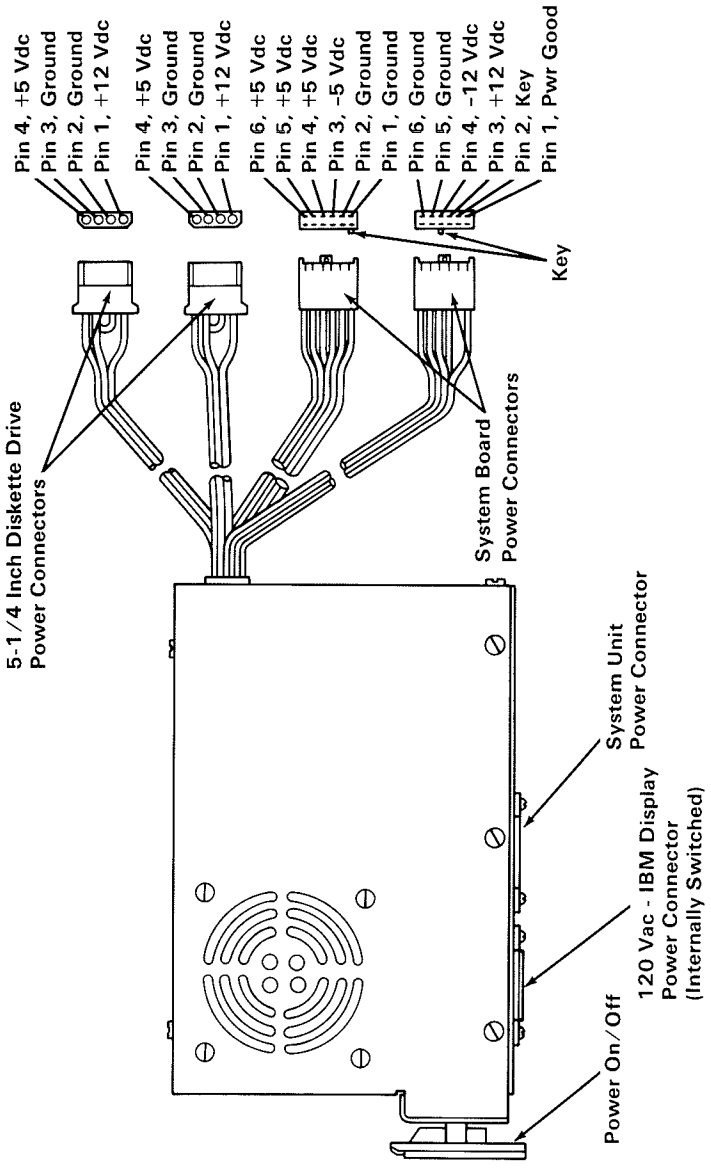
Voltage (Vdc)	Current (Amps)		Regulation (Tolerance)	
Nominal	Minimum	Maximum	+%	-%
+5.0	2.3	7.0	5	4
-5.0	0.0	0.3	10	8
+12.0	0.4	2.0	5	4
-12.0	0.0	0.25	10	9

Vac Output

The power supply provides a filtered, ac output that is switched on and off with the main power switch. The maximum current available at this output is 0.75 A. The recepticle provided at the rear of the power supply for this ac output is a nonstandard connector designed to be used only for the IBM Monochrome Display.

Power Supply Connectors and Pin Assignments

The power connector on the system board is a 12-pin male connector that plugs into the power-supply connectors. The pin configurations and locations are shown below:



Power Supply and Connectors

Over-Voltage/Over-Current Protection

The system power supply employs protection features which are described below.

Primary (Input)

The following table describes the primary (input voltage) protection for the system-unit power supply.

Voltage (Nominal Vac)	Type Protection	Rating (Amps)
120	Fuse	2

Secondary (Output)

On over-voltage, the power supply is designed to shut down all outputs when either the +5 Vdc or the +12 Vdc output exceeds 200% of its maximum rated voltage. On over-current, the supply will turn off if any output exceeds 130% of its nominal value.

Power-Good Signal

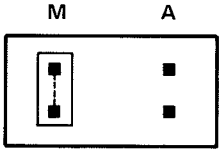
When the power supply is turned on after it has been off for a minimum of 5 seconds, it generates a power-good signal which indicates that there is adequate power for processing. When the four output voltages are above the minimum sense levels, as described below, the signal sequences to a TTL-compatible up level (2.4 Vdc to 5.5 Vdc), which is capable of sourcing 60 μA. When any of the four output voltages is below its minimum sense level or above its maximum sense level, the power good signal will be a TTL-compatible down level (0.0 Vdc to 0.4 Vdc) capable of sourcing 500 μA. The power good signal has a turn-on delay of 100 ms after the output voltages have reached their respective minimum sense levels.

Output Voltage	Under-Voltage Nominal Sense Level	Over-Voltage Nominal Sense Level
+5 Vdc	+4.0 Vdc	+5.9 Vdc
-5 Vdc	-4.0 Vdc	-5.9 Vdc
+12 Vdc	+9.6 Vdc	+14.2 Vdc
-12 Vdc	-9.6 Vdc	-14.2 Vdc

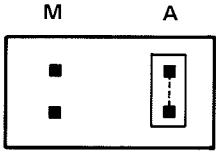
Cassette Interface

The cassette interface is controlled through software. An output from the 8253 timer controls the data to the cassette recorder through pin 5 of the cassette DIN connector at the rear of the system board. The cassette input data is read by an input port bit of the 8255A-5 programmable peripheral interface (8255A-5 PPI). This data is received through pin 4 of the cassette connector. Software algorithms are used to generate and read cassette data. The cassette drive motor is controlled through pins 1 and 3 of the cassette connector. The drive motor on/off switching is controlled by an 8255A-5 PPI output-port bit (hex 61, bit 3). The 8255A-5 address and bit assignments are defined in "I/O Address Map" earlier in this section.

A 2 by 2 Berg pin and a jumper are used on the cassette 'data out' line. The jumper allows use of the 'data out' line as a 0.075-Vdc microphone input when placed across the M and C pins of the Berg connector. A 0.68-Vdc auxiliary input to the cassette recorder is available when the jumper is placed across the A and C pins of the Berg connector. The "System Board Component Diagram" shows the location of the cassette Berg pins.



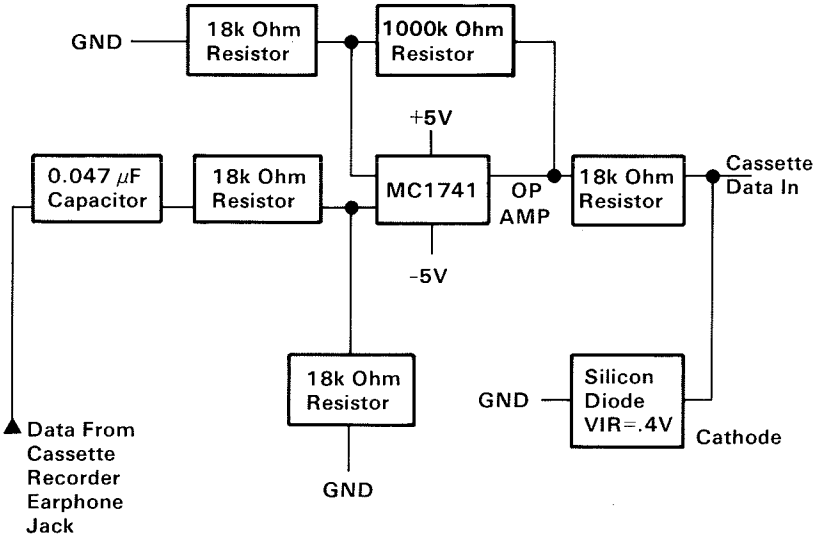
Microphone Input
(0.075 Vdc)



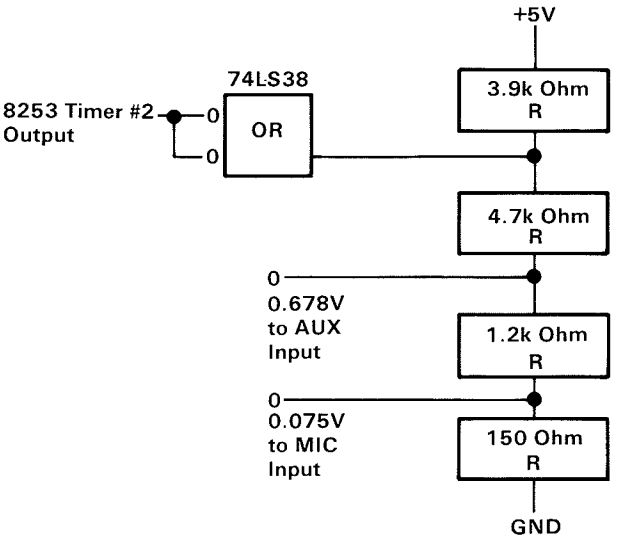
Auxiliary Input
(0.68 Vdc)

Cassette Circuit Block Diagrams

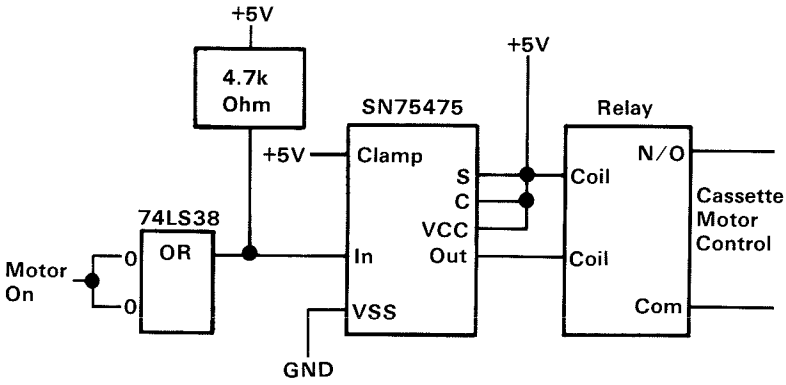
Circuit block diagrams for the cassette-interface read hardware, write hardware, and motor control are illustrated below.



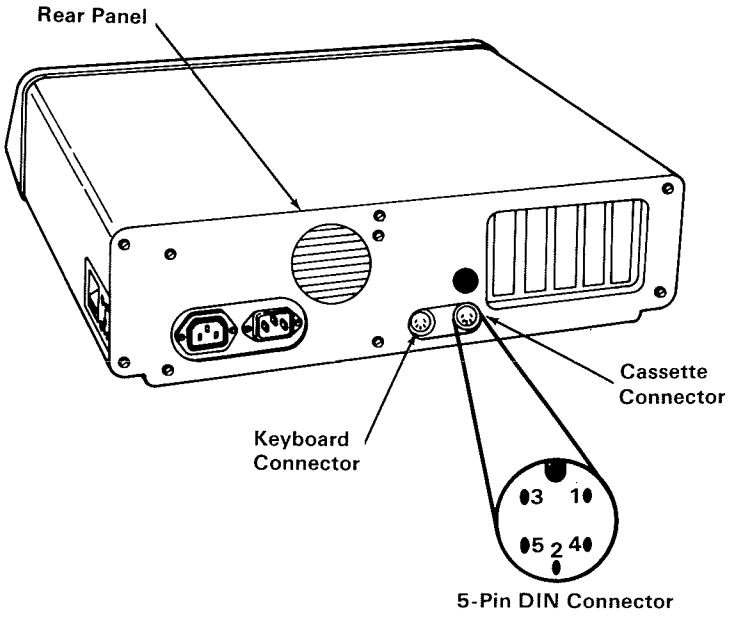
Cassette Interface Read Hardware Block Diagram



Cassette Interface Write Hardware Block Diagram



Cassette Motor Control Block Diagram



Pin	Signal	Electrical Characteristics
1	Motor Control	Common from Relay
2	Ground	
3	Motor Control	Relay N.O. (6 Vdc at 1A)
4	Data In	500nA at ±13V - at 1,000 - 2,000 Baud
5	Data Out (Microphone or Auxiliary)	250 μA at 0.68 Vdc or ** 0.075 Vdc

*All voltages and currents are maximum ratings and should not be exceeded.

**Data out can be chosen using a jumper located on the system board. (Auxiliary → 0.68 Vdc or Microphone → 0.075 Vdc).

Interchange of these voltages on the cassette recorder could lead to damage of recorder inputs.

Cassette Interface Connector Specifications

Notes:

IBM Personal Computer Math Coprocessor

The IBM Personal Computer Math Coprocessor enables the IBM Personal Computer to perform high speed arithmetic, logarithmic functions, and trigonometric operations with extreme accuracy.

The coprocessor works in parallel with the processor. The parallel operation decreases operation time by allowing the coprocessor to do mathematical calculations while the processor continues to do other functions.

The first five bits of every instruction opcode for the coprocessor are identical (11011 binary). When the processor and the coprocessor see this instruction opcode, the processor calculates the address, of any variables in memory, while the coprocessor checks the instruction. The coprocessor will then take the memory address from the processor if necessary. To access locations in memory, the coprocessor takes the local bus from the processor when the processor finishes its current instruction. When the coprocessor is finished with the memory transfer, it returns the local bus to the processor.

The IBM Math Coprocessor works with seven numeric data types divided into the three classes listed below.

- Binary integers (3 types)
- Decimal integers (1 type)
- Real numbers (3 types)

Programming Interface

The coprocessor extends the data types, registers, and instructions to the processor.

The coprocessor has eight 80-bit registers which provide the equivalent capacity of 40 16-bit registers found in the processor. This register space allows constants and temporary results to be held in registers during calculations, thus reducing memory access and improving speed as well as bus availability. The register space can be used as a stack or as a fixed register set. When used as a stack, only the top two stack elements are operated on: when used as a fixed register set, all registers are operated on. The Figure below shows representations of large and small numbers in each data type.

Data Type	Bits	Significant Digits (Decimal)	Approximate Range (decimal)
Word Integer	16	4	$-32{,}768 \leq X \leq +32{,}767$
Short Integer	32	9	$-2\times10^{9} \leq X \leq +2\times10^{9}$
Long Integer	64	18	$-9\times10^{18} \leq X \leq +9\times10^{18}$
Packed Decimal	80	18	-99...99 $\leq X \leq$ +99...99 (18 digits)
Short Real*	32	6-7	$8.43\times10^{-37} \leq \|X\| \leq 3.37\times10^{38}$
Long Real*	64	15-16	$4.19\times10^{-307} \leq \|X\| \leq 1.67\times10^{308}$
Temporary Real	80	19	$3.4\times10^{-4932} \leq \|X\| \leq 1.2\times10^{4932}$

*The short and long real data types correspond to the single and double precision data types

Data Types

Hardware Interface

The coprocessor utilizes the same clock generator and system bus interface components as the processor. The coprocessor is wired directly into the processor, as shown in the coprocessor interconnection diagram. The processor's queue status lines (QS0 and QS1) enable the coprocessor to obtain and decode instructions simultaneously with the processor. The coprocessor's busy signal informs the processor that it is executing; the processor's WAIT instruction forces the processor to wait until the coprocessor is finished executing (wait for NOT BUSY).

When an incorrect instruction is sent to the coprocessor (for example; divide by zero or load a full register), the coprocessor can signal the processor with an interrupt. There are three conditions that will disable the coprocessor interrupt to the processor:

1. Exception and Interrupt Enable bits of the control word are set to 1's.

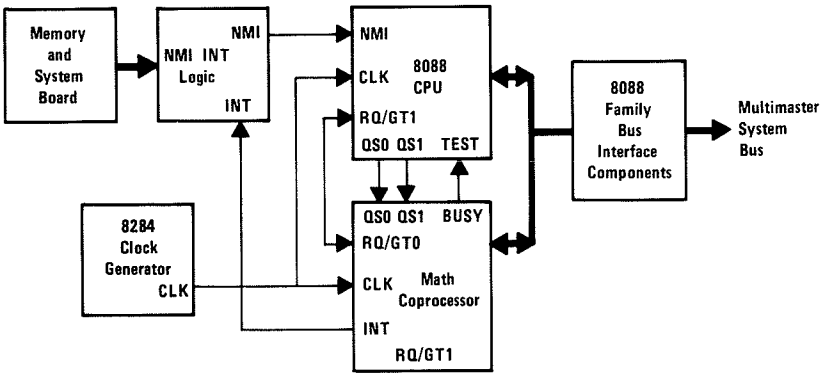
2. System board switch block 1 switch 2 set in the On position.

3. NMI Mask REG is set to zero.

At power-on time the NMI Mask REG is cleared to disable the NMI. Any software using the coprocessor's interrupt capability must ensure that conditions 2 and 3 are never met during the operation of the software or an "Endless Wait" will occur. An "Endless Wait" will have the processor waiting for the "Not Busy" signal from the coprocessor while the coprocessor is waiting for the processor to interrupt.

Because a memory parity error may also cause an interrupt to the 8088 NMI line, the program should check that a parity error did not occur (by reading the 8255 port), then clear exceptions by executing the FNSAVE or the FNCLEX instruction. In most cases, the status word would be looked at, and the exception would be identified and acted upon.

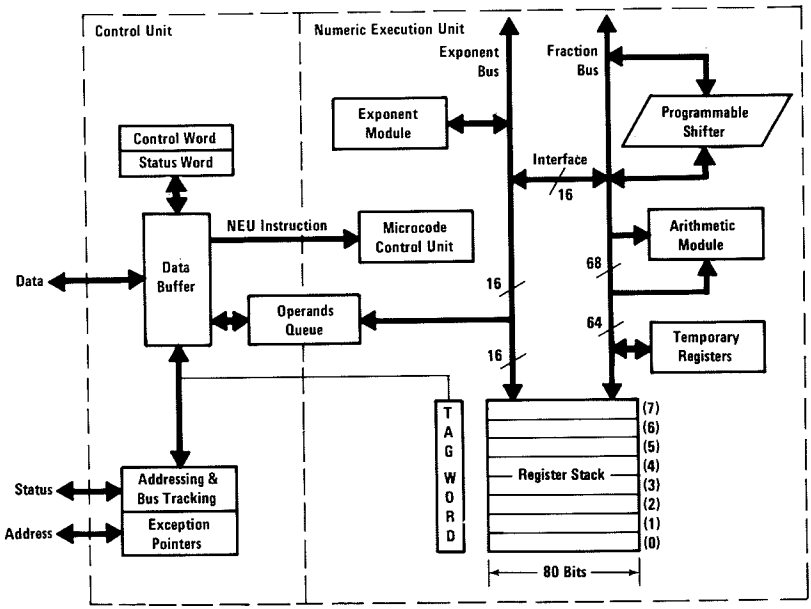
The NMI Mask REG and the coprocessors interrupt are tied to the NMI line through the NMI interrupt logic. Minor conversions of software designed for use with an 8087 must be made before existing software will be compatible with the IBM Personal Computer Math Coprocessor.



Coprocessor Interconnection

Control Unit

The control unit (CU) of the coprocessor and the processor fetch all instructions at the same time, as well as every byte of the instruction stream at the same time. The simultaneous fetching allows the coprocessor to know what the processor is doing at all times. This is necessary to keep a coprocessor instruction from going unnoticed. Coprocessor instructions are mixed with processor instructions in a single data stream. To aid the coprocessor in tracking the processor, nine status lines are interconnected (QS0, QS1, and S0 through S6).



Coprocessor Block Diagram

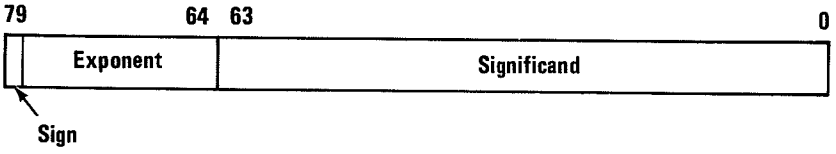
Register Stack

Each of the eight registers in the coprocessor's register stack is 80 bits wide, and each is divided into the "fields" shown in the figure below. The format in the figure below corresponds to the coprocessor's temporary real data type that is used for all calculations.

The ST field in the status word identifies the current top-of-stack register. A load ("push") operation decreases ST by 1 and loads a new value into the top register. A store operation stores the value from the current top register and then increases ST by 1. Thus, the coprocessor's register stack grows "down" toward lower-addressed registers.

Instructions may address registers either implicitly or explicitly. Instructions that operate at the top of the stack, implicitly address the register pointed to by ST. The instruction, FSQRT, replaces the number at the top with its square root; this instruction takes no operands, because the top-of-stack register is implied as the operand. Other instructions specify the register that is to be used. Explicit register addressing is "top-relative." The expression, ST, denotes the current stack top, and ST(i) refers to the ith register from the ST in the stack. If ST contains "binary 011" (register 3 is at the top of the stack), the instruction, FADD ST,ST(2), would add registers 3 and 5.

Passing subroutine parameters to the register stack eliminates the need for the subroutine to know which registers actually contain the parameters. This allows different routines to call the same subroutine without having to observe a convention for passing parameters in dedicated registers. As long as the stack is not full, each routine simply loads the parameters to the stack and calls the subroutine.



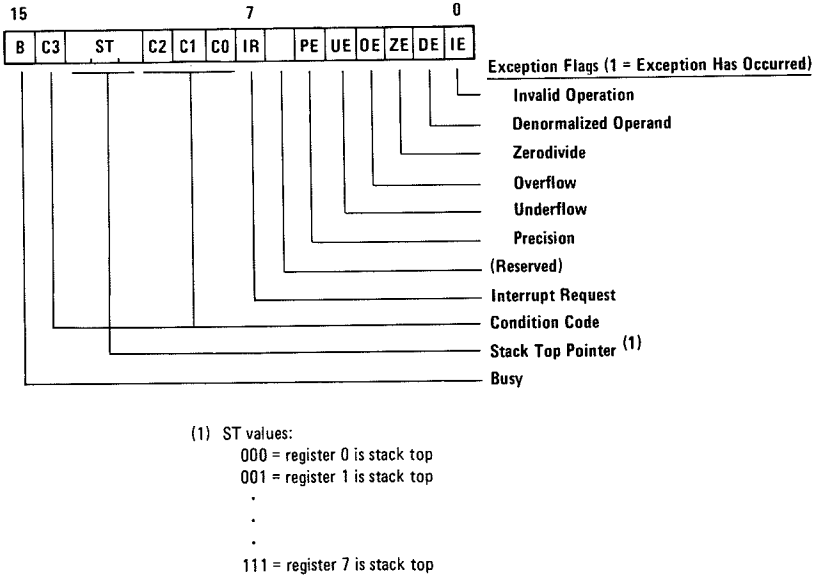
Register Structure

Status Word

The status word reflects the overall condition of the coprocessor. It may be stored in memory with a coprocessor instruction then inspected with a processor code. The status word is divided into the fields shown in the figure below. Bit 15 (BUSY) indicates when the coprocessor is executing an instruction (B=1) or when it is idle (B=0).

Several instructions (for example, the comparison instructions) post their results to the condition code (bits 14 and 10 through 8 of the status word). The main use of the condition code is for conditional branching. This may be accomplished by first executing an instruction that sets the condition code, then storing the status word in memory, and then examining the condition code with processor instructions.

Bits 13 through 11 of the status word point to the coprocessor register that is the current stack top (ST). Bit 7 is the interrupt request field, and bits 5 through 0 are set to indicate that the numeric execution unit has detected an exception while executing the instruction.

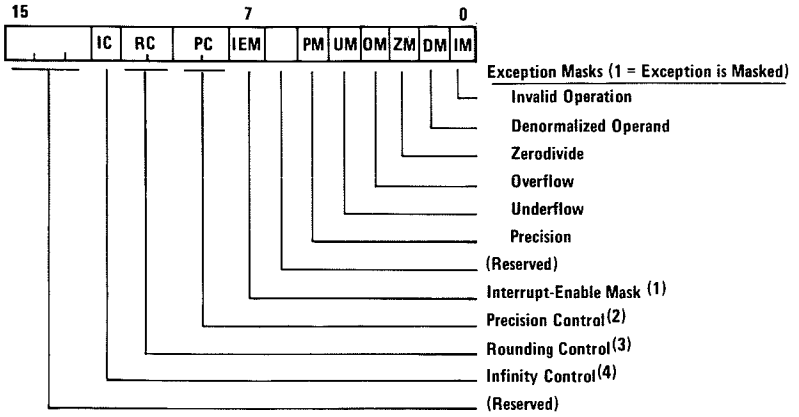


(1) ST values:
000 = register 0 is stack top
001 = register 1 is stack top
.
.
.
111 = register 7 is stack top

Status Word Format

Control Word

The coprocessor provides several options that, are selected by loading a control word register.



(1) Interrupt-Enable Mask:
- 0 = Interrupts Enabled
- 1 = Interrupts Disabled (Masked)

(2) Precision Control:
- 00 = 24 bits
- 01 = (reserved)
- 10 = 53 bits
- 11 = 64 bits

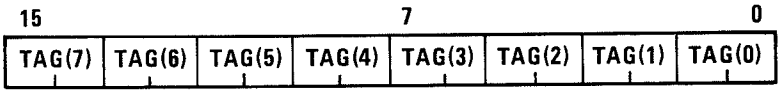
(3) Rounding Control:
- 00 = Round to Nearest or Even
- 01 = Round Down (toward ∞)
- 10 = Round Up (toward ∞)
- 11 = Chop (Truncate Toward Zero)

(4) Infinity Control:
- 0 = Projective
- 1 = Affine

Control Word Format

Tag Word

The tag word marks the content of each register, as shown in the Figure below. The main function of the tag word is to optimize the coprocessor's performance under certain circumstances, and programmers ordinarily need not be concerned with it.

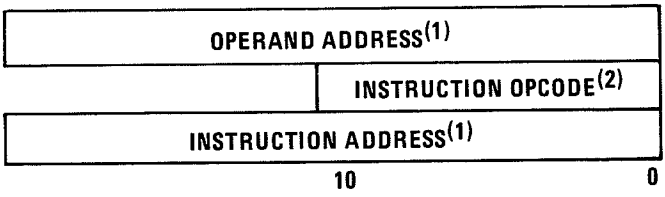


Tag values:
- 00 = Valid (Normal or Unnormal)
- 01 = Zero (True)
- 10 = Special (Not-A-Number, ∞, or Denormal)
- 11 = Empty

Tag Word Format

Exception Pointers

The exception pointers in the figure below are provided for user-written exception handlers. When the coprocessor executes an instruction, the control unit saves the instruction address and the instruction opcode in the exception pointer registers. An exception handler subroutine can store these pointers in memory and determine which instruction caused the exception.



(1) 20-bit physical address

(2) 11 least significant bits of opcode: 5 most significant bits are always COPROCESSOR HOOK (11011B)

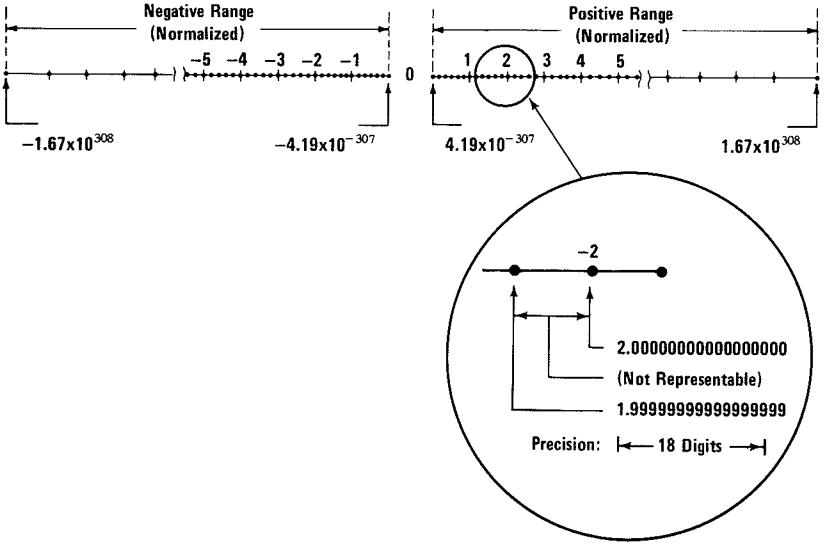
Exception Pointers Format

Number System

The figure below shows the basic coprocessor real number system on a real number line (decimal numbers are shown for clarity, although the coprocessor actually represents numbers in binary). The dots indicate the subset of real numbers the coprocessor can represent as data and final results of calculations. The coprocessor's range is approximately $\pm 4.19 \times 10^{-307}$ to $\pm 1.67 \times 10^{308}$.

The coprocessor can represent a great many of, but not all, the real numbers in its range. There is always a "gap" between two adjacent coprocessor numbers, and the result of a calculation may fall within this space. When this occurs, the coprocessor rounds the true result to a number it can represent.

The coprocessor actually uses a number system that is a superset of that shown in the figure below. The internal format (called temporary real) extends the coprocessor's range to about $\pm 3.4 \times 10^{-4932}$ to $\pm 1.2 \times 10^{4932}$, and its precision to about 19 (equivalent decimal) digits. This format is designed to provide extra range and precision for constants and intermediate results, and is not normally intended for data or final results.



Coprocessor Number System

Instruction Set

On the following pages are descriptions of the operation for the coprocessor's 69 instructions.

An instruction has two basic types of operands – sources and destinations. A source operand simply supplies one of the "inputs" to an instruction; it is not altered by the instruction. A destination operand may also provide an input to an instruction. It is distinguished from a source operand, however, because its content can be altered when it receives the result produced by that operation; that is the destination is replaced by the result.

The operands of any instructions can be coded in more than one way. For example, FADD (add real) may be written without operands, with only a source, or with a destination and a source operand. The instruction descriptions use the simple convention of separating alternative operand forms with slashes; the slashes, however, are not coded. Consecutive slashes indicate there are no explicit operands. The operands for FADD are thus described as:

source/destination, source

This means that FADD may be written in any of three ways:

FADD

FADD source

FADD destination,source

It is important to bear in mind that memory operands may be coded with any of the processor's memory addressing modes.

FABS

FABS (absolute value) changes the top stack element to its absolute value by making its sign positive.

FABS (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	14	10-17	0	2	FABS

FADD

Addition

FADD / / source/destination,source

FADDP destination,source

FIADD source

The addition instructions (add real, add real and pop, integer add) add the source and destination operands and return the sum to the destination. The operand at the stack top may be doubled by coding FADD ST,ST(0).

FADD			Exceptions: I, D, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST,ST(i)/ST(i),ST	85	70-100	0	2	FADD ST,ST(4)
short-real	105+EA	90-120+EA	4	2-4	FADD AIR_TEMP [SI]
long-real	110+EA	95-125+EA	8	2-4	FADD [BX],MEAN

FADDP			Exceptions: I, D, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(I),ST	90	75-105	0	2	FADD ST(2), ST

FIADD			Exceptions: I, D, O, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	120+EA	102-137+EA	2	2-4	FIADD DISTANCE_TRAVELLED
short-integer	125+EA	108-143+EA	4	2-4	FIADD PULSE_COUNT[SI]

FBLD

FBLD Source

FBLD (packed decimal BCD) load)) converts the content of the source operand from packed decimal to temporary real and loads (pushes) the result onto the stack. The packed decimal digits of the source are assumed to be in the range X '0-9H'.

FBLD			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
packed-decimal	300+EA	290-310+EA	10	2-4	FBLD YTD_SALES

FBSTP

FBSTP destination

FBSTP (packed decimal (BCD) store and pop) performs the inverse of FBLD, where the stack top is stored to the destination in the packed-decimal data type.

FBSTP			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
packed-decimal	530+EA	520-542+EA	12	2-4	FBSTP [BX].FORCAST

FCHS

FCHS (change sign) complements (reverses) the sign of the top stack element.

FCHS (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	15	10-17	0	2	FCHS

FCLEX/FNCLEX

FCLEX/FNCLEX (clear exceptions) clears all exception flags, the interrupt request flag, and the busy flag in the status word.

FCLEX/FNCLEX (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	5	2-8	0	2	FNCLEX

FCOM

FCOM/ /source

FCOM (compare real) compares the stack top to the source operand. This results in the setting of the condition code bits.

FCOM			Exceptions: I, D		
Operands	Execution Clocks		Trans-fers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i)	45	40-50	0	2	FCOM ST(1)
short-real	65+EA	63-70+EA	4	2-4	FCOM [BP.] UPPER_LIMIT
long-real	70+EA	65-75+EA	8	2-4	FCOM WAVELENGTH

C3	C0	Order
0	0	ST > source
0	1	ST < source
1	0	ST = source
1	1	ST ? source

NANS and ∞ (projective) cannot be compared and return C3=C0=1 as shown above.

FCOMP

FCOMP/ /source

FCOMP (compare real and pop) operates like FCOM, and in addition pops the stack

FCOMP			Exceptions: I, D		
Operands	Execution Clocks		Trans-fers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i)	47	42-52	0	2	FCOMP ST(2)
short-real	68+EA	63-73+EA	4	2-4	FCOMP [BP].N_READINGS
long-real	72+EA	67-77+EA	8	2-4	FCOMP DENSITY

FCOMPP

FCOMPP/ /source

FCOMPP (compare real and pop twice) operates like FCOM and, additionally, pops the stack twice, discarding both operands. The comparison is of the stack top to ST(1); no operands may be explicitly coded.

FCOMPP (no operands)			Exceptions: I, D		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	50	45-55	0	2	FCOMPP

FDECSTP

FDECSTP (decrement stack pointer) subtracts 1 from ST, the stack top pointer in the status word.

FDECSTP (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	9	6-12	0	2	FDECSTP

FDISI/FNDISI

FDISI/FNDISI (disable interrupts) sets the interrupt enable mask in the control word.

FDISI/FNDISI (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	5	2-8	0	2	FDISI

FDIV

Normal division

FDIV / /source/ destination,source

FDIVP destination,source

FIDIV source

The normal division instructions (divide real, divide real and pop, integer divide) divide the destination by the source and return the quotient to the destination.

FDIV					Exceptions: I, D, Z, O, U, P
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i),ST	198	193-203	0	2	FDIV
short-real	220+EA	215-225+EA	4	2-4	FDIV DISTANCE
long-real	225+EA	220-230+EA	8	2-4	FDIV ARC[DI]

FDIVP					Exceptions: I, D, Z, O, U, P
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST	202	197-207	0	2	FDIVP ST(4), ST

FIDIV					Exceptions: I, D, Z, O, U, P
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	230+EA	224-238+EA	2	2-4	FIDIV SURVEY.OBSERVATIONS
short-integer	236+EA	230-243+EA	4	2-4	FIDIV RELATIVE_ANGLE[DI]

FDIVR

Reversed Division

FDIVR / /source/ destination,source

FDIVRP destination,source

FIDIVR source

The reversed division instructions (divide real reversed, divide real reversed and pop, integer divide reversed) divide the source operand by the destination and return the quotient to the destination.

FDIVR			Exceptions: I, D, Z, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST,ST(i)/ST(i),ST	199	194-204	0	2	FDIVR ST(2), ST
short-real	221+EA	216-226+EA	6	2-4	FDIVR [BX].PULSE_RATE
long-real	226+EA	221-231+EA	8	2-4	FDIVR RECORDER.FREQUENCY

FDIVRP			Exceptions: I, D, Z, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST	203	198-208	0	2	FDIVRP ST(1), ST

FIDIVR			Exceptions: I, D, Z, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	230+EA	225-239+EA	2	2-4	FIDIVR [BP].X_COORD
short-integer	237+EA	231-245+EA	4	2-4	FIDIVR FREQUENCY

FENI/FNENI

FENI/FNENI (enable interrupts) clear the interrupt enable mask in the control word.

FENI/FNENI (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	5	2-8	0	2	FNENI

FFREE

FFREE destination

FFREE (free register) changes the destination register's tag to empty; the content of the register is not affected.

FFREE			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i)	186	9-16	0	2	FFREE ST(1)

FICOM

FICOM source

FICOM (integer compare) compares the source to the stack top.

FICOM			Exceptions: I, D		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	80+EA	72-86+EA	2	2-4	FICOM TOOL.N_PASSES
short-integer	85+EA	78-91+EA	2	2-4	FICOM [BP+41].PARM_COUNT

FICOMP

FICOMP source

FICOMP (integer compare and pop) operates the same as FICOM and additionally pops the stack.

FICOMP			Exceptions: I, D		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	82+EA	74-88+EA	2	2-4	FICOMP [BP].LIMIT [SI]
short-inter	87+EA	80-93+EA	4	2-4	FICOMP N_SAMPLES

FILD

FILD source

FILD (integer load) loads (pushes) the source onto the stack.

FILD			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	50+EA	46-54+EA	2	2-4	FILD [BX].SEQUENCE
short-integer	56+EA	52-60+EA	4	2-4	FILD STANDOFF[DI]
long-integer	64+EA	60-68+EA	8	2-4	FILD RESPONSE.COUNT

FINCSTP

FINCSTP (increment stack pointer) adds 1 to the stack top pointer (ST) in the status word.

FINCSTP (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	9	6-12	0	2	FINCSTP

FINIT/FNINIT

FINIT/FNINIT (initialize processor) performs the functional equivalent of a hardware RESET.

FINIT/FNINIT (no operands)		Exceptions: None			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	5	2-8	0	2	FINIT

Field	Value	Interpretation
Control Word		
Infinity Control	0	Projective
Rounding Control	00	Round to nearest
Precision Control	11	64 bits
Interrupt-enable Mask	1	Interrupts disabled
Exception Masks	111111	All exceptions masked
Status Word		
Busy	0	Not Busy
Condition Code	????	(Indeterminate)
Stack Top	000	Empty stack
Interrupt Request	0	No interrupt
Exception Flags	000000	No exceptions
Tag Word		
Tags	11	Empty
Registers	N.C.	Not changed
Exception Pointers		
Instruction Code	N.C.	Not changed
Instruction Address	N.C.	Not changed
Operand Address	N.C.	Not changed

FIST

FIST destination

FIST (integer store) stores the stack top to the destination in the integer format.

FIST			Exceptions: I, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	86+EA	80-90+EA	4	2-4	FIST OBS.COUNT[SI]
short-integer	88+EA	82-92+EA	6	2-4	FIST [BP].FACTORED_PULSES

FISTP

FISTP destination

FISTP (integer store and pop) operates like FIST and also pops the stack following the transfer. The destination may be any of the binary integer data types.

FISTP			Exceptions: I, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	88+EA	82-92+EA	4	2-4	FISTP [BX].ALPHA_COUNT[SI]
short-integer	90+EA	84-94+EA	6	2-4	FISTP CORRECTED_TIME
long-integer	100+EA	94-105+EA	10	2-4	FISTP PANEL.N_READINGS

FLD

FLD source

FLD (load real) loads (pushes) the source operand onto the top of the register stack.

FLD			Exceptions: I, D		
Operands	Execution Clocks		Trans-fers 8088	Bytes	Coding Example
	Typical	Range			
ST(i)	20	17-22	0	2	FLD ST(0)
short-real	43+EA	38-56+EA	4	2-4	FLD READING[SI].PRESSURE
long-real	46+EA	40-60+EA	8	2-4	FLD [BP].TEMPERATURE
temp-real	57+EA	53-65+EA	10	2-4	FLD SAVEREADING

FLDCW

FLDCW source

FLDCW (load control word) replaces the current processor control word with the word defined by the source operand.

FLDCW			Exceptions: None		
Operands	Execution Clocks		Trans-fers 8088	Bytes	Coding Example
	Typical	Range			
2-bytes	10+EA	7-14+EA	2	2-4	FLDCW CONTROL_WORD

FLDENV

FLDENV source

FLDENV (load environment) reloads the coprocessor environment from the memory area defined by the source operand.

FLDENV			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
14-bytes	40+EA	35-45+EA	14	2-4	FLDENV [BP+6]

FLDLG2

FLDLG2 (load log base 10 of 2) loads (pushes) the value of $LOG_{10}2$ onto the stack.

FLDLG2 (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	21	18-24	0	2	FLDLG2

FLDLN2

FLDLN2 (load log base e of 2) loads (pushes) the value of LOG_e2 onto the stack.

FLDLN2 (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	20	17-23	0	2	FLDLN2

FLDL2E

FLDL2E (load log base 2 of e) loads (pushes) the value LOG_2e onto the stack.

FLDL2E (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	18	15-21	0	2	FLDL2E

FLDL2T

FLDL2T (load log base 2 of 10) loads (pushes) the value of LOG_210 onto the stack.

FLDL2T (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	19	16-22	0	2	FLDL2T

FLDPI

FLDPI (load π) loads (pushes) π onto the stack.

FLDPI (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	19	16-22	0	2	FLDPI

FLDZ

FLDZ (load zero) loads (pushes) +0.0 onto the stack.

FLDZ (no operands)			Exceptions: I		
Operands	Execution Clocks		Trans-fers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	14	11-17	0	2	FLD1

FLD1

FLD1 (load one) loads (pushes) +1.0 onto the stack.

FLD1 (no operands)			Exceptions: I		
Operands	Execution Clocks		Trans-fers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	18	15-21	0	2	FLDZ

FMUL

Multiplication

FMUL / /source/destination,source

FMULP destination,source

FIMUL source

The multiplication instructions (multiply real, multiply real and pop, integer multiply) multiply the source and destination operands and return the product to the destination. Coding FMUL ST,ST(0) square the content of the stack top.

FMUL			Exceptions: I, D, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i),ST/ST,ST(i)[1]	97	90-105	0	2	FMUL ST,ST(3)
//ST(i),ST/ST,ST(i)	138	130-145	0	2	FMUL ST,ST(3)
short-real	118+EA	110-125+EA	4	2-4	FMUL SPEED_FACTOR
long-real[1]	120+EA	112-126+EA	8	2-4	FMUL [BP].HEIGHT
long-real	161+EA	154-168+EA	8	2-4	FMUL [BP].HEIGHT

[1] occurs when one or both operands is "short" - it has 40 trailing zeros in its fraction.

FMULP			Exceptions: I, D, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST[1]	100	94-108	0	2	FMULP ST(1),ST
ST(i),ST	142	134-148	0	2	FMULP ST(1),ST

[1] occurs when one or both operands is "short" - it has 40 trailing zeros in its fraction.

FIMUL			Exceptions: I, D, O, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	130+EA	124-138+EA	2	2-4	FIMUL BEARING
short-integer	136+EA	130-144+EA	4	2-4	FIMUL POSITION.Z_AXIS

FNOP

FNOP (no operation) stores the stack top to the stack top (FST ST,ST(0)) and thus effectively performs no operation.

FNOP (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	13	10-16	0	2	FNOP

FPATAN

FPATAN (partial arctangent) computes the function $\theta = \text{ARCTAN}(Y/X)$. X is taken from the top stack element and Y from ST(1). Y and X must observe the inequality $0<Y<X<\infty$. The instruction pops the stack and returns θ to the (new) stack top, overwriting the Y operand.

FPATAN (no operands)			Exceptions: U, P (operands not checked)		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	650	250-800	0	2	FPATAN

FPREM

FPREM (partial remainder) performs modulo division on the top stack element by the next stack element, that is, ST(1) is the modulus.

FPREM (no operands)			Exceptions: I, D, U		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	125	15-190	0	2	FPREM

FPTAN

FPTAN (partial tangent) computes the function Y/X =TAN(θ). θ is taken from the top stack element; it must lie in the range $0<\theta<\pi/4$. The result of the operation is a ratio; Y replaces θ in the stack and X is pushed, becoming the new stack top.

FPTAN			Exceptions: I, P (operands not checked)		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	450	30-540	0	2	FPTAN

FRNDINT

FRNDINT (round to integer) rounds the top stack element to an integer.

FRNDINT (no operands)			Exceptions: I, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	45	16-50	0	2	FRNDINT

FRSTOR

FRSTOR source

FRSTOR (restore state) reloads the coprocessor from the 94-byte memory area defined by the source operand.

FRSTOR			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
94-bytes	210+EA	205-215+EA	96	2-4	FRSTOR [BP]

FSAVE/FNSAVE

FSAVE/FNSAVE destination

FSAVE/FNSAVE (save state) writes the full coprocessor state – environment plus register stack – to the memory location defined by the destination operand.

FSAVE/FNSAVE			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
94-bytes	210+EA	205-215+EA	94	2-4	FSAVE [BP]

FSCALE

FSCALE (scale) interprets the value contained in ST(1) as an integer, and adds this value to the exponent of the number in ST. This is equivalent to:

$$ST \leftarrow ST \cdot 2^{ST(1)}$$

Thus, FSCALE provides rapid multiplication or division by integral powers of 2.

FSCALE (no operands)			Exceptions: I, O, U		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	35	32-38	0	2	FSCALE

FSQRT

FSQRT (square root) replaces the content of the top stack element with its square root.

Note: the square root of −0 is defined to be −0.

FSQRT (no operands)			Exceptions: I, D, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	183	180-186	0	2	FSQRT

FST

FST destination

FST (store real) transfers the stack top to the destination, which may be another register on the stack or long real memory operand.

FST			Exceptions: I, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i)	18	15-22	0	2	FST ST(3)
short-real	87+EA	84-90+EA	6	2-4	FST CORRELATION [DI]
long-real	100+EA	96-104+EA	10	2-4	FST MEAN_READING

FSTCW/FNSTCW

FSTCW/FNSTCW destination

FSTCW/FNSTCW (store control word) writes the current processor control word to the memory location defined by the destination.

FSTCW/FNSTCW			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
2-bytes	15+EA	12-18+EA	4	2-4	FSTCW SAVE_CONTROL

FSTENV/FNSTENV

FSTENV/FNSTENV destination

FSTENV/FNSTENV (store environment) writes the coprocessor's basic status – control, status and tag words, and exception pointers – to the memory location defined by the destination operand.

FSTENV/FNSTENV			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
14-bytes	45+EA	40-50+EA	16	2-4	FSTENV [BP]

FSTP

FSTP destination

FSTP (store real and pop) operates the same as FST, except that the stack is popped following the transfer.

FSTP			Exceptions: I, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i)	20	17-24	0	2	FSTP ST(2)
short-real	89+EA	86-92+EA	6	2-4	FSTP [BX].ADJUSTED_RPM
long-real	102+EA	98-106+EA	10	2-4	FSTP TOTAL_DOSAGE
temp-real	55+EA	52-58+EA	12	2-4	FSTP REG_SAVE[SI]

FSTSW/FNSTSW

FSTSW/FNSTSW destination

FSTSW/FNSTSW (store status word) writes the current value of the coprocessor status word to the destination operand in memory.

FSTSW/FNSTSW			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
2-bytes	14+EA	12-18+EA	4	2-4	FSTSW SAVE_STATUS

FSUB

Subtraction

FSUB / /source/destination,source

FSUBP destination,source

FISUB source

The normal subtraction instructions (subtract real, subtract real and pop, integer subtract) subtract the source operand from the destination and return the difference to the destination.

FSUB			Exceptions: I, D, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST,ST(i)/ST(i),ST	85	70-100	0	2	FSUB ST,ST(2)
short-real	105+EA	90-120+EA	4	2-4	FSUB BASE_VALUE
long-real	110+EA	95-125+EA	8	2-4	FSUB COORDINATE.X

FSUBP			Exceptions: I, D, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST	90	75-105	0	2	FSUBP ST(2),ST

FISUB			Exceptions: I, D, O, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	120+EA	102-137+EA	2	2-4	FISUB BASE_FREQUENCY
short-integer	125+EA	108-143+EA	4	2-4	FISUB TRAIN_SIZE[DI]

FSUBR

Reversed Subtraction

FSUBR / /source/destination,source

FSUBRP destination,source

FISUBR source

The reversed subtraction instructions (subtract real reversed, subtract real reversed and pop, integer subtract reversed) subtract the destination from the source and return the difference to the destination.

FSUBR			Exceptions: I, D, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST,ST(i)/ST(i),ST	87	70-100	0	2	FSUBR ST,ST(1)
short-real	105+EA	90-120+EA	4	2-4	FSUBR VECTOR[SI]
long-real	110+EA	95-125+EA	8	2-4	FSUBR [BX].INDEX

FSUBRP	Exceptions: I, D, O, U, P				
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST	90	75-105	0	2	FSUBRP ST(1),ST

FISUBR	Exceptions: I, D, O, P				
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	120+EA	103-139+EA	2	2-4	FISUBR FLOOR[BX] [SI]
short-integer	125+EA	109-144+EA	4	2-4	FISUBR BALANCE

FTST

FTST (test) tests the top stack element by comparing it to zero. The result is posted to the condition codes.

FTST (no operands)	Exceptions: I, D				
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	42	38-48	0	2	FTST

C3	C0	Result
0	0	ST is positive and nonzero
0	1	ST is negative and nonzero
1	0	ST is zero (+ or −)
1	1	ST is not comparable (that is, it is a NAN or projective ∞)

FWAIT

FWAIT (processor instruction)

FWAIT is not actually a coprocessor instruction, but an alternate mnemonic for the processor WAIT instruction. The FWAIT mnemonic should be coded whenever the programmer wants to synchronize the processor to the coprocessor, that is, to suspend further instruction decoding until the coprocessor has completed the current instruction.

FWAIT (no operands)			Exceptions: Non (CPU instruction)		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	3+5n	3+5n	0	1	FWAIT

FXAM

FXAM (examine) reports the content of the top stack element as positive/negative and NAN/unnormal/denormal/normal/zero, or empty.

FXAM			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	17	12-23	0	2	FXAM

Condition Code				Interpretation
C3	C2	C1	C0	
0	0	0	0	+ Unnormal
0	0	0	1	+ NAN
0	0	1	0	– Unnormal
0	0	1	1	– NAN
0	1	0	0	+ Normal
0	1	0	1	$+\infty$
0	1	1	0	– Normal
0	1	1	1	$-\infty$
1	0	0	0	+0
1	0	0	1	Empty
1	0	1	0	–0
1	0	1	1	Empty
1	1	0	0	+ Denormal
1	1	0	1	Empty
1	1	1	0	– Denormal
1	1	1	1	Empty

FXCH

FXCH/ /destination

FXCH (exchange registers) swaps the contents of the destination and the stack top registers. If the destination is not coded explicitly, ST(1) is used.

FXCH			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i)	12	10-15	0	2	FXCH ST(2)

FXTRACT

FXTRACT (extract exponent and significant) "decomposes" the number in the stack top into two numbers that represent the actual value of the operand's exponent and significand fields contained in the stack top and ST(1).

FXTRACT		Exceptions: I			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	50	27-55	0	2	FXTRACT

FYL2X

FYL2X (Y log base 2 of X) calculates the function $Z=Y \cdot LOG_2 X$. X is taken from the stack top and Y from ST(1). The operands must be in the ranges $0<X<\infty$ and $-\infty<Y<+\infty$. The instruction pops the stack and returns Z at the (new) stack top, replacing the Y operand.

$$LOG_n 2 \cdot LOG_2 X$$

FYL2X		Exceptions: P (operands not checked)			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	950	900-1100	0	2	FYL2X

FYL2XP1

FYL2XP1 (Y log base 2 of (X + 1)) calculates the function $Z = Y \cdot LOG_2(X+1)$. X is taken from the stack top and must be in the range $0 < |X| < (1-(\sqrt{2}/2))$. Y is taken from ST(1) and must be in the range $-\infty < Y < \infty$. FYL2XP1 pops the stack and returns Z at the (new) stack top, replacing Y.

FYL2XP1					Exceptions: P (operands not checked)
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	850	700-1000	0	2	FYL2XP1

F2XM1

F2XM1 (2 to the X minus 1) calculates the function $Y=2^x-1$. X is taken from the stack top and must be in the range $0<X<0.5$. The result Y replaces the stack top.

This instruction is designed to produce a very accurate result even when X is close to zero. To obtain $Y=2^x$, add 1 to the result delivered by F2XM1.

F2XM1					Exceptions: U, P (operands not checked)
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	500	310-630	0	2	F2XM1

Notes:

IBM Keyboard

The keyboard has a permanently attached cable that connects to a DIN connector at the rear of the system unit. This shielded four-wire cable has power (+5 Vdc), ground, and two bidirectional signal lines. The cable is approximately 6-feet long and is coiled, like that of a telephone handset.

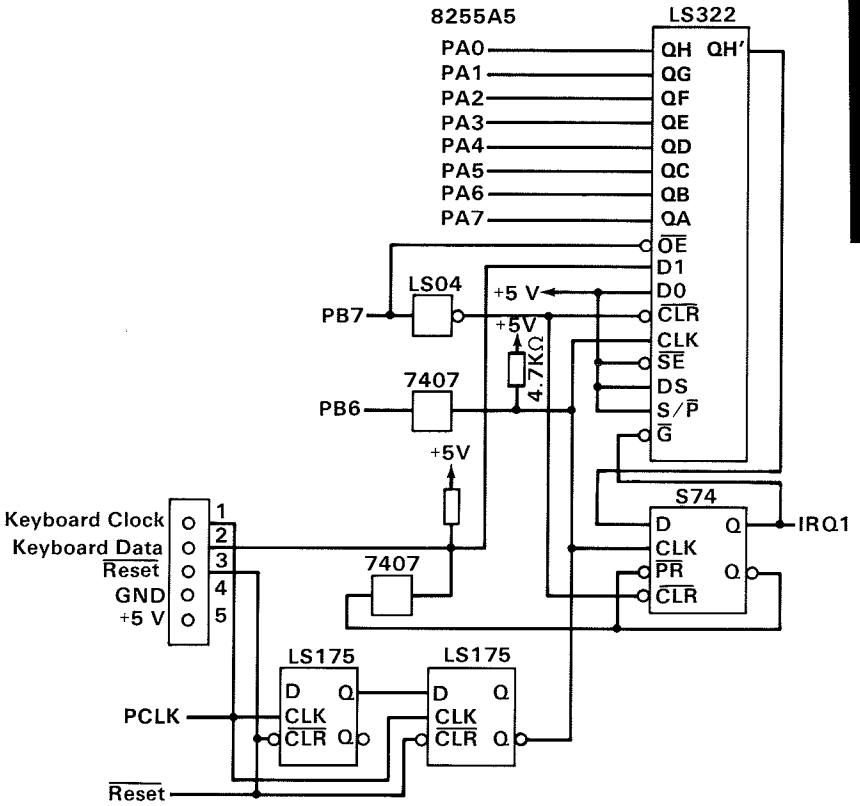
The keyboard uses a capacitive technology with a microcomputer (Intel 8048) performing the keyboard scan function. The keyboard has three tilt positions for operator comfort (5-, 7-, or 15-degree tilt orientations).

The keyboard has 83 keys arranged in three major groupings. The central portion of the keyboard is a standard typewriter keyboard layout. On the left side are 10 function keys. These keys are user-defined by the software. On the right is a 15-key keypad. These keys are also defined by the software, but have legends for the functions of numeric entry, cursor control, calculator pad, and screen edit.

The keyboard interface is defined so that system software has maximum flexibility in defining certain keyboard operations. This is accomplished by having the keyboard return scan codes rather than American Standard Code for Information Interchange (ASCII) codes. In addition, all keys are typematic and generate both a make and a break scan code. For example, key 1 produces scan code hex 01 on make and code hex 81 on break. Break codes are formed by adding hex 80 to make codes. The keyboard I/O driver can define keyboard keys as shift keys or typematic, as required by the application.

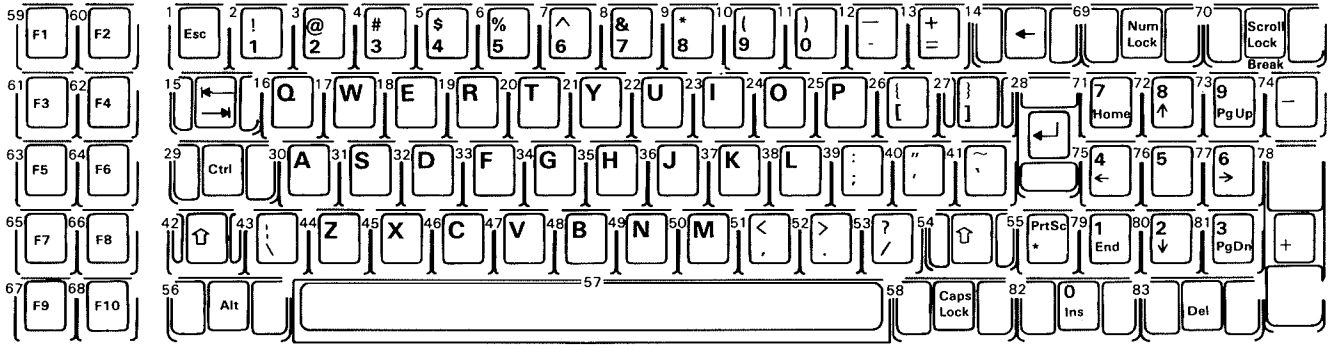
The microcomputer (Intel 8048) in the keyboard performs several functions, including a power-on self-test when requested by the system unit. This test checks the microcomputer ROM, tests memory, and checks for stuck keys. Additional functions are: keyboard scanning, buffering of up to 16 key scan codes, maintaining bidirectional serial communications with the system unit, and executing the hand-shake protocol required by each scan-code transfer.

The following pages have figures that show the keyboard, the scan codes, and the keyboard interface connector specifications.



Keyboard Interface Block Diagram

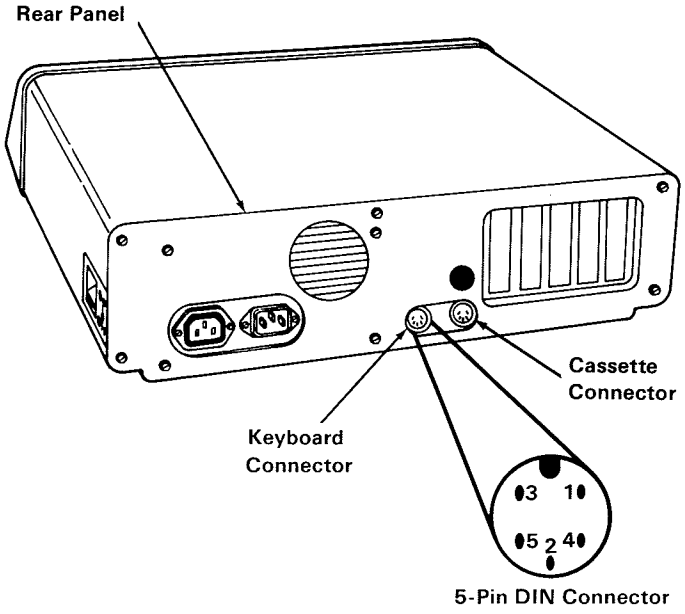
Keyboard Diagram



Note: Nomenclature is on both the top and front face of the keybutton as shown. The number to the upper left designates the button position.

Key Position	Scan Code in Hex	Key Position	Scan Code in Hex
1	01	43	2B
2	02	44	2C
3	03	45	2D
4	04	46	2E
5	05	47	2F
6	06	48	30
7	07	49	31
8	08	50	32
9	09	51	33
10	0A	52	34
11	0B	53	35
12	0C	54	36
13	0D	55	37
14	0E	56	38
15	0F	57	39
16	10	58	3A
17	11	59	3B
18	12	60	3C
19	13	61	3D
20	14	62	3E
21	15	63	3F
22	16	64	40
23	17	65	41
24	18	66	42
25	19	67	43
26	1A	68	44
27	1B	69	45
28	1C	70	46
29	1D	71	47
30	1E	72	48
31	1F	73	49
32	20	74	4A
33	21	75	4B
34	22	76	4C
35	23	77	4D
36	24	78	4E
37	25	79	4F
38	26	80	50
39	27	81	51
40	28	82	52
41	29	83	53
42	2A		

Keyboard Scan Codes



Pin	TTL Signal	Signal Level
1	+Keyboard Clock	+5 Vdc
2	+Keyboard Data	+5 Vdc
3	-Keyboard Reset (Not used by keyboard)	
	Power Supply Voltages	**Voltage**
4	Ground	0
5	+5 Volts	+5 Vdc

Keyboard Interface Connector Specifications

Expansion Unit

The expansion unit option upgrades the IBM Personal Computer by adding expansion slots in a separate unit. This option consists of an extender card, an expansion cable, and the expansion unit. The expansion unit contains a power supply, an expansion board, and a receiver card. This option utilizes one expansion slot in the system unit to provide seven additional expansion slots in the expansion unit.

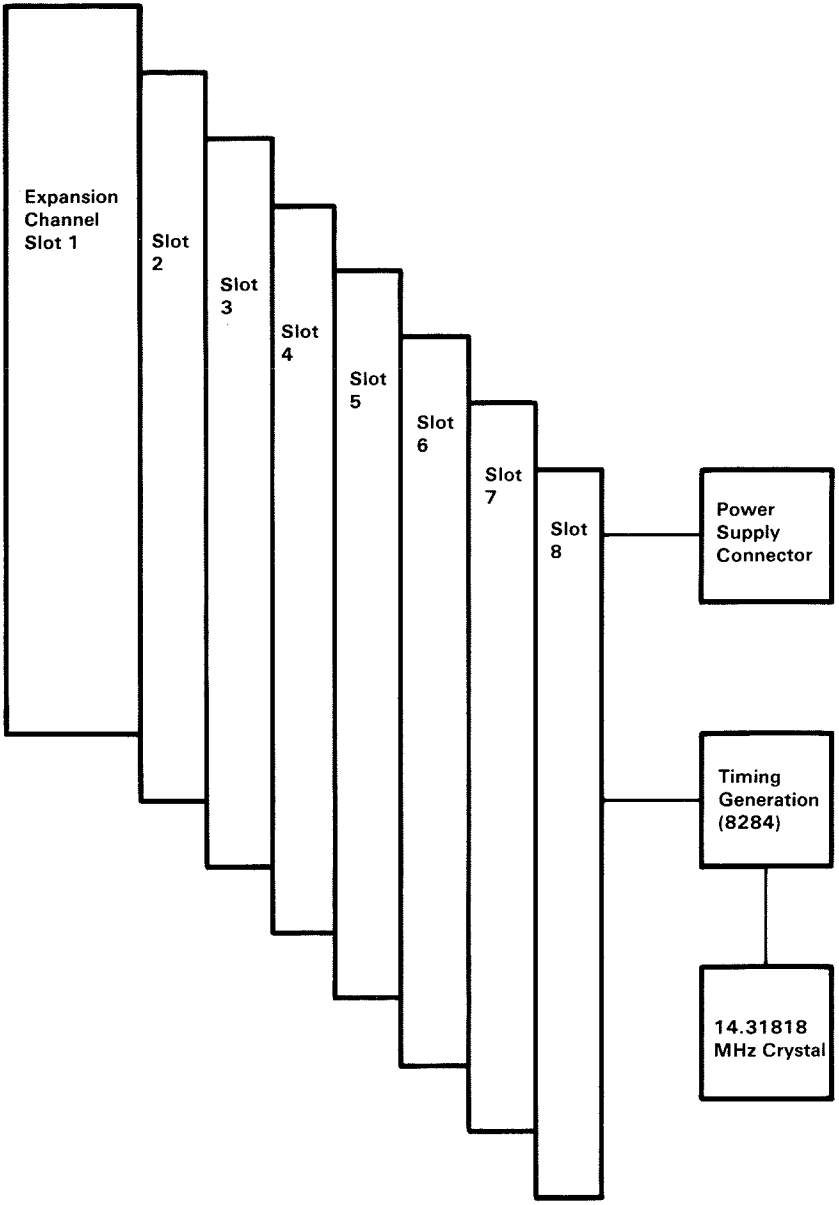
Expansion Unit Cable

The expansion unit cable consists of a 56-wire, foil-shielded cable terminated on each end with a 62-pin D-shell male connector. Either end of the expansion unit cable can be plugged into the extender card or the receiver card.

Expansion Board

The expansion board is a support board that carries the I/O channel signals from the option adapters and receiver card. These signals, except 'osc,' are carried over the expansion cable. Because 'osc' is not sent over the expansion cable, a 14.31818-MHz signal is generated on the expansion board. This signal may not be in phase with the 'osc' signal in the system unit.

Decoupling capacitors provided on the expansion board aid in noise filtering.



Expansion Board Block Diagram

Expansion Channel

All signals found on the system unit's I/O channel will be provided to expansion slots in the expansion unit, with the exception of the 'osc' signal and the voltages mentioned previously.

A 'ready' line on the expansion channel makes it possible to operate with slow I/O or memory devices. If the channel's 'I/O ch rdy' line is not activated by an addressed device, all processor-generated memory cycles take five processor clock cycles per byte for memory in the expansion unit.

The following table contains a list of all the signals that are redriven by the extender and receiver cards, and their associated time delays. The delay times include the delay due to signal propagation in the expansion cable. Assume a nominal cable delay of 3 ns. As such, device access will be less than 260 ns.

Signal	Nominal Delay (ns)	Maximum Delay (ns)	Direction (*)
A0 - A19	27	39	Output
AEN	27	39	Output
DACK0 - DACK3	27	39	Output
MEMR	27	39	Output
MEMW	51	75	Output
IOR	51	75	Output
IOW	27	39	Output
ALE	27	39	Output
CLK	27	39	Output
T/C	27	39	Output
RESET	27	39	Output
IRQ2 - IRQ7	36	(**)	Input
DRQ1 - DRQ3	36	(**)	Input
I/O CH RDY	36	51	Input
I/O CH CK	36	51	Input
D0 - D7 (Read)	84	133	Input
D0 - D7 (Write)	19	27	Output

(*) With respect to the system unit.

(**) Asynchronous nature of interrupts and other requests are more dependent on processor recognition than electrical signal propagation through expansion logic.

Power Supply

The expansion unit dc power supply is a 130-watt, 4 voltage level switching regulator. It is integrated into the expansion unit and supplies power for the expansion unit, and its options. The supply provides 15 A of +5 Vdc, plus or minus 5%, 4.2A of +12 Vdc, plus or minus 5%, 300 mA of −5 Vdc, plus or minus 10%, and 250 mA of −12 Vdc, plus or minus 10%. All power levels are regulated with over-voltage and over-current protection. The input is 120 Vac and fused. If dc over-load or over-voltage conditions exist, the supply automatically shuts down until the condition is corrected. The supply is designed for continuous operation at 130 watts.

The power supply is located at the right rear of the expansion unit. It supplies operating voltages to the expansion board, and provides two separate connections for power to the fixed disk drives. The nominal power requirements and output voltages are listed in the following tables:

Voltage (Vac at 50/60 Hz)			Frequency (Hz)	Current (Amps)
Nominal	Minimum	Maximum	+/- 3 Hz	Maximum
110	90	137	50/60	4.1 at 90 Vac

Input Requirements

Voltage (Vdc)	Current (Amps)		Regulation (Tolerance)	
Nominal	Minimum	Maximum	+%	-%
+5.0	2.3	15.0	5	4
−5.0	0.0	0.3	10	8
+12.0	0.4	4.2	5	4
−12.0	0.0	0.25	10	9

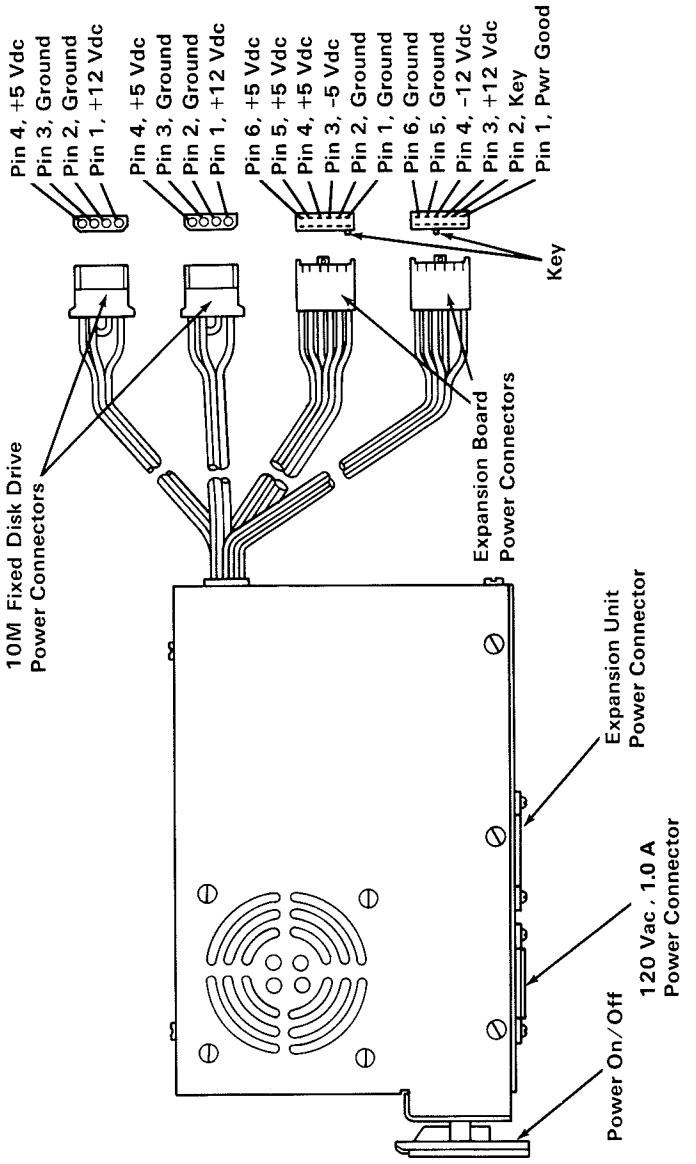
Vdc Output

Voltage (Vac)	Current (Amps)		Voltage Limits (Vac)	
Nominal	Minimum	Maximum	Minimum	Maximum
120	0.0	1.0	88	137

Vac Output

Power Supply Connectors and Pin Assignments

The power connector on the expansion board is a 12-pin male connector that plugs into the power-supply connectors. The pin configurations and locations are shown below:



Power Supply and Connectors

Over-Voltage/Over-Current Protection

Voltage Nominal Vac	Type Protection	Rating Amps
110	Fuse	5

Power On/Off Cycle: When the supply is turned off for a minimum of 1.0 second, and then turned on, the power-good signal will be regenerated.

The power-good signal indicates that there is adequate power to continue processing. If the power goes below the specified levels, the power-good signal triggers a system shutdown.

This signal is the logical AND of the dc output-voltage sense signal and the ac input voltage fail signal. This signal is TTL-compatible up-level for normal operation or down-level for fault conditions. The ac fail signal causes power-good to go to a down-level when any output voltage falls below the regulation limits.

The dc output-voltage sense signal holds the power-good signal at a down level (during power-on) until all output voltages have reached their respective minimum sense levels. The power-good signal has a turn-on delay of at least 100 ms but no greater than 500 ms.

The sense levels of the dc outputs are:

Output (Vdc)	Minimum (Vdc)	Sense Voltage Nominal (Vdc)	Maximum (Vdc)
+5	+4.5	+5.0	+5.5
−5	-4.3	−5.0	-5.5
+12	+10.8	+12.0	+13.2
−12	-10.2	−12.0	-13.2

Extender Card

The extender card is a four-plane card. The extender card redrives the I/O channel to provide sufficient power to avoid capacitive effects of the cable. The extender card presents only one load per line of the I/O channel.

The extender card has a wait-state generator that inserts a wait-state on 'memory read' and 'memory write' operations (except refreshing) for all memory contained in the expansion unit. The address range for wait-state generation is controlled by switch settings on the extender card.

The DIP switch on the extender card should be set to indicate the maximum contiguous read/write memory housed in the system unit. The extender card switch settings are located in "Appendix G: Switch Settings." Switch positions 1 through 4 correspond to address bits hex A19 to hex A16, respectively.

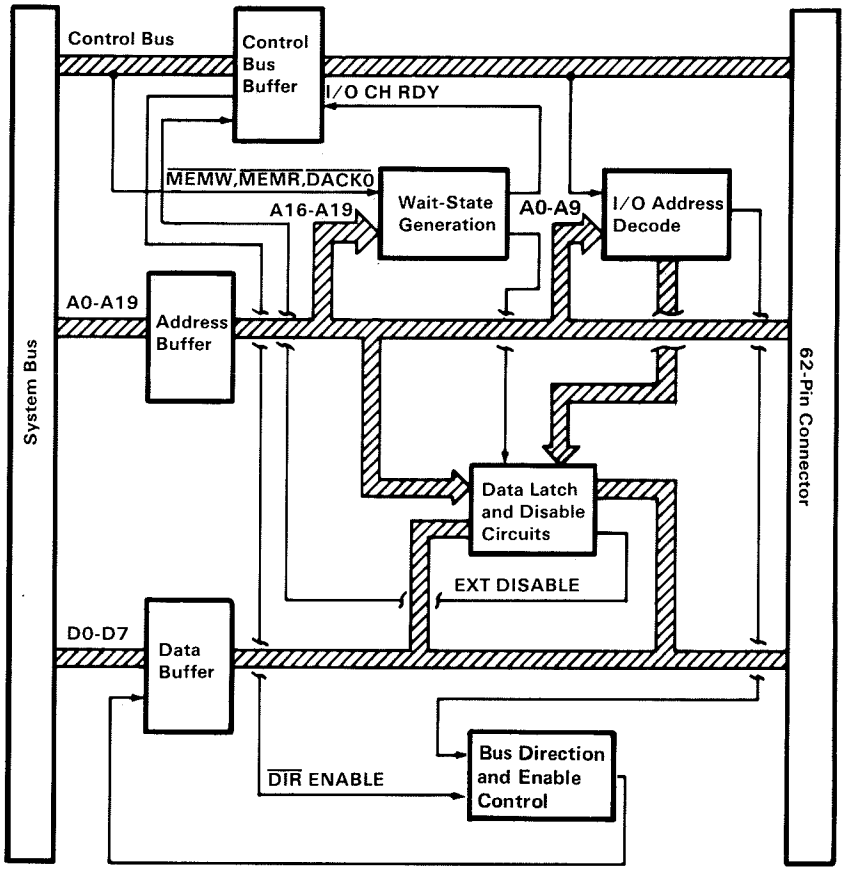
The switch settings determine which address segments have a wait state inserted during 'memory read' and 'memory write' operations. Wait states are required for any memory, including ROM on option adapters, in the expansion unit. Wait states are not inserted in the highest segment, hex addresses F0000 to FFFFF (segment F).

Extender Card Programming Considerations

Several registers associated with the expansion option are programmable and readable for diagnostic purposes. The following figure indicates the locations and functions of the registers on the extender card.

Location	Function
Memory FXXXX(*)	Write to memory to latch address bits
Port 210	Write to latch expansion bus data (ED0 - ED7)
Port 210	Read to verify expansion bus data (ED0 - ED7)
Port 211	Read high-order address bits (A8 - A15)
Port 211	Write to clear wait test latch
Port 212	Read low-order address bits (A0 - A7)
Port 213	Write 00 to disable expansion unit
Port 213	Write 01 to enable expansion unit
Port 213	Read status of expansion unit D0 = enable/disable D1 = wait-state request flag D2-D3 = not used D4-D7 = switch position 1 = Off 0 = On
(*) Example:	Write to memory location F123:4=00 Read Port 211 = 12 Read Port 212 = 34
(All values in hex)	

The expansion unit is automatically enabled upon power-up. The extender card and receiver card will both be written to, if the expansion unit is not disabled when writing to FXXXX. However, the system unit and the expansion unit are read back separately.



Extender Card Block Diagram

Receiver Card

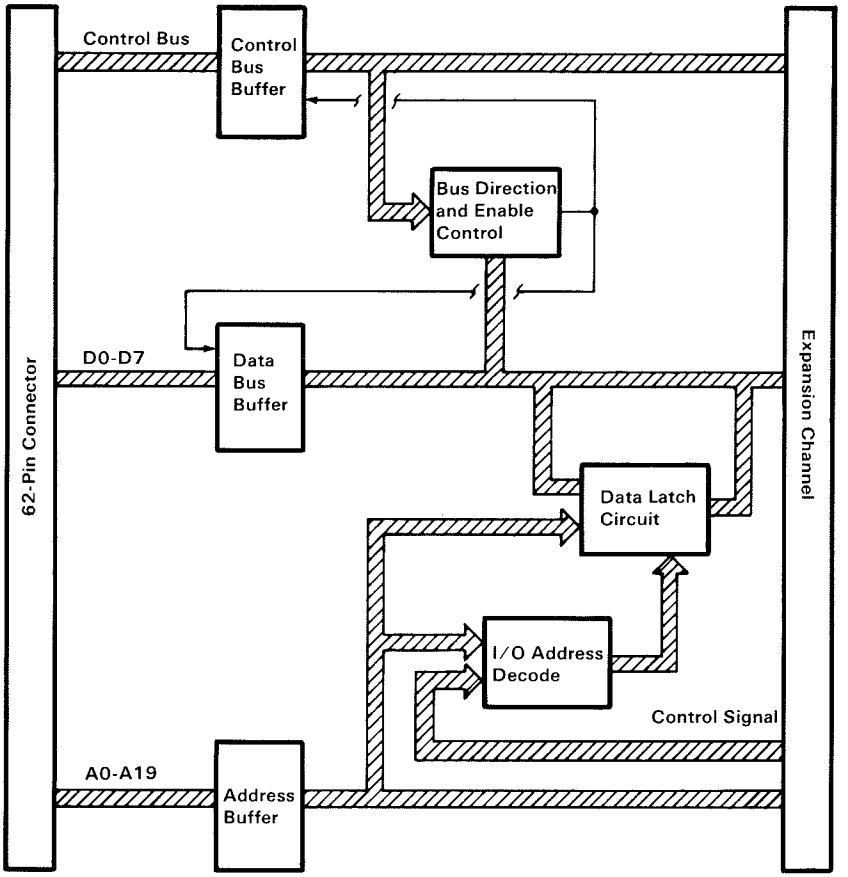
The receiver card is a four-plane card that fits in expansion slot 8 of the expansion unit. The receiver card redrives the I/O channel to provide sufficient power for additional options and to avoid capacitive effects. Directional control logic is contained on the receiver card to resolve contention and direct data flow on the I/O channel. Steering signals are transmitted back over the expansion cable for use on the extender card.

Receiver Card Programming Considerations

Several registers associated with the expansion option are programmable and readable for diagnostic purposes. The following figure indicates the locations and functions of the registers on the receiver card.

Location	Function
Memory FXXXX(*)	Write to memory to latch address bits
Port 214	Write to latch data bus bits (D0 - D7)
Port 214	Read data bus bits (D0 - D7)
Port 215	Read high-order address bits (A8 - A15)
Port 216	Read low-order address bits (A0 - A7)
(*) Example:	Write to memory location F123:4=00 Read Port 215 =12 Read Port 216 =34
(All values in hex)	

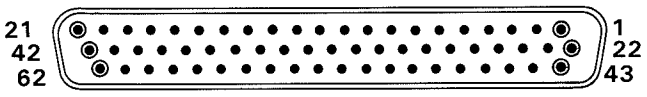
The expansion unit is automatically enabled upon power-up. The expansion unit and the system unit will be written to, if the expansion unit is not disabled when writing to FXXXX. However, the system unit and the expansion unit are read back separately.



Receiver Card Block Diagram

Expansion Unit Interface Information

The extender card and receiver card rear-panel connectors are the same. Pin and signal assignments for the extender and receiver cards are shown below.



Pin	Signal	Pin	Signal	Pin	Signal
1	+E IRQ6	22	+E D5	43	+E IRQ7
2	+E DRQ2	23	+E DRQ1	44	+E D6
3	+E DIR	24	+E DRQ3	45	+E I/O CH RDY
4	+E ENABLE	25	RESERVED	46	+E IRQ3
5	+E CLK	26	+E ALE	47	+E D7
6	-E MEM IN EXP	27	+E T/C	48	+E D1
7	+E A17	28	+E RESET	49	-E I/O CH CK
8	+E A16	29	+E AEN	50	+E IRQ2
9	+E A5	30	+E A19	51	+E D0
10	-E DACK0	31	+E A14	52	+E D2
11	+E A15	32	+E A12	53	+E D4
12	+E A11	33	+E A18	54	+E IRQ5
13	+E A10	34	-E MEMR	55	+E IRQ4
14	+E A9	35	-E MEMW	56	+E D3
15	+E A1	36	+E A0	57	GND
16	+E A3	37	-E DACK3	58	GND
17	-E DACK1	38	+E A6	59	GND
18	+E A4	39	-E IOR	60	GND
19	-E DACK2	40	+E A8	61	GND
20	-E IOW	41	+E A2	62	GND
21	+E A13	42	+E A7		

E = Extended

Connector Specifications

IBM 80 CPS Printers

The IBM 80 CPS (characters-per-second) Printers are self-powered, stand-alone, tabletop units. They attach to the system unit through a parallel signal cable, 6 feet in length. The units obtain ac power from a standard wall outlet (120 Vac). The printers are 80 cps, bidirectional, wire-matrix devices. They print characters in a 9 by 9 dot matrix with a 9-wire head. They can print in a compressed mode of 132 characters per line, in a standard mode of 80 characters per line, in a double width, compressed mode of 66 characters per line, and in a double width mode of 40 characters per line. The printers can print double-size characters and double-strike characters. The printers print the standard ASCII, 96-character, uppercase and lowercase character sets. A printer without an extended character set also has a set of 64 special block graphic characters.

The IBM 80 CPS Graphics Printer has additional capabilities including: an extended character set for international languages, subscript, superscript, an underline mode, and programmable graphics.

The printers can also accept commands setting the line-feed control desired for the application. They attach to the system unit through the printer adapter or the combination monochrome display and printer adapter. The cable is a 25-lead shielded cable with a 25-pin D-shell connector at the system unit end, and a 36-pin connector at the printer end.

(1)	**Print Method:**	Serial-impact dox matrix
(2)	**Print Speed:**	80 cps
(3)	**Print Direction:**	Bidirectional with logical seeking
(4)	**Number of Pins in Head:**	9
(5)	**Line Spacing:**	1/16 inch (4.23 mm) or programmable
(6)	**Printing Characteristics**	
	Matrix:	9 x 9
	Character Set:	Full 96-character ASCII with descenders plus 9 international characters/symbols.
	Graphic Character:	See "Additional Printer Specifications"
(7)	**Printing Sizes**	

	Characters per inch	Maximum characters per inch
Normal:	10	80
Double Width:	5	40
Compressed:	16.5	132
Double Width-Compressed:	8.25	66

(8)	**Media Handling**	
	Paper Feed:	Adjustable sprocket pin feed
	Paper Width Range:	4 inch (101.6 mm) to 10 inch (254 mm)
	Copies:	One original plus two carbon copies (total thickness not to exceed 0.012 inch (0.3 mm)). Minimum paper thickness is 0.0025 inch (0.064 mm).
	Paper Path:	Rear
(9)	**Interfaces**	
	Standard:	Parallel 8-bit Data and Control Lines
(10)	**Inked Ribbon**	
	Color:	Black
	Type:	Cartridge
	Life Expectancy:	3 million characters
(11)	**Environmental Conditions**	
	Operating Temperature Range:	41 to 95°F (5 to 35°C)
	Operating Humidity:	10 to 80% non-condensing
(12)	**Power Requirement**	
	Voltage:	120 Vac, 60 Hz
	Current:	1 A maximum
	Power Consumption:	100 VA maximum
(13)	**Physical Characteristics**	
	Height:	4.2 inches (107 mm)
	Width:	14.7 inches (374 mm)
	Depth:	12.0 inches (305 mm)
	Weight:	12 pounds (5.5 kg)

Printer Specifications

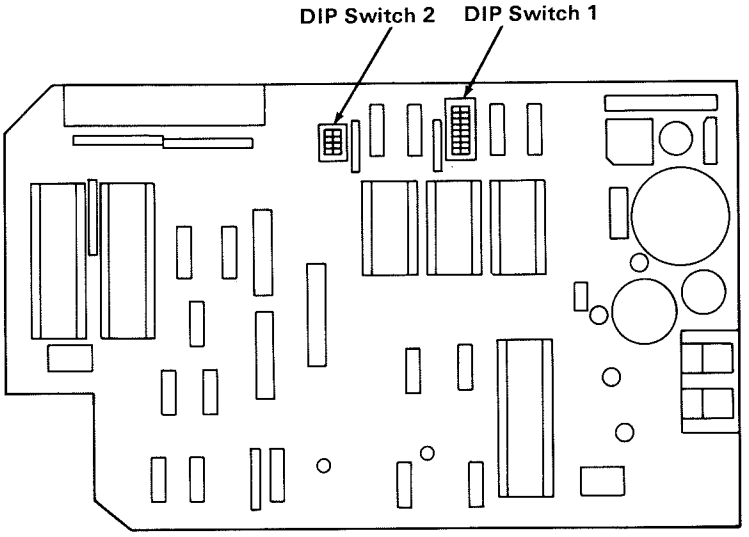
(6)	**Printing Characteristics**	
	IBM 80 CPS Matrix Printer	
	Graphics:	64 block characters.
(6)	**Printing Characteristics**	
	IBM 80 CPS Graphics Printer	Set 1
	Extra Character Set:	Additional ASCII numbers 160 to 175 contain European characters. Numbers 176 to 223 contain graphic characters. Numbers 224 to 239 contain selected Greek characters. Numbers 240 to 255 contain math and extra symbols.
		Set 2 The difference in set 2 are ASCII numbers 3, 4, 5, 6, and 21. ASCII numbers 128 to 175 contain European characters.
	Graphics:	There are 20 block characters and programmable graphics.

(7) **Printing Sizes**	Characters per inch	Maximum characters per line
Subscript:	10	80
Superscript:	10	80

Additional Printer Specifications

Setting the DIP Switches

There are two DIP switches on the control circuit board. In order to satisfy the user's specific requirements, desired control modes are selectable by the DIP switches. The functions of the switches and their preset conditions at the time of shipment are as shown in the following figures.



Location of Printer DIP Switches

Switch Number	Function	On	Off	Factory-Set Condition
1-1	Not Applicable	—	—	On
1-2	CR	Print Only	Print & Line Feed	On
1-3	Buffer Full	Print Only	Print & Line Feed	Off
1-4	Cancel Code	Invalid	Valid	Off
1-5	Delete Code	Invalid	Valid	On
1-6	Error Buzzer	Sounds	Does Not Sound	On
1-7	Character Generator	N.A.	Graphic Patterns Select	Off
1-8	SLCT IN Signal	Fixed	Not Fixed	On

Functions and Conditions of DIP Switch 1 (Matrix)

Switch Number	Function	On	Off	Factory-Set Condition
2-1	Not Applicable	—	—	On
2-2	Not Applicable	—	—	On
2-3	Auto Feed XT Signal	Fixed Internally	Not Fixed Internally	Off
2-4	Coding Table Select	N.A.	Standard	Off

Functions and Conditions of DIP Switch 2 (Matrix)

Switch Number	Function	On	Off	Factory-Set Condition
1-1	Not Applicable	—	—	On
1-2	CR	Print Only	Print & Line Feed	On
1-3	Buffer Full	Print Only	Print & Line Feed	Off
1-4	Cancel Code	Invalid	Valid	Off
1-5	Not Applicable	—	—	On
1-6	Error Buzzer	Sound	Does Not Sound	On
1-7	Character Generator	Set 2	Set 1	Off
1-8	SLCT IN Signal	Fixed Internally	Not Fixed Internally	On

Functions and Conditions of DIP Switch 1 (Graphics)

Switch Number	Function	On	Off	Factory-Set Condition
2-1	Form Length	12 Inches	11 Inches	Off
2-2	Line Spacing	1/8 Inch	1/6 Inch	Off
2-3	Auto Feed XT Signal	Fixed Internally	Not Fixed Internally	Off
2-4	1 Inch Skip Over Perforation	Valid	Not Valid	Off

Functions and Conditions of DIP Switch 2 (Graphics)

Parallel Interface Description

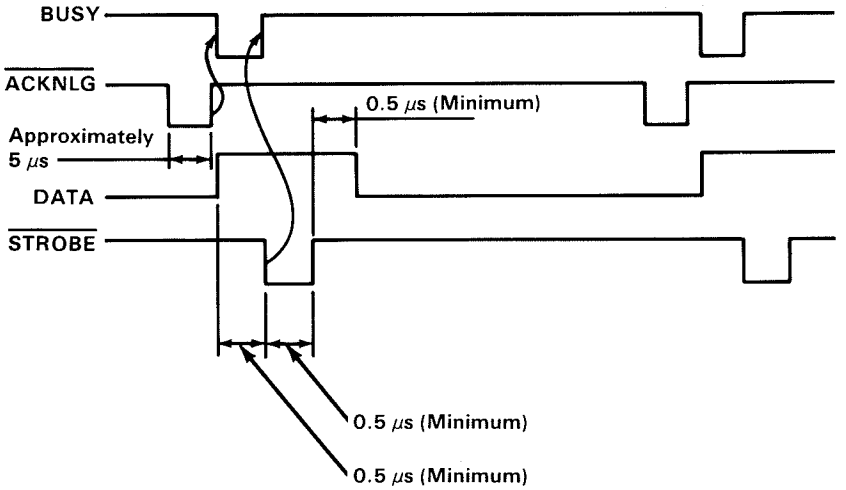
Specifications:

- Data transfer rate: 1000 cps (maximum)
- Synchronization: By externally-supplied $\overline{\text{STROBE}}$ pulses.
- Handshaking $\overline{\text{ACKNLG}}$ or BUSY signals.
- Logic level: Input data and all interface control signals are compatible with the TTL level.

Connector: Plug: 57-30360 (Amphenol)

Connector pin assignment and descriptions of respective interface signals are provided on the following pages.

Data transfer sequence:



Parallel Interface Timing Diagram

Signal Pin No.	Return Pin No.	Signal	Direction	Description
1	19	$\overline{\text{STROBE}}$	In	STROBE pulse to read data in. Pulse width must be more than 0.5 μs at receiving terminal. The signal level is normally "high"; read-in of data is performed at the "low" level of this signal.
2	20	DATA 1	In	These signals represent information of the 1st to 8th bits of parallel data respectively. Each signal is at "high" level when data is logical "1" and "low" when logical "0."
3	21	DATA 2	In	
4	22	DATA 3	In	
5	23	DATA 4	In	
6	24	DATA 5	In	
7	25	DATA 6	In	
8	26	DATA 7	In	
9	27	DATA 8	In	
10	28	$\overline{\text{ACKNLG}}$	Out	Approximately 5 μs pulse; "low" indicates that data has been received and the printer is ready to accept other data.
11	29	BUSY	Out	A "high" signal indicates that the printer cannot receive data. The signal becomes "high" in the following cases: 1. During data entry. 2. During printing operation. 3. In "offline" state. 4. During printer error status.

Connector Pin Assignment and Descriptions of Interface Signals (Part 1 of 3)

Signal Pin No.	Return Pin No.	Signal	Direction	Description
12	30	PE	Out	A "high" signal indicates that the printer is out of paper.
13	—	SLCT	Out	This signal indicates that the printer is in the selected state.
14	—	$\overline{\text{AUTO}}$ $\overline{\text{FEED XT}}$	In	With this signal being at "low" level, the paper is automatically fed one line after printing. (The signal level can be fixed to "low" with DIP SW pin 2-3 provided on the control circuit board.)
15	—	NC		Not used.
16	—	0V		Logic GND level.
17	—	CHASSIS-GND	—	Printer chassis GND. In the printer, the chassis GND and the logic GND are isolated from each other.
18	—	NC	—	Not used.
19-30	—	GND	—	"Twisted-Pair Return" signal; GND level.
31	—	$\overline{\text{INIT}}$	In	When the level of this signal becomes "low" the printer controller is reset to its initial state and the print buffer is cleared. This signal is normally at "high" level, and its pulse width must be more than 50 μs at the receiving terminal.

Connector Pin Assignment and Descriptions of Interface Signals (Part 2 of 3)

Signal Pin No.	Return Pin No.	Signal	Direction	Description
32		$\overline{\text{ERROR}}$	Out	The level of this signal becomes "low" when the printer is in "Paper End" state, "Offline" state and "Error" state.
33	—	GND	—	Same as with pin numbers 19 to 30.
34	—	NC	—	Not used.
35				Pulled up to +5 Vdc through 4.7 k-ohms resistance.
36	—	$\overline{\text{SLCT IN}}$	In	Data entry to the printer is possible only when the level of this signal is "low." (Internal fixing can be carried out with DIP SW 1-8. The condition at the time of shipment is set "low" for this signal.)

Notes: 1. "Direction" refers to the direction of signal flow as viewed from the printer.
2. "Return" denotes "Twisted-Pair Return" and is to be connected at signal-ground level.
When wiring the interface, be sure to use a twisted-pair cable for each signal and never fail to complete connection on the return side. To prevent noise effectively, these cables should be shielded and connected to the chassis of the system unit and printer, respectively.
3. All interface conditions are based on TTL level. Both the rise and fall times of each signal must be less than 0.2 μs.
4. Data transfer must not be carried out by ignoring the $\overline{\text{ACKNLG}}$ or BUSY signal. (Data transfer to this printer can be carried out only after confirming the $\overline{\text{ACKNLG}}$ signal or when the level of the BUSY signal is "low.")

Connector Pin Assignment and Descriptions of Interface Signals (Part 3 of 3)

Printer Modes for the IBM 80 CPS Printers

The IBM 80 CPS Graphics Printer can use any of the combinations listed below, and the print mode can be changed at any place within a line.

The IBM 80 CPS Matrix Printer cannot use the Subscript, Superscript, or Underline print modes. The Double Width print mode will affect the entire line with the matrix printer.

The allowed combinations of print modes that can be selected are listed in the following table. Modes can be selected and combined if they are in the same vertical column.

Printer Modes										
Normal	X	X	X							
Compressed					X	X	X			
Emphasized								X	X	X
Double Strike	X				X			X		
Subscript		X				X			X	
Superscript			X				X			X
Double Width	X	X	X		X	X	X	X	X	X
Underline	X	X	X		X	X	X	X	X	X

Printer Control Codes

On the following pages you will find complete codes for printer characters, controls, and graphics. You may want to keep them handy for future reference. The printer codes are listed in ASCII decimal numeric order (from NUL which is 0 to DEL which is 127). The examples given in the Printer Function descriptions are written in the BASIC language. The "input" description is given when more information is needed for programming considerations.

ASCII decimal values for the printer control codes can be found under "Printer Character Sets."

The descriptions that follow assume that the printer DIP switches have not been changed from their factory settings.

Printer Code	Printer Function
NUL	**Null** Used with ESC B and ESC D as a list terminator. NUL is also used with other printer control codes to select options (for example, ESC S). Example: LPRINT CHR$ (0);
BEL	**Bell** Sounds the printer buzzer for 1 second. Example: LPRINT CHR$ (7);
HT	**Horizontal Tab** Tabs to the next horizontal tap stop. Tab stops are set with ESC D. No tab stops are set when the printer is powered on. (Graphics Printer sets a tab stop every 8 columns when powered on.) Example: LPRINT CHR$ (9);
LF	**Line Feed** Spaces the paper up one line. Line spacing is 1/6-inch unless reset by ESC A, ESC 0, ESC 1, ESC 2 or ESC 3. Example: LPRINT CHR$(10);
VT	**Vertical Tab** Spaces the paper to the next vertical tab position. (Graphics Printer does not allow vertical tabs to be set; therefore, the VT code is treated as LF.) Example: LPRINT CHR$ (11);
FF	**Form Feed** Advances the paper to the top of the next page. **Note:** The location of the paper, when the printer is powered on, determines the top of the page. The next top of page is 11 inches from that position. ESC C can be used to change the page length. Example: LPRINT CHR$ (12);
CR	**Carriage Return** Ends the line that the printer is on and prints the data remaining in the printer buffer. (No Line Feed operation takes place.) **Note:** IBM Personal Computer BASIC adds a Line Feed unless 128 is added [for example, CHR$ (141)]. Example: LPRINT CHR$ (13);

Printer Code	Printer Function
SO	**Shift Out (Double Width)** Changes the printer to the Double Width print mode. **Note:** A Carriage Return, Line Feed or DC4 cancels Double Width print mode. Example: LPRINT CHR$(14);
SI	**Shift In (Compressed)** Changes the printer to the Compressed Character print mode. Example: LPRINT CHR$(15);
DC1	**Device Control 1 (Printer Selected)** (Graphics Printer ignores DC1) Printer accepts data from the system unit. Printer DIP switch 1-8 must be set to the Off position. Example: LPRINT CHR$(17);
DC2	**Device Control 2 (Compressed Off)** Stops printing in the Compressed print mode. Example: LPRINT CHR(18);
DC3	**Device Control 3 (Printer Deselected)** (Graphics Printer ignores DC3) Printer does not accept data from the system unit. The system unit must have the printer select line low, and DIP switch 1-8 must be in the Off position. Example: LPRINT CHR$(19);
DC4	**Device Control 4 (Double Width Off)** Stops printing in the Double Width print mode. Example: LPRINT CHR$(20);
CAN	**Cancel** Clears the printer buffer. Control codes, except SO, remain in effect. Example: LPRINT CHR$ (24);
ESC	**Escape** Lets the printer know that the next data sent is a printer command. (See the following list of commands.) Example: LPRINT CHR$(27);

Printer Code	Printer Function
ESC -	**Escape Minus (Underline)** Format: ESC -;n; (Graphics Printer only) ESC - followed by a 1, prints all of the following data with an underline. ESC - followed by a 0 (zero), cancels the Underline print mode. Example: LPRINT CHR$(27);CHR$(45);CHR$(1);
ESC 0	**Escape Zero (1/8-Inch Line Feeding)** Changes paper feeding to 1/8 inch. Example: LPRINT CHR$(27);CHR$(48);
ESC 1	**Escape 1 (7/72-Inch Line Feeding)** Changes paper feed to 7/72 inch. Example: LPRINT CHR$(27);CHR$(49);
ESC 2	**Escape Two (Starts Variable Line Feeding)** ESC 2 is an execution command for ESC A. If no ESC A command has been given, line feeding returns to 1/6-inch. Example: LPRINT CHR$(27);CHR$(50);
ESC 3	**Escape Three (Variable Line Feeding)** Format: ESC 3;n; (Graphics Printer only) Changes the paper feeding to n/216-inch. The example below sets the paper feeding to 54/216 (1/4) inch. The value of n must be between 1 and 255. Example: LPRINT CHR$(27);CHR$(51);CHR$(54);
ESC 6	**Escape Six (Select Character Set 2)** (Graphics Printer only) Selects character set 2. (See "Printer Character Set 2.") Example: LPRINT CHR$(27);CHR$(54);
ESC 7	**Escape Seven (Select Character Set 1.)** (Graphics Printer only) Selects character set 1. (See "Printer Character Set 1.") Character set 1 is selected when the printer is powered on or reset. Example: LPRINT CHR$(27);CHR$(55);
ESC 8	**Escape Eight (Ignore Paper End)** Allows the printer to print to the end of the paper. The printer ignores the Paper End switch. Example: LPRINT CHR$(27);CHR$(56);

Printer Code	Printer Function
ESC 9	**Escape Nine (Cancel Ignore Paper End)** Cancels the Ignore Paper End command. ESC 9 is selected when the printer is powered on or reset. Example: LPRINT CHR$(27);CHR$(57);
ESC <	**Escape Less Than (Home Head)** (Graphics Printer only) The print head will return to the left margin to print the line following ESC <. This will occur for one line only. Example: LPRINT CHR$(27);CHR$(60);
ESC A	**Escape A (Sets Variable Line Feeding)** Format: ESC A;n; Escape A sets the line-feed to n/72-inch. The example below tells the printer to set line feeding to 24/72-inch. ESC 2 must be sent to the printer before the line feeding will change. For example, ESC A;24 (text) ESC 2 (text). The text following ESC A;24 will space at the previously set line-feed increments. The text following ESC 2 will be printed with new line-feed increments of 24/72-inch. Any increment between 1/72 and 85/72 may be used. Example: LPRINT CHR$(27);CHR$(65);CHR$(24);CHR$(27);CHR$(50);
ESC B	**Escape B (Set Vertical Tabs)** Format: ESC B;n_1;n_2;...n_k;NUL; (Graphics Printer ignores ESC B) Sets vertical tab stop positions. Up to 64 vertical tab stop positions are recognized by the printer. The n's, in the format above, are used to indicate tab stop positions. Tab stop numbers must be received in ascending numeric order. The tab stop numbers will not become valid until the NUL code is entered. Once vertical tab stops are established, they will be valid until new tab stops are specified. (If the printer is reset or powered Off, set tab stops are cleared.) If no tab stop is set, the Vertical Tab command behaves as a Line Feed command. ESC B followed only by NUL will cancel tab stops. The form length must be set by the ESC C command prior to setting tabs. Example: LPRINT CHR$(27);CHR$(66);CHR$(10);CHR$(20);CHR$(40);CHR$(0);

Printer Code	Printer Function
ESC C	**Escape C (Set Lines per Page)** Format: ESC C;n; Sets the page length. The ESC C command must have a value following it to specify the length of page desired. (Maximum form length for the printer is 127 lines.) The example below sets the page length to 55 lines. The printer defaults to 66 lines per page when powered on or reset. Example: LPRINT CHR$(27);CHR$(67);CHR$(55); **Escape C (Set Inches per Page)** Format: ESC C;n;m; (Graphics Printer only) Escape C sets the length of the page in inches. This command requires a value of 0 (zero) for n, and a value between 1 and 22 for m. Example: LPRINT CHR$(27);CHR$(67);CHR$(0);CHR$(12);
ESC D	**Escape D (Set Horizontal Tab Stops)** Format: ESC D;n_1;n_2;...n_k;NUL; Sets the horizontal tab stop positions. The example below shows the horizontal tab stop positions set at printer column positions of 10, 20, and 40. They are followed by CHR$(0), the NUL code. They must also be in ascending numeric order as shown. Tab stops can be set between 1 and 80. When in the Compressed print mode, tab stops can be set up to 132. The maximum number of tabs that can be set is 112. The Graphics Printer can have a maximum of 28 tab stops. The HT (CHR$(9)) is used to execute a tab operation. Example: LPRINT CHR$(27);CHR$(68);CHR$(10)CHR$(20)CHR$(40);CHR$(0);
ESC E	**Escape E (Emphasized)** Changes the printer to the Emphasized print mode. The speed of the printer is reduced to half speed during the Emphasized print mode. Example: LPRINT CHR$(27);CHR$(69);
ESC F	**Escape F (Emphasized Off)** Stops printing in the Emphasized print mode. Example: LPRINT CHR$(27);CHR$(70);
ESC G	**Escape G (Double Strike)** Changes the printer to the Double Strike print mode. The paper is spaced 1/216 of an inch before the second pass of the print head. Example: LPRINT CHR$(27);CHR$(71);

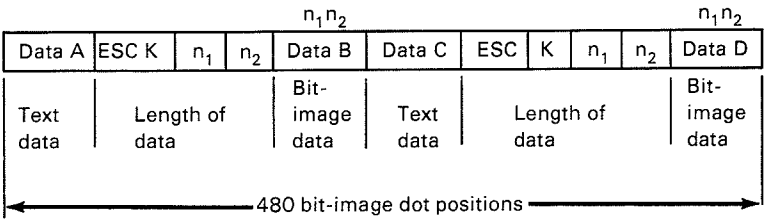
Printer Code	Printer Function
ESC H	**Escape H (Double Strike Off)** Stops printing in the Double Strike mode. Example: LPRINT CHR$(27);CHR$(72);
ESC J	**Escape J (Set Variable Line Feeding)** Format: ESC J;n; (Graphics Printer only) When ESC J is sent to the printer, the paper will feed in increments of n/216 of an inch. The value of n must be between 1 and 255. The example below gives a line feed of 50/216-inch. ESC J is canceled after the line feed takes place. Example: LPRINT CHR$(27);CHR$(74);CHR$(50);
ESC K	**Escape K (480 Bit-Image Graphics Mode)** Format ESC K;n_1;n_2;v_1;v_2;...v_k; (Graphics Printer only) Changes from the Text mode to the Bit-Image Graphics mode. n_1 and n_2 are one byte, which specify the number of bit-image data bytes to be transferred. v_1 through v_k are the bytes of the bit-image data. The number of bit-image data bytes (k) is equal to $n_1 + 256n_2$ and cannot exceed 480 bytes. At every horizontal position, each byte can print up to 8 vertical dots. Bit-image data may be mixed with text data on the same line. **Note:** Assign values to n_1 and n_2 as follows: n_1 represents values from 0 - 255. n_2 represents values from 0 - 1 x 256. MSB is most significant bit and LSB is least significant bit. n_2 MSB ... LSB 15 14 13 12 11 10 9 8 2^{15} 2^{14} 2^{13} 2^{12} 2^{11} 2^{10} 2^{9} 2^{8} n_1 MSB ... LSB 7 6 5 4 3 2 1 0 2^{7} 2^{6} 2^{5} 2^{4} 2^{3} 2^{2} 2^{1} 2^{0}

Data sent to the printer.

Text (20 characters)	ESC	K	n=360	Bit-image data	Next data

In text mode, 20 characters in text mode correspond to 120 bit-image positions (20 x 6 = 120). The printable portion left in Bit-Image mode is 360 dot positions (480 - 120 = 360).

Data sent to the printer.



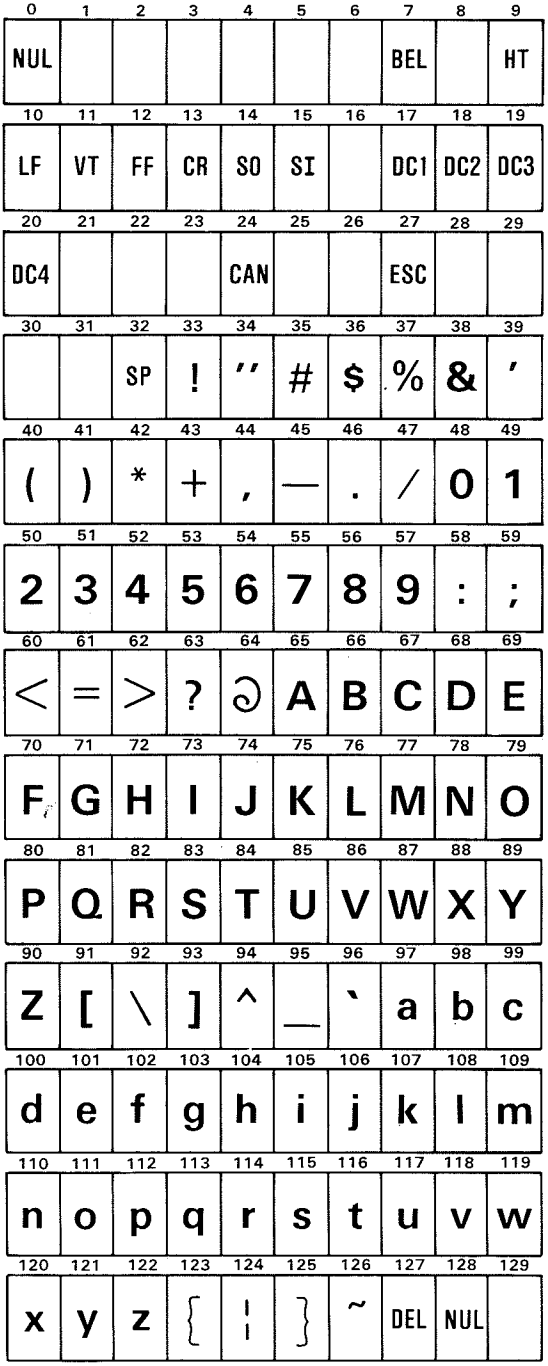
Example:

```
TYPE B:GRAPH.TXT
1  'OPEN PRINTER IN RANDOM MODE WITH LENGTH OF 255
2  OPEN "LPT1:" AS #1
3  WIDTH "LPT1:",255
4  PRINT #1,CHR$(13);CHR$(10);
5  SLASH$=CHR$(1)+CHR$(02)+CHR$(04)+CHR$(08)
6  SLASH$=SLASH$+CHR$(16)+CHR$(32)+CHR$(64)+CHR$(128)+CHR$(0)
7  GAP$=CHR$(0)+CHR$(0)+CHR$(0)
8  NDOTS=480
9  'ESC K N1 N2
10 PRINT #1,CHR$(27);"K";CHR$(NDOTS MOD 256);CHR$(FIX (NDOTS/256));
11 ' SEND NDOTS NUMBER OF BIT IMAGE BYTES
12 FOR I=1 TO NDOTS/12 'NUMBER OF SLASHES TO PRINT USING
   GRAPHICS
13 PRINT #1,SLASH$;GAP$;
14 NEXT I
15 CLOSE
16 END
```

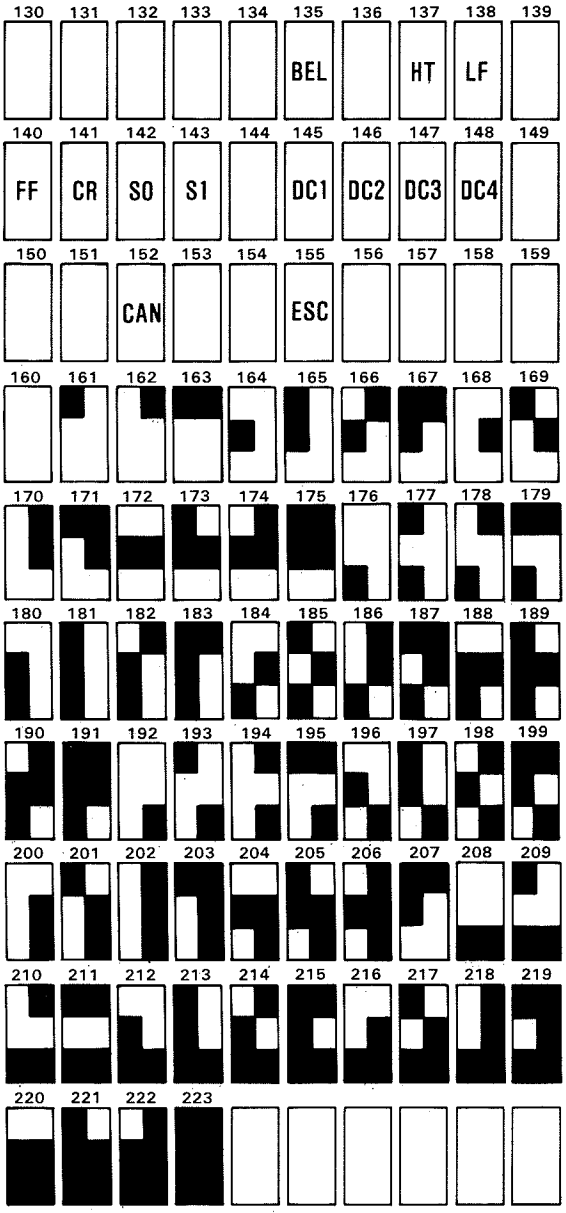
This example will give you a row of slashes printed in the 480 Bit-Image mode.

Printer Code	Printer Function
ESC L	**Escape L (960 Bit-Image Graphics Mode)** Format: ESC L;n_1;n_2;v_1;v_2;...v_k; (Graphics Printer only) Changes from the Text mode to the Bit-Image Graphics mode. The input is similar to ESC K. The 960 Bit-Image mode prints at half the speed of the 480 Bit-Image Graphics mode, but can produce a denser graphic image. The number of bytes of bit-image Data (k) is $n_1 + 256n_2$ but cannot exceed 960. n_1 is in the range of 0 to 255.
ESC N	**Escape N (Set Skip Perforation)** Format ESC N;n; (Graphics Printer only) Sets the Skip Perforation function. The number following ESC N sets the value for the number of lines of Skip Perforation. The example shows a 12-line skip perforation. This will print 54 lines and feed the paper 12 lines. The value of n must be between 1 and 127. ESC N must be reset anytime the page length (ESC C) is changed. Example: CHR$(27);CHR$(78);CHR$(12);
ESC O	**Escape O (Cancel Skip Perforation)** (Graphics Printer only) Cancels the Skip Perforation function. Example: LPRINT CHR$(27);CHR$(79);
ESC S	**Escape S (Subscript/Superscript)** Format: ESC S;n; (Graphics Printer only) Changes the printer to the Subscript print mode when ESC S is followed by a 1, as in the example below. When ESC S is followed by a 0 (zero), the printer will print in the Superscript print mode. Example: LPRINT CHR$(27);CHR$(83);CHR$(1);
ESC T	**Escape T (Subscript/Superscript Off)** (Graphics Printer only) The printer stops printing in the Subscript or Superscript print mode. Example: LPRINT CHR$(27);CHR$(84);
ESC U	**Escape U (Unidirectional Printing)** Format: ESC U;n; (Graphics Printer only) The printer will print from left to right following the input of ESC U;1. When ESC U is followed by a 0 (zero), the left to right printing operation is canceled. The Unidirectional print mode (ESC U) ensures a more accurate print-start position for better print quality. Example: LPRINT CHR$(27);CHR$(85);CHR$(1);

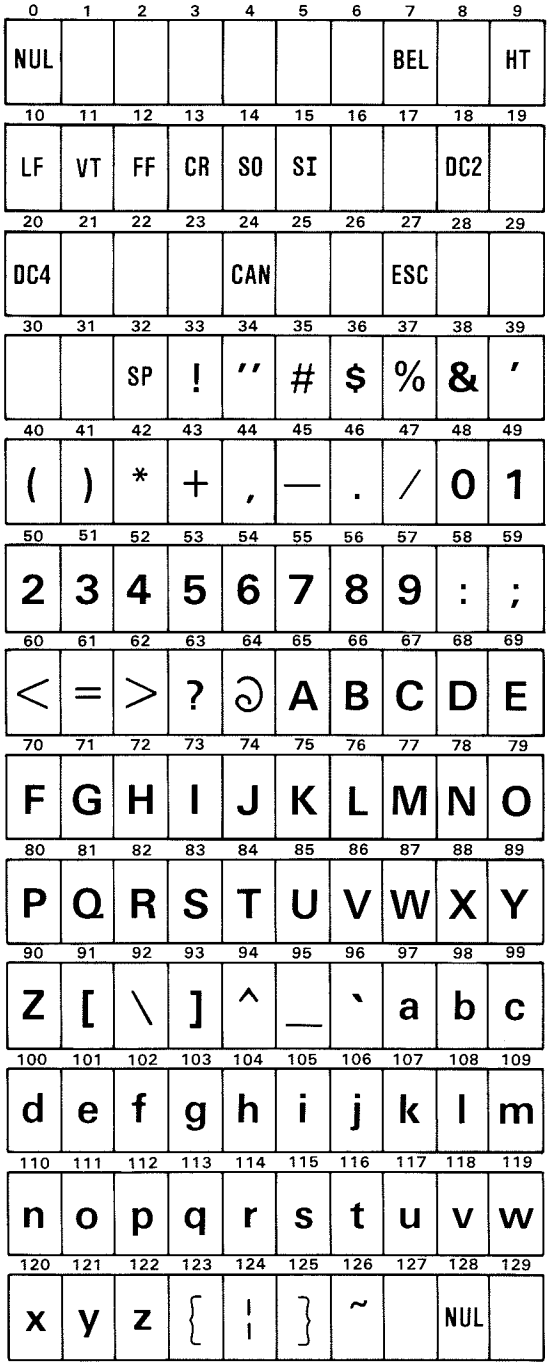
Printer Code	Printer Function
ESC W	**Escape W (Double Width)** Format: ESC W;n; (Graphics Printer only) Changes the printer to the Double Width print mode when ESC W is followed by a 1. This mode is not canceled by a line-feed operation and must be canceled with ESC W followed by a 0 (zero). Example: LPRINT CHR$(27);CHR$(87);CHR$(1);
ESC Y	**Escape Y (960 Bit-Image Graphics Mode Normal Speed)** Format: ESC Y $n_1;n_2;v_1;v_2;...v_k;$ (Graphics Printer only) Changes from the Text mode to the 960 Bit-Image Graphics mode. The printer prints at normal speed during this operation and cannot print dots on consecutive dot positions. The input of data is similar to ESC L.
ESC Z	**Escape Z (1920 Bit-Image Graphics Mode)** Format: ESC $Z;n_1;n_2;v_1;v_2;...v_k;$ (Graphics Printer only) Changes from the Text mode to the 1920 Bit-Image Graphics mode. The input is similar to the other Bit-Image Graphics modes. ESC Z can print only every third dot position.
DEL	**Delete (Clear Printer Buffer)** (Graphics Printer ignores DEL) Clears the printer buffer. Control codes, except SO, still remain in effect. DIP switch 1-5 must be in the Off position. Example: LPRINT CHR$(127);



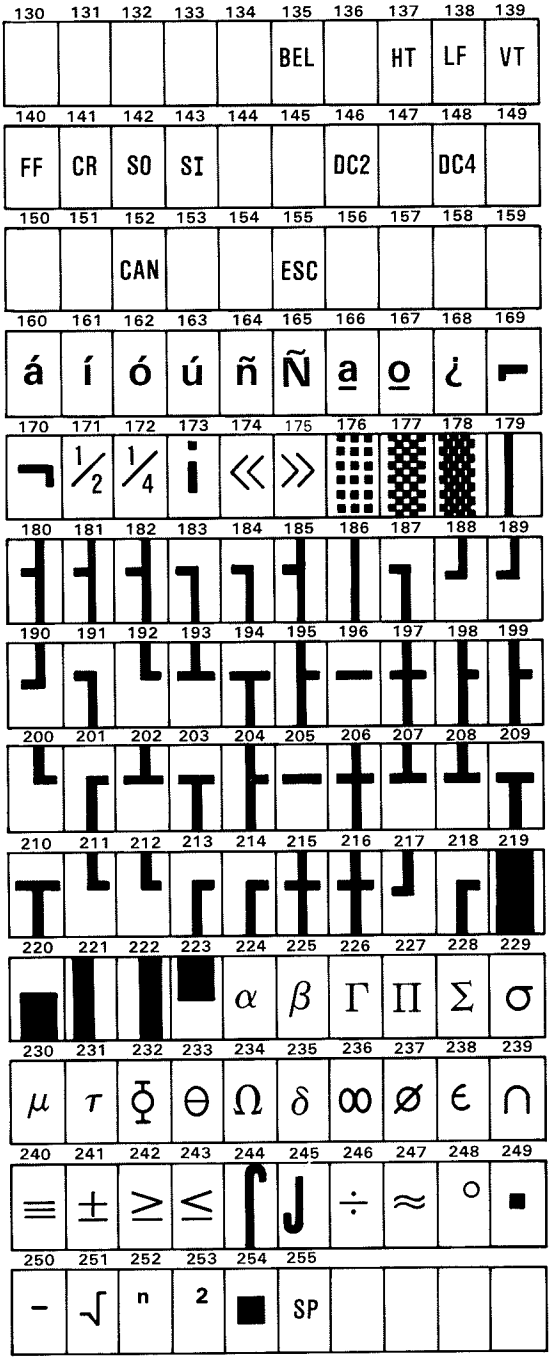
Matrix Printer Character Set (Part 1 of 2)



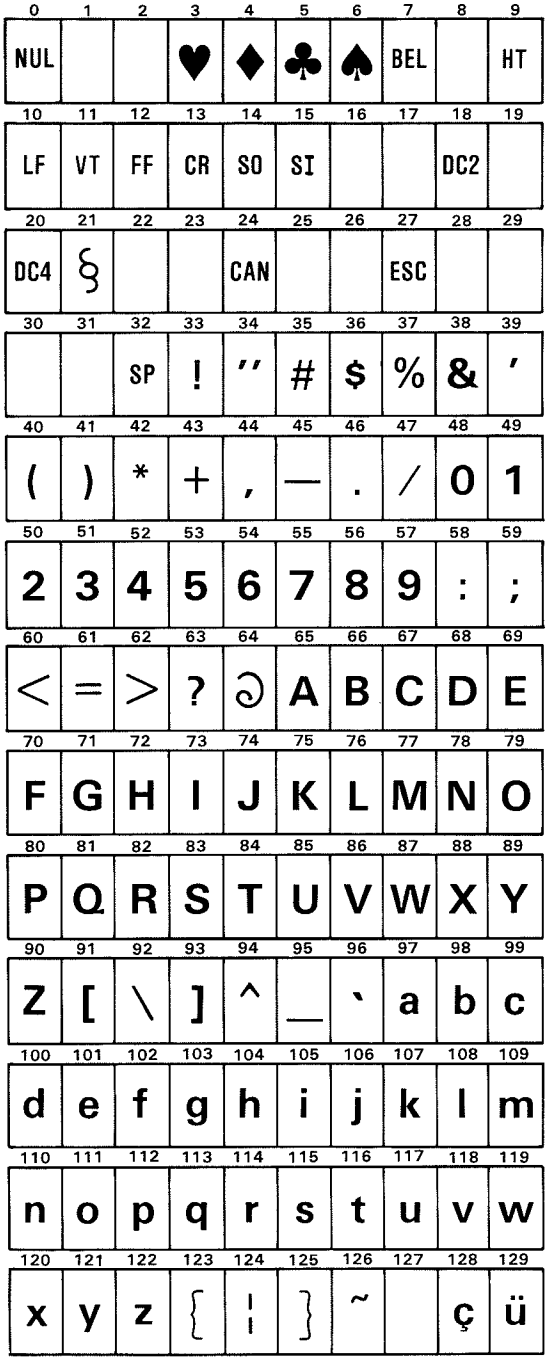
Matrix Printer Character Set (Part 2 of 2)



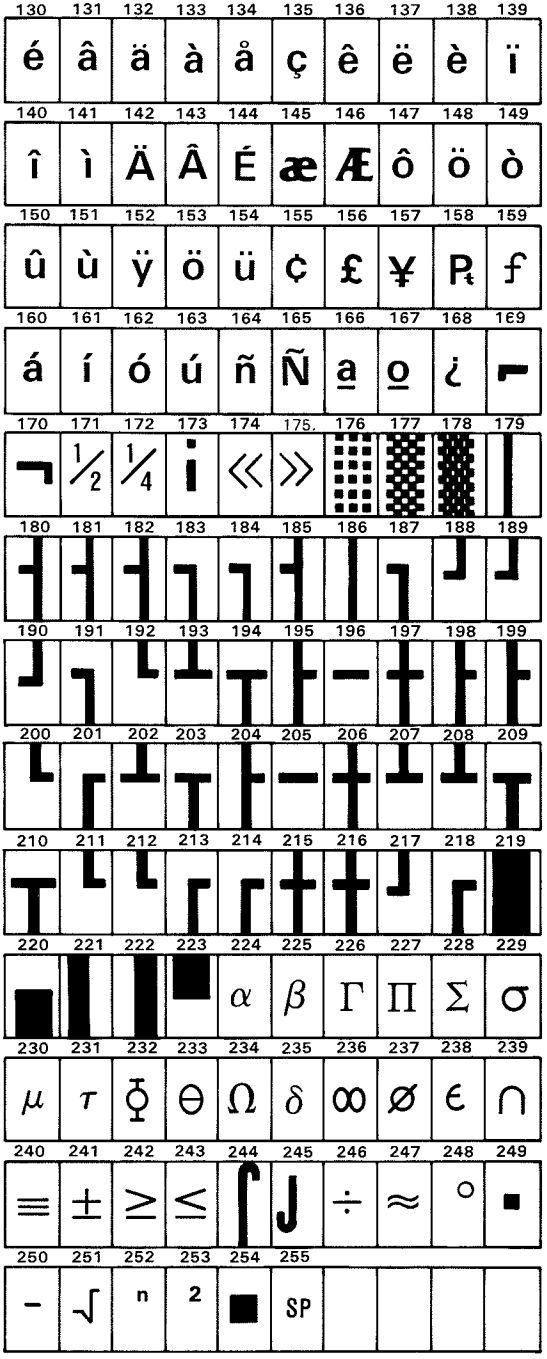
Graphics Printer Character Set 1 (Part 1 of 2)



Graphics Printer Character Set 1 (Part 2 of 2)



Graphics Printer Character Set 2 (Part 1 of 2)



Graphics Printer Character Set 2 (Part 2 of 2)

IBM Printer Adapter

The printer adapter is specifically designed to attach printers with a parallel port interface, but it can be used as a general input/output port for any device or application that matches its input/output capabilities. It has 12 TTL-buffer output points, which are latched and can be written and read under program control using the processor In or Out instruction. The adapter also has five steady-state input points that may be read using the processor's In instructions.

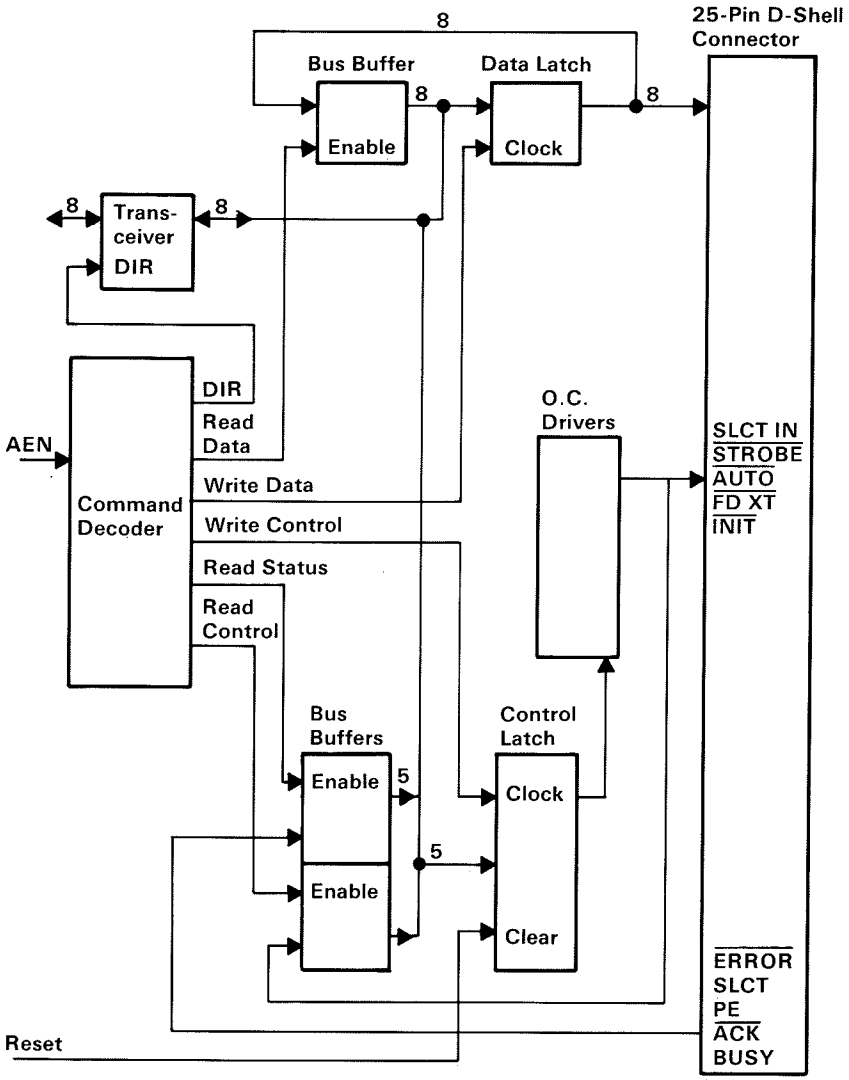
In addition, one input can also be used to create a processor interrupt. This interrupt can be enabled and disabled under program control. Reset from the power-on circuit is also ORed with a program output point, allowing a device to receive a power-on reset when the processor is reset.

The input/output signals are made available at the back of the adapter through a right-angled, PCB-mounted, 25-pin, D-shell connector. This connector protrudes through the rear panel of the system or expansion unit, where a cable may be attached.

When this adapter is used to attach a printer, data or printer commands are loaded into an 8-bit, latched, output port, and the strobe line is activated, writing data to the printer. The program then may read the input ports for printer status indicating when the next character can be written, or it may use the interrupt line to indicate "not busy" to the software.

The output ports may also be read at the card's interface for diagnostic loop functions. This allows faults to be isolated between the adapter and the attaching device.

This same function is also part of the combination IBM Monochrome Display and Printer Adapter. A block diagram of the printer adapter is on the next page.



Printer Adapter Block Diagram

Programming Considerations

The printer adapter responds to five I/O instructions: two output and three input. The output instructions transfer data into 2 latches whose outputs are presented on pins of a 25-pin D-shell connector.

Two of the three input instructions allow the processor to read back the contents of the two latches. The third allows the processor to read the real time status of a group of pins on the connector.

A description of each instruction follows.

IBM Monochrome Display & Printer Adapter				**Printer Adapter**			
Output to address hex 3BC				Output to address hex 378			
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2

The instruction captures data from the data bus and is present on the respective pins. These pins are each capable of sourcing 2.6 mA and sinking 24 mA.

It is essential that the external device not try to pull these lines to ground.

IBM Monochrome Display & Printer Adapter		**Printer Adapter**			
Output to address hex 3BE		Output to address hex 37A			
	Bit 4	$\overline{\text{Bit 3}}$	Bit 2	$\overline{\text{Bit 1}}$	$\overline{\text{Bit 0}}$
	IRQ Enable	Pin 17	Pin 16	Pin 14	Pin 1

This instruction causes the latch to capture the five least significant bits of the data bus. The four least significant bits present their outputs, or inverted versions of their outputs, to the respective pins shown above. If bit 4 is written as 1, the card will interrupt the processor on the condition that pin 10 transitions high to low.

These pins are driven by open collector drivers pulled to +5 Vdc through 4.7 k-ohm resistors. They can each sink approximately 7 mA and maintain 0.8 volts down-level.

IBM Monochrome Display & Printer Adapter	Printer Adapter
Input from address hex 3BC	Input from address hex 378

This command presents the processor with data present on the pins associated with the out to hex 3BC. This should normally reflect the exact value that was last written to hex 3BC. If an external device should be driving data on these pins (in violation of usage ground rules) at the time of an input, this data will be ORed with the latch contents.

IBM Monochrome Display & Printer Adapter	Printer Adapter
Input from address hex 3BD	Input from address hex 379

This command presents realtime status to the processor from the pins as follows.

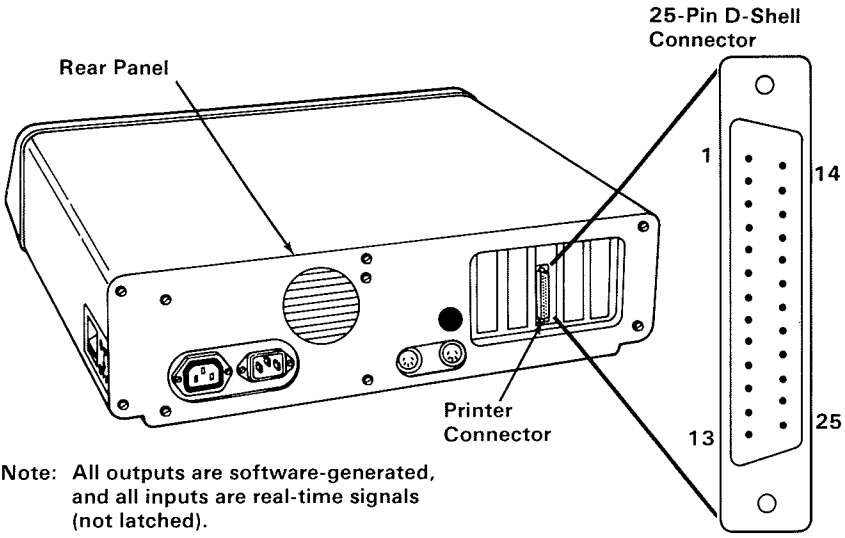
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Pin 11	Pin 10	Pin 12	Pin 13	Pin 15	—	—	—

IBM Monochrome Display & Printer Adapter	Printer Adapter
Input from address hex 3BE	Input from address hex 37A

This instruction causes the data present on pins 1, 14, 16, 17, and the IRQ bit to read by the processor. In the absence of external drive applied to these pins, data read by the processor will exactly match data last written to hex 3BE in the same bit positions. Note that data bits 0-2 are not included. If external drivers are dotted to these pins, that data will be ORed with data applied to the pins by the hex 3BE latch.

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
			IRQ Enable	$\overline{\text{Pin 17}}$	Pin 16	$\overline{\text{Pin 14}}$	$\overline{\text{Pin 1}}$
			Por=0	Por=1	Por=0	Por=1	Por=1

These pins assume the states shown after a reset from the processor.



Note: All outputs are software-generated, and all inputs are real-time signals (not latched).

At Standard TTL Levels

Printer	Signal Name	Adapter Pin Number	Printer Adapter
	-Strobe	1	
	+Data Bit 0	2	
	+Data Bit 1	3	
	+Data Bit 2	4	
	+Data Bit 3	5	
	+Data Bit 4	6	
	+Data Bit 5	7	
	+Data Bit 6	8	
	+Data Bit 7	9	
	-Acknowledge	10	
	+Busy	11	
	+P.End (out of paper)	12	
	+Select	13	
	-Auto Feed	14	
	-Error	15	
	-Initialize Printer	16	
	-Select Input	17	
	Ground	18-25	

Connector Specifications

IBM Monochrome Display and Printer Adapter

This chapter has two functions. The first is to provide the interface to the IBM Monochrome Display. The second provides a parallel interface for the IBM 80 CPS Printer. This second function is fully discussed in the "IBM Printer Adapter" section.

The monitor adapter is designed around the Motorola 6845 CRT controller module. There are 4K bytes of static memory on the adapter which is used for the display buffer. This buffer has two ports and may be accessed directly by the processor. No parity is provided on the display buffer.

Two bytes are fetched from the display buffer in 553 ns, providing a data rate of 1.8M bytes/second.

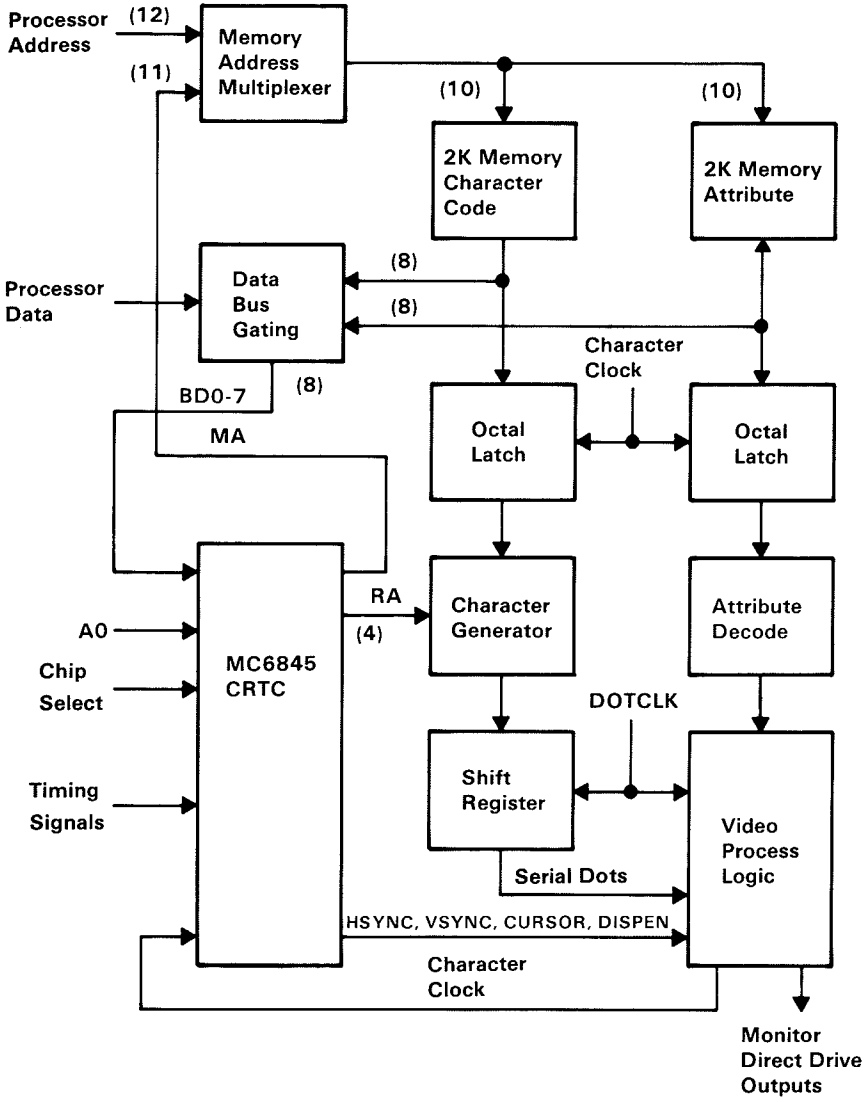
The monitor adapter supports 256 different character codes. An 8K-byte character generator contains the fonts for the character codes. The characters, values, and screen characteristics are given in "Appendix C: Of Characters, Keystrokes, and Color."

This monitor adapter, when used with a display containing P39 phosphor, will not support a light pen.

Where possible, only one low-power Schottky (LS) load is present on any I/O slot. Some of the address bus lines have two LS loads. No signal has more than two LS loads.

Characteristics of the monitor adapter are listed below:

- 80 by 25 screen
- Direct-drive output
- 9 by 14 character box
- 7 by 9 character
- 18 kHz monitor
- Character attributes



IBM Monochrome Display Adapter Block Diagram

Programming Considerations

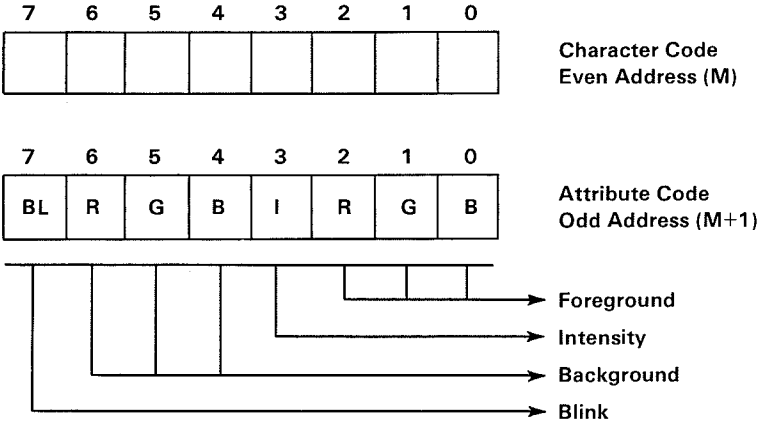
The following table summarizes the 6845 internal data registers, their functions, and their parameters. For the IBM Monochrome Display, the values must be programmed into the 6845 to ensure proper initialization of the device.

Register Number	Register File	Program Unit	IBM Monochrome Display (Address in hex)
R0	Horizontal Total	Characters	61
R1	Horizontal Displayed	Characters	50
R2	Horizontal Sync Position	Characters	52
R3	Horizontal Sync Width	Characters	F
R4	Vertical Total	Character Rows	19
R5	Vertical Total Adjust	Scan Line	6
R6	Vertical Displayed	Character Row	19
R7	Vertical Sync Position	Character Row	19
R8	Interlace Mode	--------	02
R9	Maximum Scan Line Address	Scan Line	D
R10	Cursor Start	Scan Line	B
R11	Cursor End	Scan Line	C
R12	Start Address (H)	--------	00
R13	Start Address (L)	--------	00
R14	Cursor (H)	--------	00
R15	Cursor (L)	--------	00
R16	Reserved	--------	--
R17	Reserved	--------	--

To ensure proper initialization, the first command issued to the attachment must be to send to CRT control port 1 (hex 3B8), a hex 01, to set the high-resolution mode. If this bit is not set, then the processor access to the monochrome adapter must never occur. If the high-resolution bit is not set, the processor will stop running.

System configurations that have both an IBM Monochrome Display Adapter and Printer Adapter, and an IBM Color/Graphics Monitor Adapter, must ensure that both adapters are properly initialized after a power-on reset. Damage to either display may occur if not properly initialized.

The IBM Monochrome Display and Printer Adapter supports 256 different character codes. In the character set are alphanumerics and block graphics. Each character in the display buffer has a corresponding character attribute. The character code must be an even address, and the attribute code must be an odd address in the display buffer.



The adapter decodes the character attribute byte as defined above. The blink and intensity bits may be combined with the foreground and background bits to further enhance the character attribute functions listed below.

Background R G B	Foreground R G B	Function
0 0 0	0 0 0	Non-Display
0 0 0	0 0 1	Underline
0 0 0	1 1 1	White Character/Black Background
1 1 1	0 0 0	Reverse Video

The 4K display buffer supports one screen of 25 rows of 80 characters, plus a character attribute for each display character. The starting address of the buffer is hex B0000. The display buffer can be read from using DMA; however, at least one wait-state will be inserted by the processor. The duration of the wait-state will vary, because the processor/monitor access is synchronized with the character clock on this adapter.

Interrupt level 7 is used on the parallel interface. Interrupts can be enabled or disabled through the printer control port. The interrupt is a high-level active signal.

The figure below breaks down the functions of the I/O address decode for the adapter. The I/O address decode is from hex 3B0 through hex 3BF. The bit assignment for each I/O address follows:

I/O Register Address	Function
3B0	Not Used
3B1	Not Used
3B2	Not Used
3B3	Not Used
3B4*	6845 Index Register
3B5*	6845 Data Register
3B6	Not Used
3B7	Not Used
3B8	CRT Control Port 1
3B9	Reserved
3BA	CRT Status Port
3BB	Reserved
3BC	Parallel Data Port
3BD	Printer Status Port
3BE	Printer Control Port
3BF	Not Used

*The 6845 Index and Data Registers are used to program the CRT controller to interface the high-resolution IBM Monochrome Display.

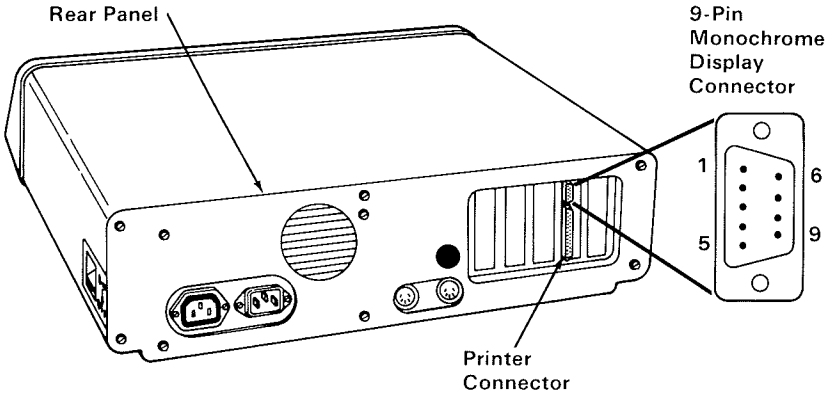
I/O Address and Bit Map

Bit Number	Function
0	+High Resolution Mode
1	Not Used
2	Not Used
3	+Video Enable
4	Not Used
5	+Enable Blink
6,7	Not Used

6845 CRT Control Port 1 (Hex 3B8)

Bit Number	Function
0	+Horizontal Drive
1	Reserved
2	Reserved
3	+Black/White Video

6845 CRT Status Port (Hex 3BA)



At Standard TTL Levels

IBM Monochrome Display			IBM Monochrome Display and Printer Adapter
	Ground	1	
	Ground	2	
	Not Used	3	
	Not Used	4	
	Not Used	5	
←	+Intensity	6	
←	+Video	7	
←	+Horizontal	8	
←	-Vertical	9	

Note: Signal voltages are 0.0 to 0.6 Vdc at down level and +2.4 to 3.5 Vdc at high level.

Connector Specifications

Notes:

IBM Monochrome Display

The high-resolution IBM Monochrome Display attaches to the system unit through two cables approximately 3 feet (914 millimeters) in length. One cable is a signal cable that contains the direct drive interface from the IBM Monochrome Display and Printer Adapter.

The second cable provides ac power to the display from the system unit. This allows the system-unit power switch to also control the display unit. An additional benefit is a reduction in the requirements for wall outlets to power the system. The display contains an 11-½ inch (283 millimeters), diagonal 90° deflection CRT. The CRT and analog circuits are packaged in an enclosure so the display may either sit on top of the system unit or on a nearby tabletop or desk. The unit has both brightness and contrast adjustment controls on the front surface that are easily accessible to the operator.

Operating Characteristics

Screen

- High-persistence green phosphor (P 39).
- Etched surface to reduce glare.
- Size is 80 characters by 25 lines.
- Character box is 9 dots wide by 14 dots high.

Video Signal

- Maximum bandwidth of 16.257 MHz.

Vertical Drive

- Screen refreshed at 50 Hz with 350 lines of vertical resolution and 720 lines of horizontal resolution.

Horizontal Drive

- Positive-level, TTL-compatibility at a frequency of 18.432 kHz.

IBM Color/Graphics Monitor Adapter

The IBM Color/Graphics Monitor Adapter is designed to attach to the IBM Color Display, to a variety of television-frequency monitors, or to home television sets (user-supplied RF modulator is required for home television sets). The adapter is capable of operating in black-and-white or color. It provides three video interfaces: a composite-video port, a direct-drive port, and a connection interface for driving a user-supplied RF modulator. In addition, a light pen interface is provided.

The adapter has two basic modes of operation: alphanumeric (A/N) and all-points-addressable graphics (APA). Additional modes are available within the A/N and APA modes. In the A/N mode, the display can be operated in either a 40-column by 25-row mode for a low-resolution monitor or home television, or in an 80-column by 25-row mode for high-resolution monitors. In both modes, characters are defined in an 8-wide by 8-high character box and are 7-wide by 7-high, with one line of descender for lowercase characters. Both uppercase and lowercase characters are supported in all modes.

The character attributes of reverse video, blinking, and highlighting are available in the black-and-white mode. In the color mode, sixteen foreground and eight background colors are available for each character. In addition, blinking on a per-character basis is available.

The monitor adapter contains 16K bytes of storage. As an example, a 40-column by 25-row display screen uses 1000 bytes to store character information, and 1000 bytes to store attribute/color information. This would mean that up to eight display screens can be stored in the adapter memory. Similarly, in an 80-column by 25-row mode, four display screens may be stored in the adapter. The entire 16K bytes of storage on the display adapter are directly addressable by the processor, which allows maximum software flexibility in managing the screen.

In A/N color modes, it is also possible to select the color of the screen's border. One of sixteen colors can be selected.

In the APA mode, there are two resolutions available: a medium-resolution color graphics mode (320 PELs by 200 rows) and a high-resolution black-and-white graphics mode (640 PELs by 200 rows). In the medium-resolution mode, each picture element (PEL) may have one of four colors. The background color (color 0) may be any of the 16 possible colors. The remaining three colors come from one of the two software-selectable palettes. One palette contains green/red/brown; the other contains cyan/magenta/white.

The high-resolution mode is available only in black-and-white because the entire 16K bytes of storage in the adapter is used to define the on or off of the PELs.

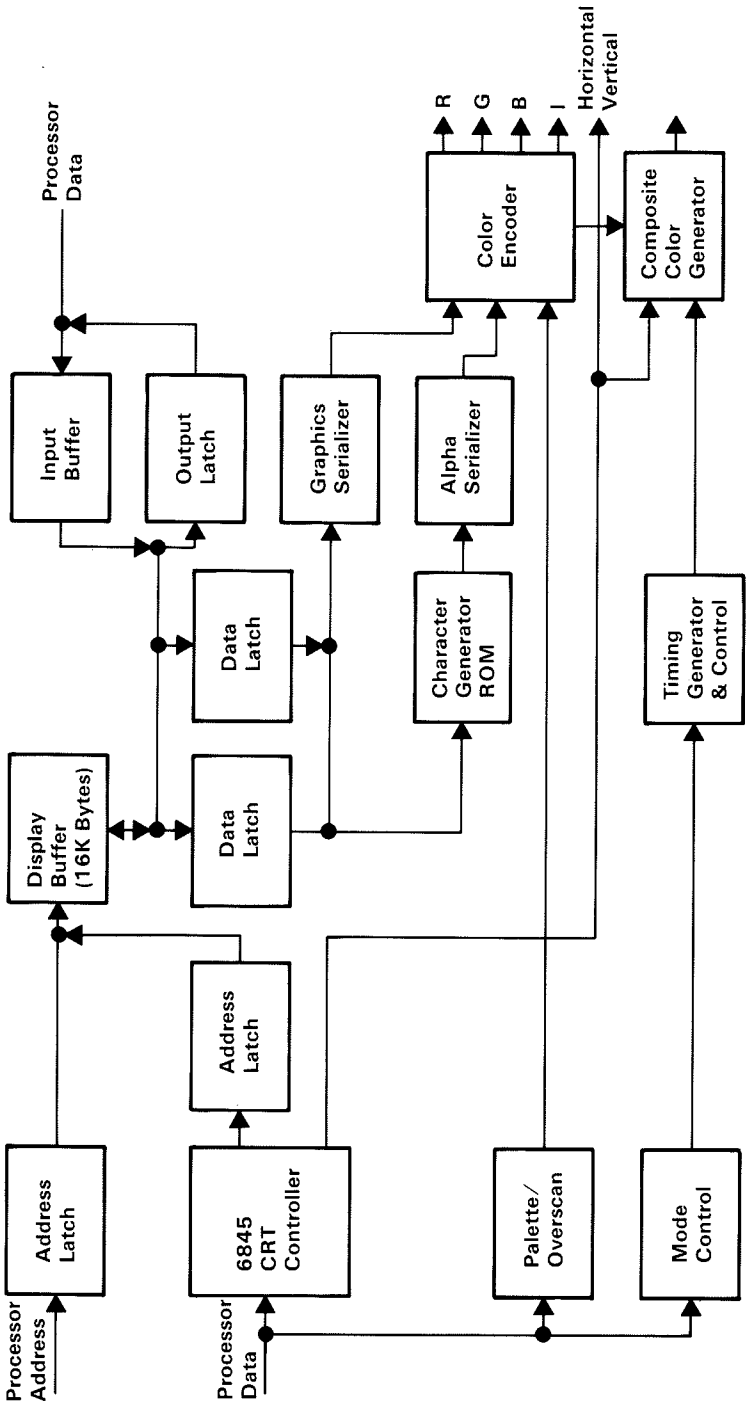
The adapter operates in noninterlace mode at either 7 or 14 MHz, depending on the mode of operation selected.

In the A/N mode, characters are formed from a ROM character generator. The character generator contains dot patterns for 256 different characters. The character set contains the following major groupings of characters:

- 16 special characters for game support
- 15 characters for word-processing editing support
- 96 characters for the standard ASCII graphics set
- 48 characters for foreign-language support
- 48 characters for business block-graphics support (allowing drawing of charts, boxes, and tables using single and double lines)
- 16 selected Greek characters
- 15 selected scientific-notation characters

The color/graphics monitor adapter function is packaged on a single card. The direct-drive and composite-video ports are right-angle mounted connectors on the adapter, and extend through the rear panel of the unit. The direct-drive video port is a 9-pin D-shell female connector. The composite-video port is a standard female phono-jack.

The display adapter is implemented using a Motorola 6845 CRT controller device. This adapter is highly programmable with respect to raster and character parameters. Therefore, many additional modes are possible with clever programming of the adapter.



Color/Graphics Monitor Adapter Block Diagram

Descriptions of Major Components

Motorola 6845 CRT Controller

This device provides the necessary interface to drive a raster-scan CRT.

Mode Set Register

This is a general-purpose, programmable, I/O register. It has I/O ports that may be individually programmed. Its function in this attachment is to provide mode selection and color selection in the medium-resolution color-graphics mode.

Display Buffer

The display buffer resides in the processor-address space, starting at address hex B8000. It provides 16K bytes of dynamic read/write memory. A dual-ported implementation allows the processor and the graphics control unit to access the buffer. The processor and the CRT control unit have equal access to this buffer during all modes of operation, except in the high-resolution alphanumeric mode. In this mode, only the processor should access to this buffer during the horizontal-retrace intervals. While the processor may write to the required buffer at any time, a small amount of display interference will result if this does not occur during the horizontal-retrace intervals.

Character Generator

This attachment utilizes a ROM character generator. It consists of 8K bytes of storage that cannot be read from or written to under software control. This is a general-purpose ROM character generator with three different character fonts. Two character fonts are used on the color/graphics adapter: a 7-high by 7-wide double-dot font and a 5-wide by 7-high single-dot font. The font is selected by a jumper (P3). The single-dot font is selected by inserting the jumper; the double-dot font is selected by removing the jumper.

Timing Generator

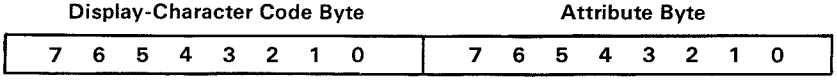
This generator produces the timing signals used by the 6845 CRT controller and by the dynamic memory. It also resolves the processor/graphic controller contentions for accessing the display buffer.

Composite Color Generator

This generator produces base band video color information.

Alphanumeric Mode

Every display-character position in the alphanumeric mode is defined by two bytes in the regen buffer (a part of the monitor adapter), not the system memory. Both the color/graphics and the monochrome display adapter use the following 2-byte character/attribute format.

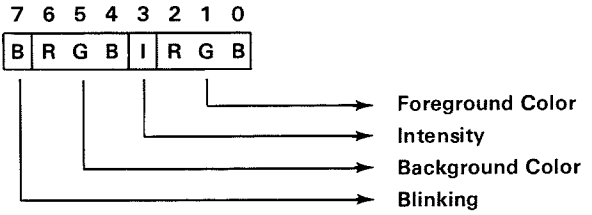


The functions of the attribute byte are defined by the following table:

Attribute Function	Attribute Byte							
	7	6	5	4	3	2	1	0
	B	R	G	B	I	R	G	B
	FG	Background			Foreground			
Normal	B	0	0	0	I	1	1	1
Reverse Video	B	1	1	1	I	0	0	0
Nondisplay (Black)	B	0	0	0	I	0	0	0
Nondisplay (White)	B	1	1	1	I	1	1	1

I = Highlighted Foreground (Character)
B = Blinking Foreground (Character)

The attribute byte definitions are:



In the alphanumeric mode, the display mode can be operated in either a low-resolution mode or a high-resolution mode.

The low-resolution alphanumeric mode has the following features:

- Supports home color televisions or low-resolution monitors
- Displays up to 25 rows of 40 characters each
- ROM character generator that contains dot patterns for a maximum of 256 different characters
- Requires 2,000 bytes of read/write memory (on the adapter)
- Character box is 8-high by 8-wide
- Two jumper-controlled character fonts are available:
  5-wide by 7-high single-dot character font with one descender
  7-wide by 7-high double-dot character font with one descender
- One character attribute for each character

The high-resolution alphanumeric mode has the following features:

- Supports the IBM Color Display or other color monitor with direct-drive input capability
- Supports a black-and-white composite-video monitor
- Displays up to 25 rows of 80 characters each

- ROM displays generator that contains dot patterns for a maximum of 256 different characters
- Requires 4,000 bytes of read/write memory (on the adapter)
- Character box is 8-high by 8-wide
- Two jumper-controlled character fonts are available:
  5-wide by 7-high single-dot character font with one descender
  7-wide by 7-high double-dot character font with one descender
- One character attribute for each character

Monochrome vs Color/Graphics Character Attributes

Foreground and background colors are defined by the attribute byte of each character, whether using the IBM Monochrome Display and Printer Adapter or the IBM Color/Graphics Monitor Adapter. The following table describes the colors for each adapter:

Attribute Byte								Monochrome Display Adapter		Color/Graphics Monitor Adapter	
7	6	5	4	3	2	1	0				
B	R	G	B	I	R	G	B	Background Color	Character Color	Background Color	Character Color
FG	Background			Foreground							
B	0	0	0	I	1	1	1	Black	White	Black	White
B	1	1	1	I	0	0	0	White	Black	White	Black
B	0	0	0	I	0	0	0	Black	Black	Black	Black
B	1	1	1	I	1	1	1	White	White	White	White

The monochrome display adapter will produce white characters on a white background with any other code. The color/graphics adapter will change foreground and background colors according to the color value selected. The color values for the various red, green, blue, and intensity bit settings are given in the following table.

R	G	B	I	Color
0	0	0	0	Black
0	0	1	0	Blue
0	1	0	0	Green
0	1	1	0	Cyan
1	0	0	0	Red
1	0	1	0	Magenta
1	1	0	0	Brown
1	1	1	0	White
0	0	0	1	Gray
0	0	1	1	Light Blue
0	1	0	1	Light Green
0	1	1	1	Light Cyan
1	0	0	1	Light Red
1	0	1	1	Light Magenta
1	1	0	1	Yellow
1	1	1	1	White (High Intensity)

Code written with an underline attribute for the IBM Monochrome Display, when executed on a color/graphics monitor adapter, will result in a blue character where the underline attribute is encountered. Also, code written on a color/graphics monitor adapter with blue characters will be displayed as white characters on a black background, with a white underline on the IBM Monochrome Display.

Remember that not all monitors recognize the intensity (I) bit.

Graphics Mode

The IBM Color/Graphics Monitor Adapter has three modes available within the graphics mode. They are low-resolution color graphics, medium-resolution color graphics, and high-resolution color graphics. However, only medium- and high-resolution graphics are supported in ROM. The following table summarizes the three modes.

Mode	Horizontal (PELs)	Vertical (Rows)	Number of Colors Available (Includes Background Color)
Low Resolution	160	100	16 (Includes black-and-white)
Medium Resolution	320	200	4 Colors Total 1 of 16 for Background and 1 of Green, Red, or Brown or 1 of Cyan, Magenta, or White
High Resolution	640	200	Black-and-white only

Low-Resolution Color-Graphics Mode

The low-resolution mode supports home television or color monitors. This mode is not supported in ROM. It has the following features:

- Contains a maximum of 100 rows of 160 PELs, with each PEL being 2-high by 2-wide
- Specifies 1 of 16 colors for each PEL by the I, R, G, and B bits
- Requires 16,000 bytes of read/write memory (on the adapter)
- Uses memory-mapped graphics

Medium-Resolution Color-Graphics Mode

The medium-resolution mode supports home televisions or color monitors. It has the following features:

- Contains a maximum of 200 rows of 320 PELs, with each PEL being 1-high by 1-wide
- Preselects one of four colors for each PEL
- Requires 16,000 bytes of read/write memory (on the adapter)
- Uses memory-mapped graphics

- Formats 4 PELs per byte in the following table:

7	6	5	4	3	2	1	0
C1	C0	C1	C0	C1	C0	C1	C0
First Display PEL		Second Display PEL		Third Display PEL		Fourth Display PEL	

- Organizes graphics storage in two banks of 8,000 bytes, using the following format:

Memory Address (in hex)	Function
B8000	Even Scans (0,2,4,...198) 8,000 bytes
B9F3F	Not Used
BA000	Odd Scans (1,3,5...199) 8,000 Bytes
BBF3F	Not Used
BBFFF	

Address hex B8000 contains PEL instruction for the upper-left corner of the display area.

- Color selection is determined by the following logic:

C1	C0	Function
0	0	Dot takes on the color of 1 of 16 preselected background colors
0	1	Selects first color of preselected Color Set 1 or Color Set 2
1	0	Selects second color of preselected Color Set 1 or Color Set 2
1	1	Selects third color of preselected Color Set 1 or Color Set 2

C1 and C0 will select 4 of 16 preselected colors. This color selection (palette) is preloaded in an I/O port.

Tow two colors sets are:

Color Set 1	Color Set 2
Color 1 is Green	Color 1 is Cyan
Color 2 is Red	Color 2 is Magenta
Color 3 is Brown	Color 3 is White

The background colors are the same basic 8 colors as defined for low-resolution graphics, plus 8 alternate intensities defined by the intensity bit, for a total of 16 colors, including black and white.

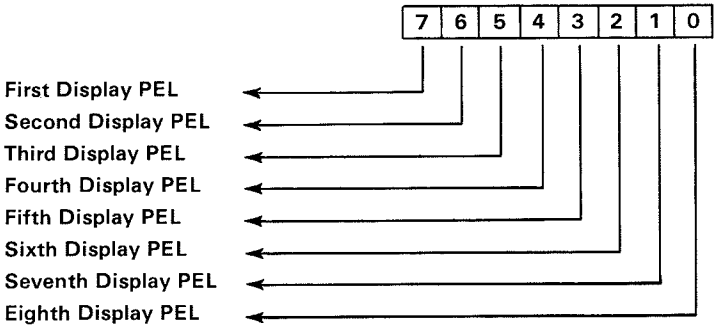
High-Resolution Black-and-White Graphics Mode

The high-resolution mode supports color monitors. This mode has the following features:

- Contains a maximum of 200 rows of 640 PELs, with each PEL being 1-high by 1-wide.
- Supports black-and-white mode only.
- Requires 16,000 bytes of read/write memory (on the adapter).

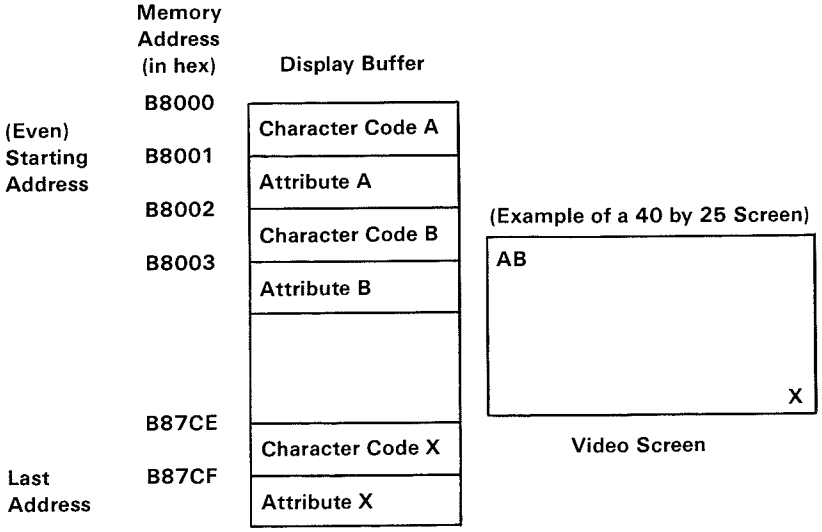
- Addressing and mapping procedures are the same as medium-resolution color graphics, but the data format is different. In this mode, each bit in memory is mapped to a PEL on the screen.

- Formats 8 PELs per byte in the following manner:



Description of Basic Operations

In the alphanumeric mode, the adapter fetches character and attribute information from its display buffer. The starting address of the display buffer is programmable through the 6845, but it must be an even address. The character codes and attributes are then displayed according to their relative positions in the buffer.



The processor and the display control unit have equal access to the display buffer during all the operating modes, except the high-resolution alphanumeric mode. During this mode, the processor should access the display buffer during the vertical retrace time. If it does not, the display will be affected with random patterns as the processor is using the display buffer. In the alphanumeric mode, the characters are displayed from a prestored ROM character generator that contains the dot patterns of all the displayable characters.

In the graphics mode, the displayed dots and colors (up to 16K bytes) are also fetched from the display buffer. The bit configuration for each graphics mode is explained in "Graphics Mode."

I	R	G	B	Color
0	0	0	0	Black
0	0	0	1	Blue
0	0	1	0	Green
0	0	1	1	Cyan
0	1	0	0	Red
0	1	0	1	Magenta
0	1	1	0	Brown
0	1	1	1	White
1	0	0	0	Gray
1	0	0	1	Light Blue
1	0	1	0	Light Green
1	0	1	1	Light Cyan
1	1	0	0	Light Red
1	1	0	1	Light Magenta
1	1	1	0	Yellow
1	1	1	1	High Intensity White

Note: "I" provides extra luminance (brightness) to each available shade. This results in the light colors listed above, except for monitors that do not recognize the "I" bit.

Summary of Available Colors

Programming Considerations

Programming the 6845 CRT Controller

The 6845 has 19 accessible internal registers, which are used to define and control a raster-scan CRT display. One of these registers, the Index register, is actually used as a pointer to the other 18 registers. It is a write-only register, which is loaded from the processor by executing an 'out' instruction to I/O address hex 3D4. The five least significant bits of the I/O bus are loaded into the Index register.

In order to load any of the other 18 registers, the Index register is first loaded with the necessary pointer; then the Data Register is loaded with the information to be placed in the selected register. The Data Register is loaded from the processor by executing an Out instruction to I/O address hex 3D5.

The following table defines the values that must be loaded into the 6845 CRT Controller registers to control the different modes of operation supported by the attachment:

Address Register	Register Number	Register Type	Units	I/O	40 by 25 Alpha-numeric	80 by 25 Alpha-numeric	Graphic Modes
0	R0	Horizontal Total	Character	Write Only	38	71	38
1	R1	Horizontal Displayed	Character	Write Only	28	50	28
2	R2	Horizontal Sync Position	Character	Write Only	2D	5A	2D
3	R3	Horizontal Sync Width	Character	Write Only	0A	0A	0A
4	R4	Vertical Total	Character Row	Write Only	1F	1F	7F
5	R5	Vertical Total Adjust	Scan Line	Write Only	06	06	06
6	R6	Vertical Displayed	Character Row	Write Only	19	19	64
7	R7	Vertical Sync Position	Character Row	Write Only	1C	1C	70
8	R8	Interlace Mode	-	Write Only	02	02	02
9	R9	Maximum Scan Line Address	Scan Line	Write Only	07	07	01
A	R10	Cursor Start	Scan Line	Write Only	06	06	06
B	R11	Cursor End	Scan Line	Write Only	07	07	07
C	R12	Start Address (H)	-	Write Only	00	00	00
D	R13	Start Address (L)	-	Write Only	00	00	00
E	R14	Cursor Address (H)	-	Read/ Write	XX	XX	XX
F	R15	Cursor Address (L)	-	Read/ Write	XX	XX	XX
10	R16	Light Pen (H)	-	Read Only	XX	XX	XX
11	R17	Light Pen (L)	-	Read Only	XX	XX	XX

Note: All register values are given in hexadecimal

6845 Register Description

Programming the Mode Control and Status Register

The following I/O devices are defined on the color/graphics adapter.

Hex Address	A9	A8	A7	A6	A5	A4	A3	A2	A1	A0	Function of Register
3D8	1	1	1	1	0	1	1	0	0	0	Mode Control Register (D0)
3D9	1	1	1	1	0	1	1	0	0	1	Color Select Register (D0)
3DA	1	1	1	1	0	1	1	0	1	0	Status Register (D1)
3DB	1	1	1	1	0	1	1	0	1	1	Clear Light Pen Latch
3DC	1	1	1	1	0	1	1	1	0	0	Preset Light Pen Latch
3D4	1	1	1	1	0	1	0	Z	Z	0	6845 Index Register
3D5	1	1	1	1	0	1	0	Z	Z	1	6845 Data Register
3D0	1	1	1	1	0	1	0	Z	Z	0	6845 Registers
3D1	1	1	1	1	0	1	0	Z	Z	1	6845 Registers

Z = don't care condition

Color-Select Register

This is a 6-bit output-only register (cannot be read). Its I/O address is hex 3D9, and it can be written to by using the 8088 I/O Out command.

Bit 0	Selects B (Blue) Border Color in 40 x 25 Alphanumeric Mode Selects B (Blue) Background Color in 320 x 200 Graphics Mode Selects B (Blue) Foreground Color in 640 x 200 Graphics Mode
Bit 1	Selects G (Green) Border Color in 40 x 25 Alphanumeric Mode Selects G (Green) Background Color in 320 x 200 Graphics Mode Selects G (Green) Foreground Color in 640 x 200 Graphics Mode
Bit 2	Selects R (Red) Border Color in 40 x 25 Alphanumeric Mode Selects R (Red) Background Color in 320 x 200 Graphics Mode Selects R (Red) Foreground Color in 640 x 200 Graphics Mode
Bit 3	Selects I (Intensified) Border Color in 40 x 25 Alphanumeric Mode Selects I (Intensified) Background Color in 320 x 200 Graphics Mode Selects I (Intensified) Foreground Color in 640 x 200 Graphics Mode
Bit 4	Selects Alternate, Intensified Set of Colors in Graphics Mode Selects Background Colors in the Alphanumeric Mode
Bit 5	Selects Active Color Set in 320 x 200 Graphics Mode
Bit 6	Not Used
Bit 7	Not Used

Bits 0, 1, 2, 3 These bits select the screen's border color in the 40 by 25 alphanumeric mode. They select the screen's background color (C0-C1) in the medium-resolution (320 by 200) color-graphics mode.

Bits 4 This bit, when set, will select an alternate, intensified set of colors. Selects background colors in the alphanumeric mode.

Bit 5 This bit is only used in the medium-resolution (320 by 200) color-graphics mode. It is used to select the active set of screen colors for the display.

When bit 5 is set to 1, colors are determined as follows:

C1	C0	Set Selected
0	0	Background (Defined by bits 0-3 of port hex 3D9)
0	1	Cyan
1	0	Magenta
1	1	White

When bit 5 is set to 0, colors are determined as follows:

C1	C0	Set Selected
0	0	Background (Defined by bits 0-3 of port hex 3D9)
0	1	Green
1	0	Red
1	1	Brown

Mode-Select Register

This is a 6-bit output-only register (cannot be read). Its I/O address is hex 3D8, and it can be written to using the 8088 I/O Out command.

The following is a description of the register's functions:

Bit 0	80 x 25 Alphanumeric Mode
Bit 1	Graphics Select
Bit 2	Black/White Select
Bit 3	Enable Video Signal
Bit 4	High-Resolution (640 x 200) Black/White Mode
Bit 5	Change Background Intensity to Blink Bit
Bit 6	Not Used
Bit 7	Not Used

Bit 0 A 1 selects 80 by 25 alphanumeric mode
A 0 selects 40 by 25 alphanumeric mode

Bit 1 A 1 selects 320 by 200 graphics mode
A 0 selects alphanumeric mode

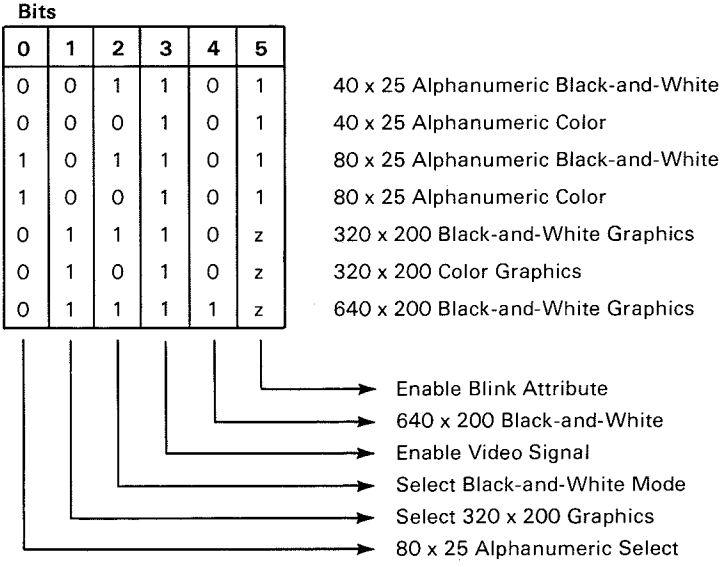
Bit 2 A 1 selects black-and-white mode
A 0 selects color mode

Bit 3 A 1 enables the video signal at certain times when modes are being changed. The video signal should be disabled when changing modes.

Bit 4 A 1 selects the high-resolution (640 by 200) black-and-white graphics mode. One color of 8 can be selected on direct-drive sets in this mode by using register hex 3D9.

Bit 5 When on, this bit will change the character background intensity to the blinking attribute function for alphanumeric modes. When the high-order attribute bit is not selected, 16 background colors (or intensified colors) are available. For normal operation, this bit should be set to 1 to allow the blinking function.

Mode Register Summary



z = don't care condition

Note: The low-resolution (160 by 100) mode requires special programming and is set up as the 40 by 25 alphanumeric mode.

Status Register

The status register is a 4-bit read-only register. Its I/O address is hex 3DA, and it can be read using the 8088 I/O In instruction. The following is a description of the register functions:

Bit 0	Display Enable
Bit 1	Light-Pen Trigger Set
Bit 2	Light-Pen Switch Made
Bit 3	Vertical Sync
Bit 4	Not Used
Bit 5	Not Used
Bit 6	Not Used
Bit 7	Not Used

Bit 0 This bit, when active, indicates that a regen buffer memory access can be made without interfering with the display.

Bit 1 This bit, when active, indicates that a positive-going edge from the light-pen has set the light pen's trigger. This trigger is reset upon power-on and may also be cleared by performing an I/O Out command to hex address 3DB. No specific data setting is required; the action is address-activated.

Bit 2 The light-pen switch status is reflected in this status bit. The switch is not latched or debounced. A 0 indicates that the switch is on.

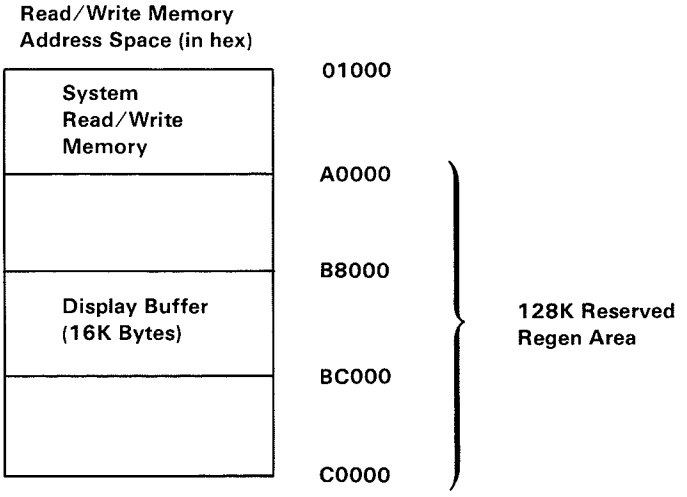
Bit 3 This bit, when active, indicates that the raster is in a vertical retrace mode. This is a good time to perform screen-buffer updating.

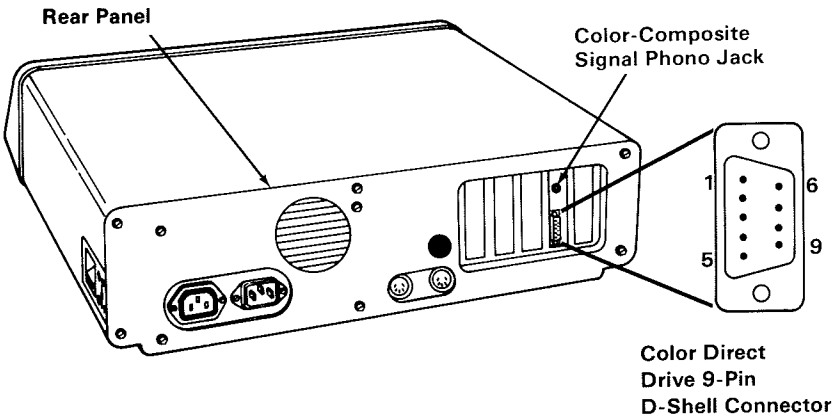
Sequence of Events for Changing Modes

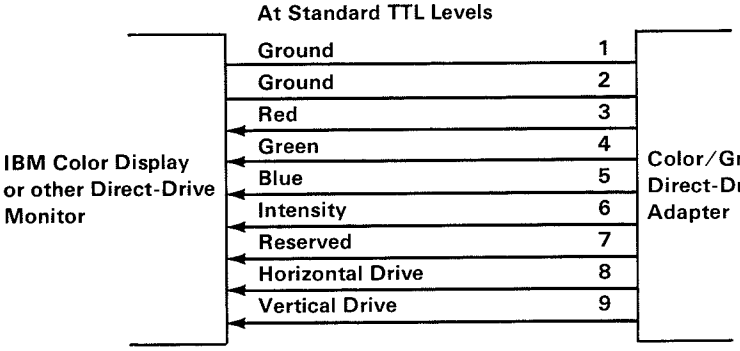
1. Determine the mode of operation.
2. Reset 'video enable' bit in mode-select register.
3. Program 6845 to select mode.
4. Program mode/color select registers including re-enabling video.

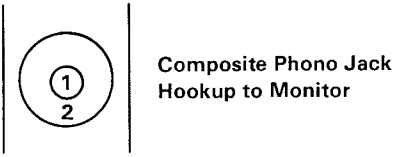
Memory Requirements

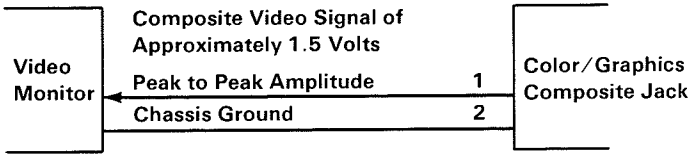
The memory used by this adapter is self-contained. It consists of 16K bytes of memory without parity. This memory is used as both a display buffer for alphanumeric data and as a bit map for graphics data. The regen buffer's address starts at hex B8000.



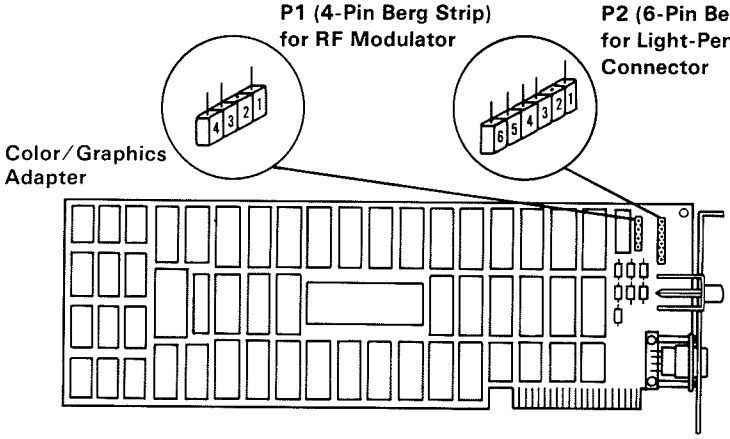


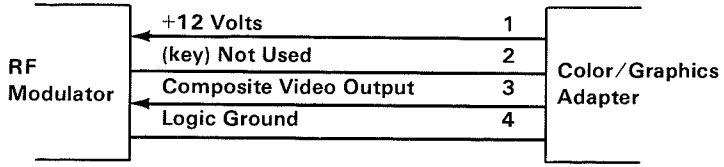




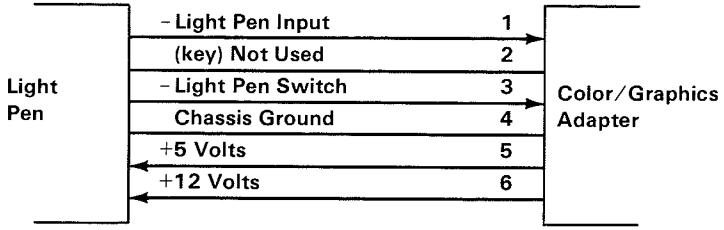


Connector Specifications (Part 1 of 2)





RF Modulator Interface



Light Pen Interface

Connector Specifications (Part 2 of 2)

IBM Color Display

The IBM Color Display attaches to the system unit by a signal cable that is approximately 5 feet (1.5 meters) in length. This signal cable provides a direct-drive interface from the IBM Color/Graphics Monitor Adapter.

A second cable provides ac power to the display from a standard wall outlet. The display has its own power control and indicator. The display will accept either 120-volt 60-Hz, or 220-volt 50-Hz power. The power supply in the display automatically switches to match the applied power.

The display has a 13-inch (340 millimeters) CRT. The CRT and analog circuits are packaged in an enclosure so the display may sit either on top of the system unit or on a nearby tabletop or desk. Front panel controls and indicators include: Power-On control, Power-On indicator, Brightness and Contrast controls. Two additional rear-panel controls are the Vertical Hold and Vertical Size controls.

Operating Characteristics

Screen

- High contrast (black) screen.
- Displays up to 16 colors, when used with the IBM Color/Graphics Monitor Adapter.
- Characters defined in an 8-high by 8-wide matrix.

Video Signal

- Maximum video bandwidth of 14 MHz.
- Red, green, and blue video signals and intensity are all independent.

Vertical Drive

- Screen refreshed at 60 Hz with 200 vertical lines of resolution.

Horizontal Drive

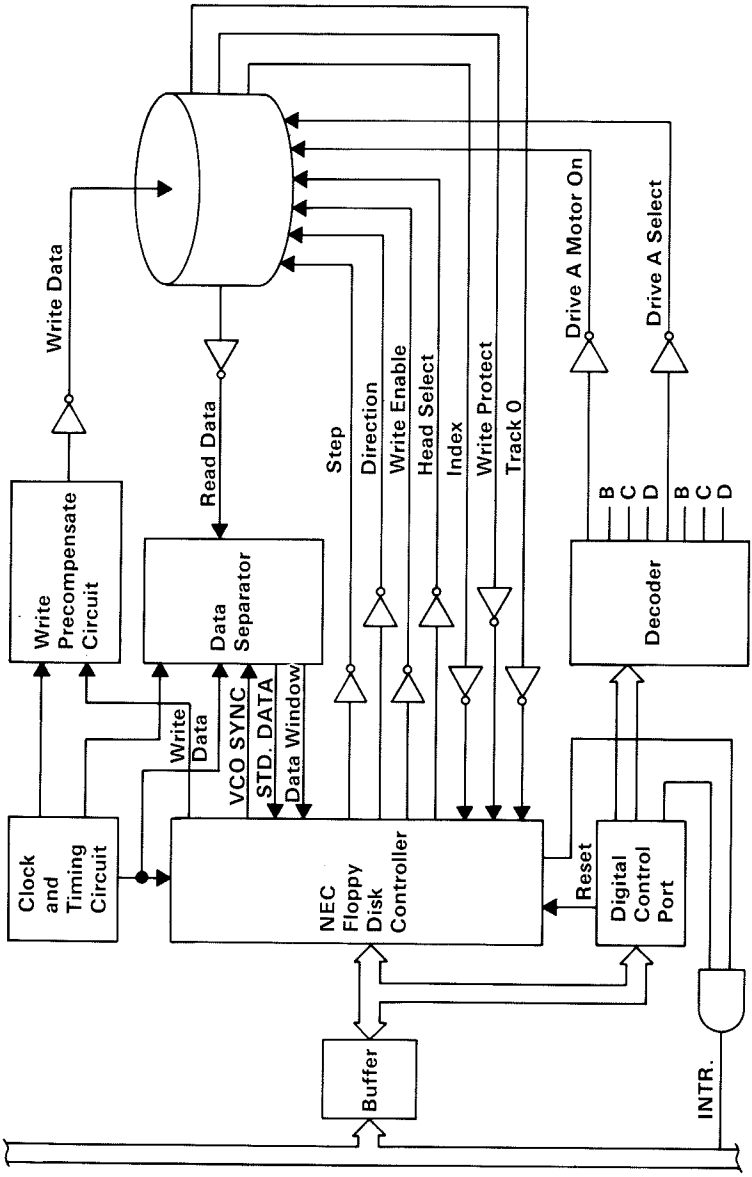
- Positive-level, TTL-compatibility, at a frequency of 15.75 kHz.

IBM 5-1/4" Diskette Drive Adapter

The 5-1/4 inch diskette drive adapter fits into one of the expansion slots in the system unit. It attaches to one or two diskette drives through an internal, daisy-chained flat cable that connects to one end of the drive adapter. The adapter has a connector at the other end that extends through the rear panel of the system unit. This connector has signals for two additional external diskette drives; thus the 5-1/4 inch diskette drive adapter can attach four 5-1/4 inch drives – two internal and two external.

The adapter is designed for double-density, MFM-coded, diskette drives and uses write precompensation with an analog phase-lock loop for clock and data recovery. The adapter is a general-purpose device using the NEC μPD765 compatible controller. Therefore, the diskette drive parameters are programmable. In addition, the attachment supports the diskette drive's write-protect feature. The adapter is buffered on the I/O bus and uses the system board's direct memory access (DMA) for record data transfers. An interrupt level is also used to indicate when an operation is complete and that a status condition requires processor attention.

In general, the 5-1/4 inch diskette drive adapter presents a high-level command interface to software I/O drivers. A block diagram of the 5-1/4 inch diskette drive adapter is on the following page.



5-1/4 Inch Diskette Drive Adapter Block Diagram

Functional Description

From a programming point of view, this attachment consists of an 8-bit digital-output register in parallel with an NEC μPD765 or equivalent floppy disk controller (FDC).

In the following description, drive numbers 0, 1, 2, and 3 are equivalent to drives A, B, C, and D.

Digital-Output Register

The digital-output register (DOR) is an output-only register used to control drive motors, drive selection, and feature enable. All bits are cleared by the I/O interface reset line. The bits have the following functions:

Bits 0 and 1 — These bits are decoded by the hardware to select one drive if its motor is on:

Bit 1	Bit 0	Drive
0	0	0 (A)
0	1	1 (B)
1	0	2 (C)
1	1	3 (D)

Bit 2 — The FDC is held reset when this bit is clear. It must be set by the program to enable the FDC.

Bit 3 — This bit allows the FDC interrupt and DMA requests to be gated onto the I/O interface. If this bit is cleared, the interrupt and DMA request I/O interface drivers are disabled.

Bits 4, 5, 6, and 7 — These bits control, respectively, the motors of drives 0, 1, 2 (A, B, C), and 3 (D). If a bit is clear, the associated motor is off, and the drive cannot be selected.

Floppy Disk Controller

The floppy disk controller (FDC) contains two registers that may be accessed by the main system processor: a status register and a data register. The 8-bit main status register contains the status information of the FDC and may be accessed at any time. The 8-bit data register (actually consisting of several registers in a stack with only one register presented to the data bus at a time) stores data, commands, parameters, and provides floppy disk drive (FDD) status information. Data bytes are read from or written to the data register in order to program or obtain results after a particular command. The main status register may only be read and is used to facilitate the transfer of data between the processor and FDC.

The bits in the main status register (hex 34F) are defined as follows:

Bit Number	Name	Symbol	Description
DB0	FDD A Busy	DAB	FDD number 0 is in the Seek mode.
DB1	FDD B Busy	DBB	FDD number 1 is in the Seek mode.
DB2	FDD C Busy	DCB	FDD number 2 is in the Seek mode.
DB3	FDD D Busy	DDB	FDD number 3 is in the Seek mode.
DB4	FDC Busy	CB	A read or write command is in process.
DB5	Non-DMA Mode	NDM	The FDC is in the non-DMA mode.
DB6	Data Input/ Output	DIO	Indicates direction of data transfer between FDC and processor. If DIO = "1," then transfer is from FDC data register to the processor. If DIO = "0," then transfer is from the processor to FDC data register.
DB7	Request for Master	RQM	Indicates data register is ready to send or receive data to or from the processor. Both bits DIO and RQM should be used to perform the handshaking functions of "ready" and "direction" to the processor.

The FDC is capable of performing 15 different commands. Each command is initiated by a multi-byte transfer from the processor, and the result after execution of the command may also be a multi-byte transfer back to the processor. Because of this multi-byte interchange of information between the FDC and the processor, it is convenient to consider each command as consisting of three phases:

Command Phase

The FDC receives all information required to perform a particular operation from the processor.

Execution Phase

The FDC performs the operation it was instructed to do.

Result Phase

After completion of the operation, status and other housekeeping information is made available to the processor.

Programming Considerations

The following tables define the symbols used in the command summary, which follows.

Symbol	Name	Description
A0	Address Line 0	A0 controls selection of main status register (A0 = 0) or data register (A0 = 1).
C	Cylinder Number	C stands for the current/selected cylinder (track) number of the medium.
D	Data	D stands for the data pattern that is going to be written into a sector.
D7-D0	Data Bus	8-bit data bus, where D7 stands for a most significant bit, and D0 stands for a least significant bit.
DTL	Data Length	When N is defined as 00, DTL stands for the data length that users are going to read from or write to the sector.
EOT	End of Track	EOT stands for the final sector number on a cylinder.
GPL	Gap Length	GPL stands for the length of gap 3 (spacing between sectors excluding VCO sync field).
H	Head Address	H stands for head number 0 or 1, as specified in ID field.
HD	Head	HD stands for a selected head number 0 or 1. (H = HD in all command words.)
HLT	Head Load Time	HLT stands for the head load time in the FDD (4 to 512 ms in 4-ms increments).
HUT	Head Unload Time	HUT stands for the head unload time after a read or write operation has occurred (0 to 480 ms in 32-ms increments).
MF	FM or MFM Mode	If MF is low, FM mode is selected; if it is high, MFM mode is selected only if MFM is implemented.
MT	Multi-Track	If MT is high, a multi-track operation is to be performed. (A cylinder under both HD0 and HD1 will be read or written.)
N	Number	N stands for the number of data bytes written in a sector.

Symbol Descriptions (Part 1 of 2)

Symbol	Name	Description
NCN	New Cylinder Number	NCN stands for a new cylinder number, which is going to be reached as a result of the seek operation. (Desired position of the head.)
ND	Non-DMA Mode	ND stands for operation in the non-DMA mode.
PCN	Present Cylinder Number	PCN stands for cylinder number at the completion of sense-interrupt-status command indicating the position of the head at present time.
R	Record	R stands for the sector number, which will be read or written.
R/W	Read/Write	R/W stands for either read (R) or write (W) signal.
SC	Sector	SC indicates the number of sectors per cylinder.
SK	Skip	SK stands for skip deleted-data address mark.
SRT	Step Rate Time	SRT stands for the stepping rate for the FDD (2 to 32 ms in 2-ms increments).
ST 0 ST 1 ST 2 ST 3	Status 0 Status 1 Status 2 Status 3	ST 0-3 stand for one of four registers that store the status information after a command has been executed. This information is available during the result phase after command execution. These registers should not be confused with the main status register (selected by A0 =0). ST 0-3 may be read only after a command has been executed and contain information relevant to that particular command.
STP	Scan Test	During a scan operation, if STP =1, the data in contiguous sectors is compared byte-by-byte with data sent from the processor (or DMA), and if STP =2, then alternate sectors are read and compared.
US0, US1	Unit Select	US stands for a selected drive number encoded the same as bits 0 and 1 of the digital output register (DOR).

Symbol Descriptions (Part 2 of 2)

Command Summary

In the following table, 0 indicates "logical 0" for that bit, 1 means "logical 1," and X means "don't care."

Phase	R/W	Data Bus D7	D6	D5	D4	D3	D2	D1	D0	Remarks
		Read Data								
Command	W	MT	MF	SK	0	0	1	1	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					Sector ID information
	W				H					prior to command
	W				R					execution.
	W				N					
	W				EOT					
	W				GPL					
	W				DTL					
Execution										Data transfer between the FDD and main system.
Result	R				ST 0					Status information
	R				ST 1					after command
	R				ST 2					execution.
	R				C					Sector ID information
	R				H					after command
	R				R					execution.
	R				N					
		Read Deleted Data								
Command	W	MT	MF	SK	0	1	1	0	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					Sector ID information
	W				H					prior to command
	W				R					execution.
	W				N					
	W				EOT					
	W				GPL					
	W				DTL					
Execution										Data transfer between the FDD and main system.
Result	R				ST 0					Status information
	R				ST 1					after command
	R				ST 2					execution.
	R				C					Sector ID information
	R				H					after command
	R				R					execution.
	R				N					

Phase	R/W	Data Bus D7	D6	D5	D4	D3	D2	D1	D0	Remarks
		Write Data								
Command	W	MT	MF	0	0	0	1	0	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W	C								Sector ID information
	W	H								to command
	W	R								execution.
	W	N								
	W	EOT								
	W	GPL								
	W	DTL								
Execution										Data transfer between the main system and FDD.
Result	R	ST 0								Status information
	R	ST 1								after command
	R	ST 2								execution.
	R	C								Sector ID information
	R	H								after command
	R	R								execution.
	R	N								
		Write Deleted Data								
Command	W	MT	MF	0	0	1	0	0	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W	C								Sector ID information
	W	H								prior to command
	W	R								execution.
	W	N								
	W	EOT								
	W	GPL								
	W	DTL								
Execution										Data transfer between FDD and main system.
Result	R	ST 0								Status ID information
	R	ST 1								after command
	R	ST 2								execution.
	R	C								Sector ID information
	R	H								after command
	R	R								execution.
	R	N								

Phase	R/W	Data Bus D7	D6	D5	D4	D3	D2	D1	D0	Remarks
		Read a Track								
Command	W	0	MF	SK	0	0	0	1	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W	C								Sector ID information
	W	H								prior to command
	W	R								execution.
	W	N								
	W	EOT								
	W	GPL								
	W	DTL								
Execution										Data transfer between the FDD and main system. FDC reads all of cylinder's contents from index hole to EOT.
Result	R	ST 0								Status information
	R	ST 1								after command
	R	ST 2								execution.
	R	C								Sector ID information
	R	H								after command
	R	R								execution.
	R	N								
		Read ID								
Command	W	0	MF	0	0	1	0	1	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
Execution										The first correct ID information on the cylinder is stored in data register.
Result	R	ST 0								Status information
	R	ST 1								after command
	R	ST 2								execution.
	R	C								Sector ID information
	R	H								during execution
	R	R								phase.
	R	N								

Phase	R/W	Data Bus D7	D6	D5	D4	D3	D2	D1	D0	Remarks
		Format a Track								
Command	W	0	MF	0	0	1	1	0	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				N					Bytes/Sector
	W				SC					Sector/Track
	W				GPL					Gap 3
	W				D					filler byte.
Execution										FDC formats an entire cylinder.
Result	R				ST 0					Status information
	R				ST 1					after command
	R				ST 2					execution.
	R				C					In this case, the ID
	R				H					information has no
	R				R					meaning.
	R				N					
		Scan Equal								
Command	W	MT	MF	SK	1	0	0	0	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					Sector ID information
	W				H					prior to command
	W				R					execution.
	W				N					
	W				EOT					
	W				GPL					
	W				STP					
Execution										Data compared between the FDD and the main system.
Result	R				ST 0					Status information
	R				ST 1					after command
	R				ST 2					execution.
	R				C					Sector ID information
	R				H					after Command
	R				R					execution.
	R				N					

Phase	R/W	Data Bus D7	D6	D5	D4	D3	D2	D1	D0	Remarks
		Scan Low or Equal								
Command	W	MT	MF	SK	1	1	0	0	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W	C								Sector ID information
	W	H								prior to command
	W	R								execution.
	W	N								
	W	EOT								
	W	GPL								
	W	STP								
Execution										Data compared between the FDD and main system.
Result	R	ST 0								Status information
	R	ST 1								after command
	R	ST 2								execution.
	R	C								Sector ID information
	R	H								after command
	R	R								execution.
	R	N								
		Scan High or Equal								
Command	W	MT	MF	SK	1	1	1	0	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W	C								Sector ID information
	W	H								prior to command
	W	R								execution.
	W	N								
	W	EOT								
	W	GPL								
	W	STP								
Execution										Data compared between the FDD and main system.
Result	R	ST 0								Status information
	R	ST 1								after command
	R	ST 2								execution.
	R	C								Sector ID information
	R	H								after command
	R	R								execution.
	R	N								

Phase	R/W	Data Bus D7	D6	D5	D4	D3	D2	D1	D0	Remarks
		Recalibrate								
Command	W	0	0	0	0	0	1	1	1	Command Codes
	W	X	X	X	X	X	0	US1	US0	
Execution No Result Phase										Head retracted to track 0
		Sense Interrupt Status								
Command	W	0	0	0	0	1	0	0	0	Command Codes
Result	R				ST 0					Status information at the end of seek operation about the FDC
	R				PCN					
		Specify								
Command	W	0	0	0	0	0	0	1	1	Command Codes
	W	—SRT————						HUT——		
	W	———	HLT————						ND	
No Result Phase										
		Sense Drive Status								
Command	W	0	0	0	0	0	1	0	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
Result	R				ST 3					Status information about FDD.
		Seek								
Command	W	0	0	0	0	1	1	1	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				NCN					
Execution										Head is positioned over proper cylinder on diskette.
No Result Phase										
		Invalid								
Command	W	Invalid Codes								Invalid command codes (NoOp - FDC goes into standy state).
Result	R				ST 0					ST 0 = 80.

Bit No.	Bit Name	Bit Symbol	Description
D7 D6	Interrupt Code	IC	D7 = 0 and D6 = 0 Normal termination of command (NT). Command was completed and properly executed. D7 = 0 and D6 = 1 Abnormal termination of command (AT). Execution of command was started, but was not successfully completed. D7 = 1 and D6 = 0 Invalid command issue (IC). Command that was issued was never started. D7 = 1 and D6 = 1 Abnormal termination because, during command execution, the ready signal from FDD changed state.
D5	Seek End	SE	When the FDC completes the seek command, this flag is set to 1 (high).
D4	Equipment Check	EC	If a fault signal is received from the FDD, or if the track 0 signal fails to occur after 77 step pulses (recalibrate command), then this flag is set.
D3	Not Ready	NR	When the FDD is in the not-ready state and a read or write command is issued, this flag is set. If a read or write command is issued to side 1 of a single-sided drive, then this flag is set.
D2	Head Address	HD	This flag is used to indicate the state of the head at interrupt.
D1 D0	Unit Select 1 Unit Select 0	US 1 US 0	These flags are used to indicate a drive unit number at interrupt.

Command Status Register 0

Bit			Description
No.	Name	Symbol	
D7	End of Cylinder	EN	When the FDC tries to access a sector beyond the final sector of a cylinder, this flag is set.
D6	—	—	Not used. This bit is always 0 (low).
D5	Data Error	DE	When the FDC detects a CRC error in either the ID field or the data field, this flag is set.
D4	Over Run	OR	If the FDC is not serviced by the main system during data transfers within a certain time interval, this flag is set.
D3	—	—	Not used. This bit is always 0 (low).
D2	No Data	ND	During execution of a read data, write deleted data, or scan command, if the FDC cannot find the sector specified in the ID register, this flag is set. During execution of the read ID command, if the FDC cannot read the ID field without an error, then this flag is set. During the execution of the read a cylinder command, if the starting sector cannot be found, then this flag is set.
D1	Not Writable	NW	During execution of a write data, write deleted data, or format-a-cylinder command, if the FDC detects a write-protect signal from the FDD, then this flag is set.
D0	Missing Address Mark	MA	If the FDC cannot detect the ID address mark, this flag is set. Also, at the same time, the MD (missing address mark in the data field) of status register 2 is set.

Command Status Register 1

Bit			Description
No.	Name	Symbol	
D7	—	—	Not used. This bit is always 0 (low).
D6	Control Mark	CM	During execution of the read data or scan command, if the FDC encounters a sector that contains a deleted data address mark, this flag is set.
D5	Data Error in Data Field	DD	If the FDC detects a CRC error in the data, then this flag is set.
D4	Wrong Cylinder	WC	This bit is related to the ND bit, and when the contents of C on the medium are different from that stored in the ID register, this flag is set.
D3	Scan Equal Hit	SH	During execution of the scan command, if the condition of "equal" is satisfied, this flag is set.
D2	Scan Not Satisfied	SN	During execution of the scan command, if the FDC cannot find a sector on the cylinder that meets the condition, then this flag is set.
D1	Bad Cylinder	BC	This bit is related to the ND bit, and when the contents of C on the medium are different from that stored in the ID register, and the contents of C is FF, then this flag is set.
D0	Missing Address Mark in Data Field	MD	When data is read from the medium, if the FDC cannot find a data address mark or deleted data address mark, then this flag is set.

Command Status Register 2

Bit No.	Bit Name	Bit Symbol	Description
D7	Fault	FT	This bit is the status of the fault signal from the FDD.
D6	Write Protected	WP	This bit is the status of the write-protected signal from the FDD.
D5	Ready	RY	This bit is the status of the ready signal from the FDD.
D4	Track 0	T0	This bit is the status of the track 0 signal from the FDD.
D3	Two Side	TS	This bit is the status of the two-side signal from the FDD.
D2	Head Address	HD	This bit is the status of the side-select signal from the FDD.
D1	Unit Select 1	US 1	This bit is the status of the unit-select-1 signal from the FDD.
D0	Unit Select 0	US 0	This bit is the status of the unit-select-0 signal from the FDD.

Command Status Register 3

Programming Summary

FDC Data Register — I/O Address Hex 3F5

FDC Main Status Register — I/O Address Hex 3F4

Digital Output Register — I/O Address Hex 3F2

Bit 0	Drive Select	00: DR #A 10: DR #C 01: DR #B 11: DR #D
1		
2	Not FDC Reset	
3	Enable INT & DMA Requests	
4	Drive A Motor Enable	
5	Drive B Motor Enable	
6	Drive C Motor Enable	
7	Drive D Motor Enable	

All bits cleared with channel reset.

DPC Registers

FDC Constants (in hex)

N:	02	GPL Format:	05
SC:	08	GPL R/W:	2A
HUT:	F	HLT:	01
SRT:	C	(6 ms track-to-track)	

Drive Constants

Head Load	35 ms
Head Settle	15 ms
Motor Start	250 ms

Comments

- Head loads with drive select, wait HD load before R/W.
- Following access, wait HD settle time before R/W.
- Drive motors should be off when not in use. Only A or B and C or D may run simultaneously. Wait motor start time before R/W.
- Motor must be on for drive to be selected.
- Data errors can occur while using a home television as the system display. Locating the TV too close to the diskette area can cause this to occur. To correct the problem, move the TV away from, or to the opposite side of the system unit.

System I/O Channel Interface

All signals are TTL-compatible:

Most Positive Up Level	5.5 Vdc
Least Positive Up Level	2.7 Vdc
Most Positive Down Level	0.5 Vdc
Least Positive Down Level	−0.5 Vdc

The following lines are used by this adapter.

+D0-7 (Bidirectional, load: 1 74LS, driver: 74LS 3-state). These eight lines form a bus by which all commands, status, and data are transferred. Bit 0 is the low-order bit.

+A0-9 (Adapter input, load: 1 74LS)
These ten lines form an address bus by which a register is selected to receive or supply the byte transferred through lines D0-7. Bit 0 is the low-order bit.

+AEN (Adapter input, load: 1 74LS)
The content of lines A0-9 is ignored if this line is active.

−IOW (Adapter input, load: 1 74LS)
The content of lines D0-7 is stored in the register addressed by lines A0-9 or DACK2 at the trailing edge of this signal.

−IOR (Adapter input, load: 1 74LS)
The content of the register addressed by lines A0-9 or DACK2 is gated onto lines D0-7 when this line is active.

−DACK2 (Adapter input, load: 2 74LS)
This line being active degates output DRQ2, selects the FDC data register as the source/destination of bus D0-7, and indirectly gates T/C to IRQ6.

+T/C (Adapter input, load: 4 74LS)
This line and DACK2 being active indicates that the byte of data for which the DMA count was initialized is now being transferred.

+RESET (Adapter input, load: 1 74LS)
An up level aborts any operation in process and clears the digital output register (DOR).

+DRQ2 (Adapter output, driver: 74LS 3-state)
This line is made active when the attachment is ready to transfer a byte of data to or from main storage. The line is made inactive by DACK2 becoming active or an I/O read of the FDC data register.

+IRQ6 (Adapter output, driver: 74LS 3-state)
This line is made active when the FDC has completed an operation. It results in an interrupt to a routine which should examine the FDC result bytes to reset the line and determine the ending condition.

Drive A and B Interface

All signals are TTL-compatible:

Most Positive Up Level	5.5 Vdc
Least Positive Up Level	2.4 Vdc
Most Positive Down Level	0.4 Vdc
Least Positive Down Level	−0.5 Vdc

All adapter outputs are driven by open-collector gates. The drive(s) must provide termination networks to Vcc (except motor enable, which has a 2000-ohm resistor to Vcc).

Each adapter input is terminated with a 150-ohm resistor to Vcc.

Adapter Outputs

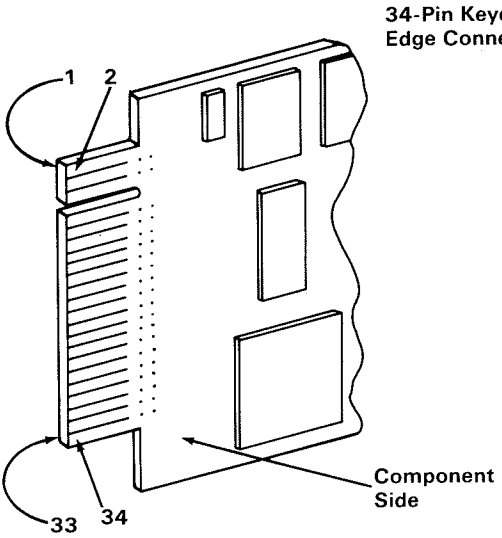
−Drive Select A and B (Driver: 7438)
These two lines are used by drives A and B to degate all drivers to the adapter and receivers from the attachment (except motor enable) when the line associated with a drive is inactive.

−Motor Enable A and B	(Driver: 7438) The drive associated with each of these lines must control its spindle motor such that it starts when the line becomes active and stops when the line becomes inactive.
−Step	(Driver: 7438) The selected drive moves the read/write head one cylinder in or out per the direction line for each pulse present on this line.
−Direction	(Driver: 7438) For each recognized pulse of the step line, the read/write head moves one cylinder toward the spindle if this line is active, and away from the spindle if inactive.
−Head Select	(Driver: 7438) Head 1 (upper head) will be selected when this line is active (low).
−Write Data	(Driver: 7438) For each inactive to active transition of this line while write enable is active, the selected drive causes a flux change to be stored on the diskette.
−Write Enable	(Driver: 7438) The drive disables write current in the head unless this line is active.

Adapter Inputs

−Index	The selected drive supplies one pulse per diskette revolution on this line.
−Write Protect	The selected drive makes this line active if a write-protected diskette is mounted in the drive.

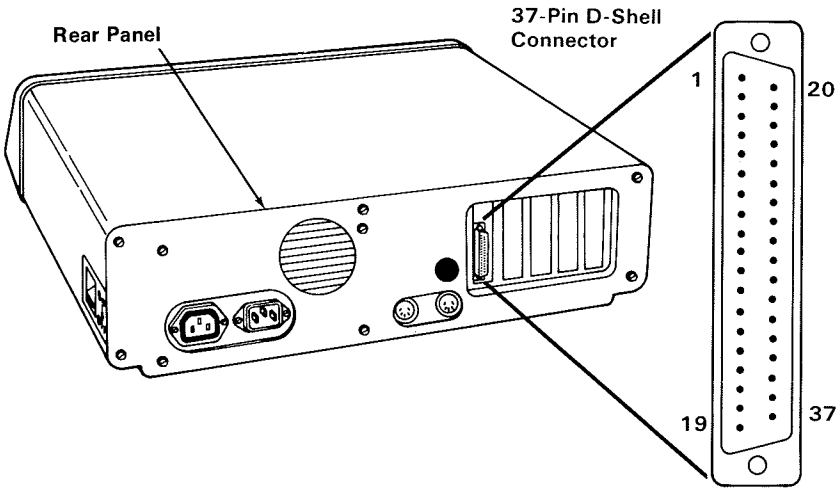
−Track 0	The selected drive makes this line active if the read/write head is over track 0.
−Read Data	The selected drive supplies a pulse on this line for each flux change encountered on the diskette.



Note: Lands 1-33 (odd numbers) are on the back of the board. Lands 2-34 (even numbers) are on the front, or component side.

	At Standard TTL Levels	Land Number	
	Ground-Odd Numbers	1-33	
	Unused	2,4,6	
	Index	8	→
	Motor Enable A	10	←
	Drive Select B	12	←
	Drive Select A	14	←
	Motor Enable B	16	←
	Direction (Stepper Motor)	18	←
Diskette Drives	Step Pulse	20	← Drive Adapter
	Write Data	22	←
	Write Enable	24	←
	Track 0	26	→
	Write Protect	28	→
	Read Data	30	→
	Select Head 1	32	←
	Unused	34	

Connector Specifications (Part 1 of 2)



	At Standard TTL Levels	Pin Number	
External Drives	Unused	1-5	Drive Adapter
	Index	6	
	Motor Enable C	7	
	Drive Select D	8	
	Drive Select C	9	
	Motor Enable D	10	
	Direction (Stepper Motor)	11	
	Step Pulse	12	
	Write Data	13	
	Write Enable	14	
	Track 0	15	
	Write Protect	16	
	Read Data	17	
	Select Head 1	18	
	Ground	20-37	

Connector Specifications (Part 2 of 2)

IBM 5-1/4" Diskette Drive

The system unit has space and power for one or two 5-1/4 inch diskette drives. A drive can be single-sided or double-sided with 40 tracks for each side, is fully self-contained, and consists of a spindle drive system, a read positioning system, and a read/write/erase system.

The diskette drive uses modified frequency modulation (MFM) to read and write digital data, with a track-to-track access time of 6 milliseconds.

To load a diskette, the operator raises the latch at the front of the diskette drive and inserts the diskette into the slot. Plastic guides in the slot ensure the diskette is in the correct position. Closing the latch centers the diskette and clamps it to the drive hub. After 250 milliseconds, the servo-controlled dc drive motor starts and drives the hub at a constant speed of 300 rpm. The head positioning system, which consists of a 4-phase stepper-motor and band assembly with its associated electronics, moves the magnetic head so it comes in contact with the desired track of the diskette. The stepper-motor and band assembly uses one-step rotation to cause a one-track linear movement of the magnetic head. No operator intervention is required during normal operation. During a write operation, a 0.013-inch (0.33 millimeter) data track is recorded, then tunnel-erased to 0.012 inch (0.030 millimeter). If the diskette is write-protected, a write-protect sensor disables the drive's circuitry, and an appropriate signal is sent to the interface.

Data is read from the diskette by the data-recovery circuitry, which consists of a low-level read amplifier, differentiator, zero-crossing detector, and digitizing circuits. All data decoding is done by an adapter card.

The diskette drive also has the following sensor systems:

1. The track 00 switch, which senses when the head/carriage assembly is at track 00.

2. The index sensor, which consists of an LED light source and phototransistor. This sensor is positioned so that when an index hole is detected, a digital signal is generated.

3. The write-protect sensor disables the diskette drive's electronics whenever a write-protect tab is applied to the diskette.

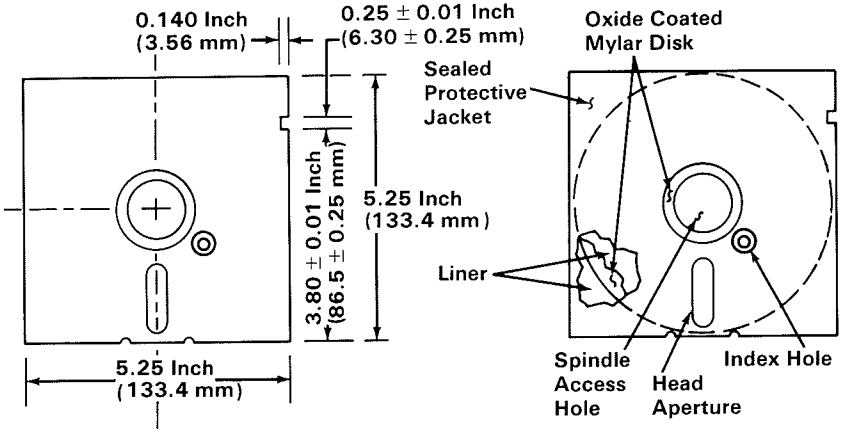
For interface information, refer to "IBM 5-1/4" Diskette Drive Adapter" earlier in this section.

Media	Industry-compatible 5-1/4 inch diskette
Tracks per inch	48
Number of tracks	40
Dimensions	
Height	3.38 inches (85.85 mm)
Width	5.87 inches (149.10 mm)
Depth	8.00 inches (203.2 mm)
Weight	4.50 pounds (2.04 kg)
Temperature (Exclusive of media)	
Operating	50°F to 112°F (10°C to 44°C)
Non operating	-40°F to 140°F (-40°C to 60°C)
Relative humidity (Exclusive of media)	
Operating	20% to 80% (non condensing)
Non operating	5% to 95% (non condensing)
Seek Time	6 ms track-to-track
Head Settling Time	15 ms (last track addressed)
Error Rate	1 per 10^9 (recoverable) 1 per 10^{12} (non recoverable) 1 per 10^6 (seeks)
Head Life	20,000 hours (normal use)
Media Life	3.0 x 10^6 passes per track
Disk Speed	300 rpm +/- 1.5% (long term)
Instantaneous Speed Variation	+/- 3.0%
Start/Stop Time	250 ms (maximum)
Transfer Rate	250K bits/sec
Recording Mode	MFM
Power	+12 Vdc +/- 0.6 V, 900 mA average +5 Vdc +/- 0.25 V, 600 mA average

Mechanical and Electrical Specifications

Diskettes

The IBM 5-1/4" Diskette Drive uses a standard 5.25-inch (133.4-millimeter) diskette. For programming considerations, single-sided, double-density, soft-sectored diskettes are used for single-sided drives. Double-sided drives use double-sided, double-density, soft-sectored diskettes. The figure below is a simplified drawing of the diskette used with the diskette drive. This recording medium is a flexible magnetic disk enclosed in a protective jacket. The protected disk, free to rotate within the jacket, is continuously cleaned by the soft fabric lining of the jacket during normal operation. Read/write/erase head access is made through an opening in the jacket. Openings for the drive hub and diskette index hole are also provided.



Recording Medium

Notes:

IBM Fixed Disk Drive Adapter

The fixed disk drive adapter attaches to one or two fixed disk drive units, through an internal daisy-chained flat cable (data/control cable). Each system supports a maximum of one fixed disk drive adapter and two fixed disk drives.

The adapter is buffered on the I/O bus and uses the system board direct memory access (DMA) for record data transfers. An interrupt level also is used to indicate operation completion and status conditions that require processor attention.

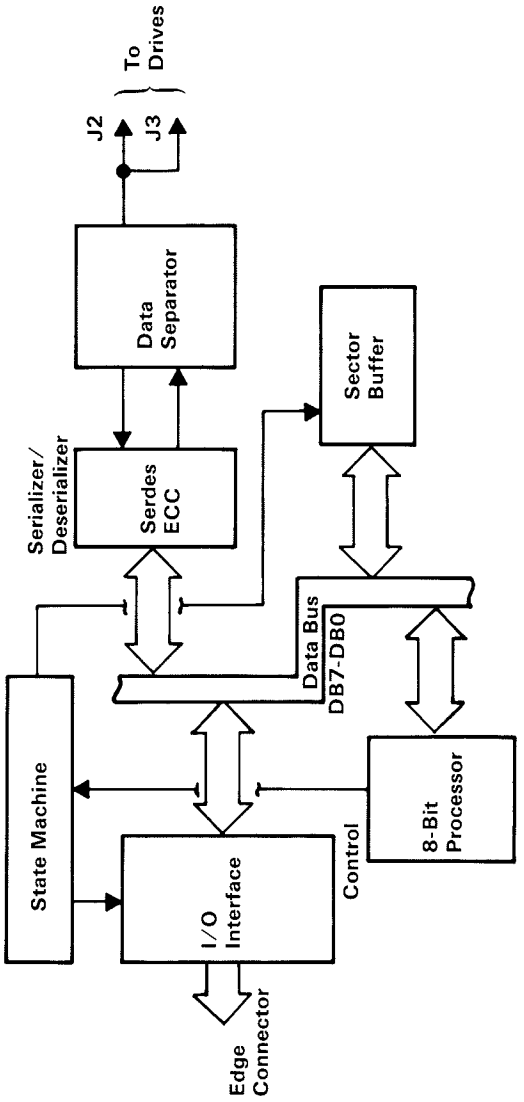
The fixed disk drive adapter provides automatic 11-bit burst error detection and correction in the form of 32-bit error checking and correction (ECC).

The device level control for the fixed disk drive adapter is contained on a ROM module on the adapter. A listing of this device level control can be found in "Appendix A: ROM BIOS Listings."

WARNING: The last cylinder on the fixed disk drive is reserved for diagnostic use. Diagnostic write tests will destroy any data on this cylinder.

Fixed Disk Controller

The disk controller has two registers that may be accessed by the main system processor: a status register and a data register. The 8-bit status register contains the status information of the disk controller, and can be accessed at any time. The 8-bit data register (actually consisting of several registers in a stack with only one register presented to the data bus) stores data, commands, parameters, and provides the disk controller's status information. Data bytes are read from, or written to the data register in order to program or obtain the results after a particular command. The status register is a read-only register, and is used to help the transfer of data between the processor and the disk controller. The controller-select pulse is generated by writing to port address hex 322.



Fixed Disk Drive Adapter Block Diagram

Programming Considerations

Status Register

At the end of all commands from the system board, the disk controller returns a completion status byte back to the system board. This byte informs the system unit if an error occurred during the execution of the command. The following shows the format of this byte.

Bit	7	6	5	4	3	2	1	0
	0	0	d	0	0	0	e	0

Bits 0, 1, 2, 3, 4, 6, 7 — These bits are set to zero.

Bit 1 — When set, this bit shows an error has occurred during command execution.

Bit 5 — This bit shows the logical unit number of the drive.

If the interrupts are enabled, the controller sends an interrupt when it is ready to transfer the status byte. Busy from the disk controller is unasserted when the byte is transferred to complete the command.

Sense Bytes

If the status register receives an error (bit 1 is set), then the disk controller requests four bytes of sense data. The format for the four bytes is as follows:

Bits	7	6	5	4	3	2	1	0
Byte 0	Address Valid	0	Error Type		Error Code			
Byte 1	0	0	d	Head Number				
Byte 2	Cylinder High			Sector Number				
Byte 3	Cylinder Low							

Remarks

d = drive

Byte 0	Bits 0, 1, 2, 3	Error code.
Byte 0	Bits 4, 5	Error type.
Byte 0	Bit 6	Set to 0 (spare).
Byte 0	Bit 7	The address valid bit. Set only when the previous command required a disk address, in which case it is returned as a 1; otherwise, it is a 0.

The following disk controller tables list the error types and error codes found in byte 0:

	Error Type	Error Code	
Bits	5 4	3 2 1 0	Description
	0 0	0 0 0 0	The controller did not detect any error during the execution of the previous operation.
	0 0	0 0 0 1	The controller did not detect an index signal from the drive.
	0 0	0 0 1 0	The controller did not get a seek-complete signal from the drive after a seek operation (for all non-buffered step seeks).
	0 0	0 0 1 1	The controller detected a write fault from the drive during the last operation.
	0 0	0 1 0 0	After the controller selected the drive, the drive did not respond with a ready signal.
	0 0	0 1 0 1	Not used.
	0 0	0 1 1 0	After stepping the maximum number of cylinders, the controller did not receive the track 00 signal from the drive.
	0 0	0 1 1 1	Not used.
	0 0	1 0 0 0	The drive is still seeking. This status is reported by the Test Drive Ready command for an overlap seek condition when the drive has not completed the seek. No time-out is measured by the controller for the seek to complete.

	Error Type	Error Code	
Bits	5 4	3 2 1 0	Description
	0 1	0 0 0 0	ID Read Error: The controller detected an ECC error in the target ID field on the disk.
	0 1	0 0 0 1	Data Error: The controller detected an uncorrectable ECC error in the target sector during a read operation.
	0 1	0 0 1 0	Address Mark: The controller did not detect the target address mark (AM) on the disk.
	0 1	0 0 1 1	Not used.
	0 1	0 1 0 0	Sector Not Found: The controller found the correct cylinder and head, but not the target sector.
	0 1	0 1 0 1	Seek Error: The cylinder or head address (either or both) did not compare with the expected target address as a result of a seek.
	0 1	0 1 1 0	Not used.
	0 1	0 1 1 1	Not used.
	0 1	1 0 0 0	Correctable Data Error: The controller detected a correctable ECC error in the target field.
	0 1	1 0 0 1	Bad Track: The controller detected a bad track flag during the last operation. No retries are attempted on this error.

	Error Type	Error Code	
Bits	5 4	3 2 1 0	Description
	1 0	0 0 0 0	Invalid Command: The controller has received an invalid command from the system unit.
	1 0	0 0 0 1	Illegal Disk Address: The controller detected an address that is beyond the maximum range.

	Error Type	Error Code	
Bits	5 4	3 2 1 0	Description
	1 1	0 0 0 0	RAM Error: The controller detected a data error during the RAM sector-buffer diagnostic test.
	1 1	0 0 0 1	Program Memory Checksum Error: During this internal diagnostic test, the controller detected a program-memory checksum error.
	1 1	0 0 1 0	ECC Polynominal Error: During the controller's internal diagnostic tests, the hardware ECC generator failed its test.

Data Register

The processor specifies the operation by sending the 6-byte device control block (DCB) to the controller. The figure below shows the composition of the DCB, and defines the bytes that make up the DCB.

Bit	7	6	5	4	3	2	1	0
Byte 0	Command Class			Opcode				
Byte 1	0	0	d	Head Number				
Byte 2	Cylinder High			Sector Number				
Byte 3	Cylinder Low							
Byte 4	Interleave or Block Count							
Byte 5	Control Field							

Byte 0 – Bits 7, 6, and 5 identify the class of the command.
Bits 4 through 0 contain the Opcode command.

Byte 1 – Bit 5 identifies the drive number.
Bits 4 through 0 contain the disk head number to be selected.
Bits 6 and 7 are not used.

Byte 2 – Bits 6 and 7 contain the two most significant bits of the cylinder number.
Bits 0 through 5 contain the sector number.

Byte 3 – Bits 0 through 7 are the eight least significant bits of the cylinder number.

Byte 4 – Bits 0 through 7 specify the interleave or block count.

Byte 5 – Bits 0 through 7 contain the control field.

Control Byte

Byte 5 is the control field of the DCB and allows the user to select options for several types of disk drives. The format of this byte is as follows:

Bits	7	6	5	4	3	2	1	0
	r	a	0	0	0	s	s	s

Remarks

r = retries
s = step option
a = retry option on data ECC error

Bit 7 Disables the four retries by the controller on all disk-access commands. Set this bit only during the evaluation of the performance of a disk drive.

Bit 6 If set to 0 during read commands, a reread is attempted when an ECC error occurs. If no error occurs during reread, the command will complete with no error status. If this bit is set to 1, no reread is attempted.

Bits 5, 4, 3 Set to 0.

Bits 2, 1, 0 These bits define the type of drive and select the step option. See the following figure.

Bits 2, 1, 0	
0 0 0	This drive is not specified and defaults to 3 milliseconds per step.
0 0 1	N/A
0 1 0	N/A
0 1 1	N/A
1 0 0	200 microseconds per step.
1 0 1	70 microseconds per step (specified by BIOS).
1 1 0	3 milliseconds per step.
1 1 1	3 milliseconds per step.

Command Summary

Test Drive Ready (Class 0, Opcode 00)

Bit	7	6	5	4	3	2	1	0
Byte 0	0	0	0	0	0	0	0	0
Byte 1	0	0	d	x	x	x	x	x

d = drive (0 or 1)
x = don't care
Bytes 2, 3, 4, 5 = don't care

Recalibrate (Class 0, Opcode 01)

Bit	7	6	5	4	3	2	1	0
Byte 0	0	0	0	0	0	0	0	1
Byte 1	0	0	d	x	x	x	x	x
Byte 5	r	0	0	0	0	s	s	s

d = drive (0 or 1)
x = don't care
r = retries
s = Step Option
Bytes 2, 3, 4 = don't care
ch = cylinder high

Reserved (Class 0, Opcode 02)

This Opcode is not used.

Request Sense Status (Class 0, Opcode 03)

Bit	7	6	5	4	3	2	1	0
Byte 0	0	0	0	0	0	0	1	1
Byte 1	0	0	d	x	x	x	x	x

d = drive (0 or 1)
x = don't care
Bytes 2, 3, 4, 5 = don't care

Format Drive (Class 0, Opcode 04)

Bit	7	6	5	4	3	2	1	0
Byte 0	0	0	0	0	0	1	0	0
Byte 1	0	0	d	Head Number				
Byte 2	ch		0	0	0	0	0	0
Byte 3	Cylinder Low							
Byte 4	0	0	0	Interleave				
Byte 5	r	0	0	0	0	s	s	s

d = drive (0 or 1)
r = retries
s = step option
ch = cylinder high

Interleave: 1 to 16 for 512-byte sectors.

Ready Verify (Class 0, Opcode 05)

Bit	7	6	5	4	3	2	1	0
Byte 1	0	0	0	0	0	1	0	1
Byte 1	0	0	d	Head Number				
Byte 2	ch		Sector Number					
Byte 3	Cylinder Low							
Byte 4	Block Count							
Byte 5	r	a	0	0	0	s	s	s

d = drive (0 or 1)
r = retries
s = step option
a = retry option on data ECC
ch = cylinder high

Format Track (Class 0, Opcode 06)

Bit	7	6	5	4	3	2	1	0
Byte 0	0	0	0	0	0	1	1	0
Byte 1	0	0	d	Head Number				
Byte 2	ch			0	0	0	0	0
Byte 3	Cylinder Low							
Byte 4	0	0	0	Interleave				
Byte 5	r	0	0	0	0	s	s	s

d = drive (0 or 1)
r = retries
s = step option
ch =cylinder high

Interleave: 1 to 16 for 512-byte sectors

Format Bad Track (Class 0, Opcode 07)

Bit	7	6	5	4	3	2	1	0
Byte 0	0	0	0	0	0	1	1	1
Byte 1	0	0	d	Head Number				
Byte 2	ch			0	0	0	0	0
Byte 3	Cylinder Low							
Byte 4	0	0	0	Interleave				
Byte 5	r	0	0	0	0	s	s	s

d = drive (0 or 1)
r = retries
s = step option
ch = cylinder high

Interleave: 1 to 16 for 512-byte sectors

Read (Class 0, Opcode 08)

Bit	7	6	5	4	3	2	1	0
Byte 0	0	0	0	0	1	0	0	0
Byte 1	0	0	d	Head Number				
Byte 2	ch			Sector Number				
Byte 3	Cylinder Low							
Byte 5	r	a	0	0	0	s	s	s

d = drive (0 or 1)
r = retries
a = retry option on data ECC error
s = step option
ch =cylinder high

Reserved (Class 0, (Opcode 09)

This Opcode is not used

Write (Class 0, Opcode 0A)

Bit	7	6	5	4	3	2	1	0
Byte 0	0	0	0	0	1	0	1	0
Byte 1	0	0	d	Head Number				
Byte 2	ch			Sector Number				
Byte 3	Cylinder Low							
Byte 4	Block Count							
Byte 5	r	0	0	0	0	s	s	s

d = drive (0 or 1)
r = retries
s = step option
ch = cylinder high

Seek (Class 0, Opcode 0B)

Bit	7	6	5	4	3	2	1	0
Byte 0	0	0	0	0	1	0	1	1
Byte 1	0	0	d	Head Number				
Byte 2	ch			0	0	0	0	0
Byte 3	Cylinder Low							
Byte 4	x	x	x	x	x	x	x	x
Byte 5	r	0	0	0	0	s	s	s

d = drive (0 or 1)
r = retries
s = step option
x = don't care
ch = cylinder high

Command	Data Control Block	Remarks
Initialize Drive Characteristics* (Class 0, Opcode 0C)	Bit 7 6 5 4 3 2 1 0 Byte 0 0 0 0 0 1 1 0 0	Bytes 1, 2, 3, 4, 5 = don't care
Read ECC Burst Error Length (Class 0, Opcode 0D)	Bit 7 6 5 4 3 2 1 0 Byte 0 0 0 0 0 1 1 0 1	Bytes 1, 2, 3, 4, 5 = don't care
Read Data from Sector Buffer (Class 0, Opcode 0E)	Bit 7 6 5 4 3 2 1 0 Byte 0 0 0 0 0 1 1 1 0	Bytes 1, 2, 3, 4, 5 = don't care
Write Data to Sector Buffer (Class 0, Opcode 0F)	Bit 7 6 5 4 3 2 1 0 Byte 0 0 0 0 0 1 1 1 1	Bytes 1, 2, 3, 4, 5 = don't care
RAM Diagnostic (Class 7, Opcode 00)	Bit 7 6 5 4 3 2 1 0 Byte 0 1 1 1 0 0 0 0 0	Bytes 1, 2, 3, 4, 5 = don't care
Reserved (Class 7, Opcode 01)		This Opcode is not used
Reserved (Class 7, Opcode 02)		This Opcode is not used

*Initialize Drive Characteristics: The DCB must be followed by eight additional bytes.

Maximum number of cylinders	(2 bytes)
Maximum number of heads	(1 byte)
Start reduced write current cylinder	(2 bytes)
Start write precompensation cylinder	(2 bytes)
Maximum ECC data burst length	(1 byte)

Drive Diagnostic (Class 7, Opcode 03)

Bit	7	6	5	4	3	2	1	0
Byte 0	1	1	1	0	0	0	1	1
Byte 1	0	0	d	x	x	x	x	x
Byte 2	x	x	x	x	x	x	x	x
Byte 3	x	x	x	x	x	x	x	x
Byte 4	x	x	x	x	x	x	x	x
Byte 5	r	0	0	0	0	s	s	s

d = drive (0 or 1)
s = step option
r = retries
x = don't care

Controller Internal Diagnostics (Class 7, Opcode 04)

Bit	7	6	5	4	3	2	1	0
Byte 0	1	1	1	0	0	1	0	0

Bytes 1, 2, 3, 4, 5 = don't care

Read Long* (Class 7, Opcode 05)

Bit	7	6	5	4	3	2	1	0
Byte 0	1	1	1	0	0	1	0	1
Byte 1	0	0	d	Head Number				
Byte 2	ch	Sector Number						
Byte 3	Cylinder Low							
Byte 4	Block Count							
Byte 5	r	0	0	0	0	s	s	s

d = drive (0 or 1)
s = step option
r = retries
ch = cylinder high

Write Long (Class 7, Opcode 06)**

Bit	7	6	5	4	3	2	1	0
Byte 0	1	1	1	0	0	1	1	0
Byte 1	0	0	d	Head Number				
Byte 2	ch	Sector Number						
Byte 3	Cylinder Low							
Byte 4	Block Count							
Byte 5	r	0	0	0	0	s	s	s

d = drive (0 or 1)
s = step option
r = retries
ch = cylinder high

*Returns 512 bytes plus 4 bytes of ECC data per sector.
**Requires 512 bytes plus 4 bytes of ECC data per sector.

Programming Summary

The two least-significant bits of the address bus are sent to the system board's I/O port decoder, which has two sections. One section is enabled by the I/O read signal (−IOR) and the other by the I/O write signal (−IOW). The result is a total of four read/write ports assigned to the disk controller board.

The address enable signal (AEN) is asserted by the system board when DMA is controlling data transfer. When AEN is asserted, the I/O port decoder is disabled.

The following figure is a table of the four read/write ports:

R/W	Port Address	Function
Read Write	320 320	Read data (from controller to system unit). Write data (from system unit to controller).
Read Write	321 321	Read controller hardware status. Controller reset.
Read Write	322 322	Reserved. Generate controller-select pulse.
Read Write	323 323	Not used. Write pattern to DMA and interrupt mask register.

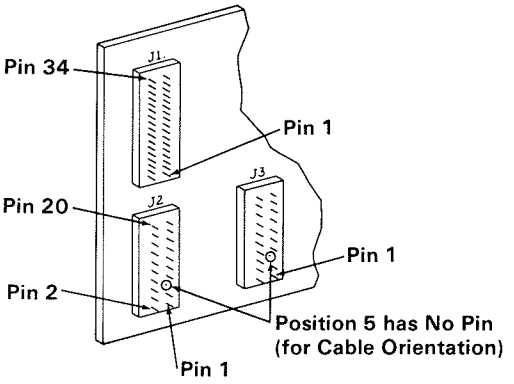
System I/O Channel Interface

The following lines are used by the disk controller:

A0-A19	Positive true 20-bit address. The least-significant 10 bits contain the I/O address within the range of hex 320 to hex 323 when an I/O read or write is executed by the system unit. The full 20 bits are decoded to address the read-only memory (ROM) between the addresses of hex C8000 and C9FFF.
D0-D7	Positive 8-bit data bus over which data and status information is passed between the system board and the controller.
$\overline{\text{IOR}}$	Negative true signal that is asserted when the system board reads status or data from the controller under either programmed I/O or DMA control.
$\overline{\text{IOW}}$	Negative true signal that is asserted when the system board sends a command or data to the controller under either programmed I/O or DMA control.
AEN	Positive true signal that is asserted when the DMA in the system board is generating the I/O Read (−IOR) or I/O Write (−IOW) signals and has control of the address and data buses.
RESET	Positive true signal that forces the disk controller to its initial power-up condition.
IRQ 5	Positive true interrupt request signal that is asserted by the controller, when enabled to interrupt the system board on the return ending status byte from the controller.

DRQ 3 — Positive-true DMA-request signal that is asserted by the controller when data is available for transfer to or from the controller under DMA control. This signal remains active until the system board's DMA channel activates the DMA-acknowledge signal (−DACK 3) in response.

$\overline{\text{DACK 3}}$ — This signal is true when negative, and is generated by the system board DMA channel in response to a DMA request (DRQ 3).



Disk Drive Connector J1	Signal	Pin Number	Disk Adapter Connector J1
	Ground - Odd Numbers	1-33	
	Reserved	4, 16, 30, 32	
←	-Reduced Write Current	2	
←	-Write Gate	6	
←	-Seek Complete	8	
→	-Track 00	10	
→	-Write Fault	12	→
←	-Head Select 2^0	14	
←	-Head Select 2^1	18	
→	-Index	20	
→	-Ready	22	
←	-Step	24	
←	-Drive Select 1	26	
←	-Drive Select 2	28	
←	-Direction In	34	

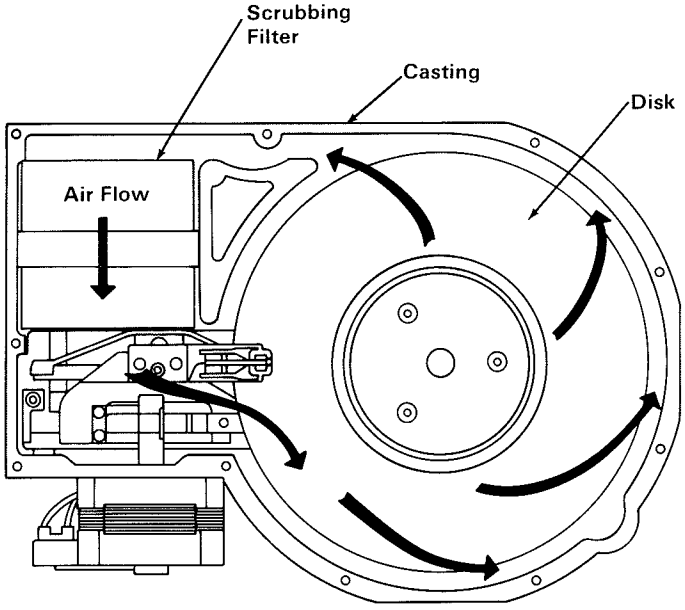
Disk Drive Connector J2 or J3	Signal	Pin Number	Disk Adapter Connector J2 or J3
	Ground	2, 4, 6, 8, 12, 16, 20	
→	Drive Select	1	
	Reserved	3, 7	
	Spare	9, 10, 5 (No Pin)	
	Ground	11	
←	MFM Write Data	13	
←	-MFM Write Data	14	
	Ground	15	
→	MFM Read Data	17	
→	-MFM Read Data	18	
	Ground	19	

Fixed Disk Adapter Interface Specifications

IBM 10MB Fixed Disk Drive

The disk drive is a random-access storage device that uses two non-removable 5-1/4 inch disks for storage. Each disk surface employs one movable head to service 306 cylinders. The total formatted capacity of the four heads and surfaces is 10 megabytes (17 sectors per track with 512 bytes per sector and a total of 1224 tracks).

An impact-resistant enclosure provides mechanical and contamination protection for the heads, actuator, and disks. A self-contained recirculating system supplies clean air through a 0.3-micron filter. Thermal isolation of the stepper and spindle motor assemblies from the disk enclosure results in a very low temperature rise within the enclosure. This isolation provides a greater off-track margin and the ability to perform read and write operations immediately after power-up with no thermal stabilization delay.



Media	Rigid media disk
Number of Tracks	1224
Track Density	345 tracks per inch
Dimensions	
Height	3.25 inches (82.55 mm)
Width	5.75 inches (146.05 mm)
Depth	8.0 inches (203.2 mm)
Weight	4.6 lb (2.08 kg)
Temperature	
Operating	40°F to 122°F (4°C to 50°C)
Non operating	-40°F to 140°F (-40°C to 60°C)
Relative Humidity	
Operating	8% to 80% (non condensing)
Maximum Wet Bulb	78°F (26°C)
Shock	
Operating	10 Gs
Non operating	20 Gs
Access Time	3 ms track-to-track
Average Latency	8.33 ms
Error Rates	
Soft Read Errors	1 per 10^{10} bits read
Hard Read Errors	1 per 10^{12} bits read
Seek Errors	1 per 10^{6} seeks
Design Life	5-years (8,000 hours MTF)
Disk Speed	3600 rpm ±1%
Transfer Rate	5.0 M bits/sec
Recording Mode	MFM
Power	+12 Vdc ± 5% 1.8 A (4.5 A maximum) +5 Vdc ± 5% 0.7 A (1.0 A maximum)
Maximum Ripple	1% with equivalent resistive load

Mechanical and Electrical Specifications

IBM Memory Expansion Options

Three memory expansion options (32KB, 64KB, and 64/256KB) and two memory module kits (16KB and 64KB) are available for the IBM Personal Computer. Memory expansion is described in the following chart:

	Minimum Memory	Maximum Memory	Number of 16K Memory Module Kits	Number of 64K Memory Module Kits	Memory Module Type
16/64K System Board	16K	64K	1, 2, or 3		16K by 1 Bit, 16 pin
64/256K System Board	64K	256K		1, 2, or 3	64K by 1 Bit, 16 pin
64/256K Memory Option	64K	256K		1, 2, or 3	64K by 1 Bit, 16 pin
32K Memory Option	32K				16K by 1 Bit, 16 pin
64K Memory Option	64K				Stacked 32K by 1 Bit, 18 pin

The system board must be fully populated before any memory expansion options can be installed. An expansion option must be configured to reside at a sequential 32K or 64K memory address boundary within the system address space. This is done by setting the DIP switches on the option.

All memory expansion options are parity checked. If a parity error is detected, a latch is set and an I/O channel check line is activated, indicating an error to the processor.

In addition to the memory modules, the memory expansion options contain the following circuits: bus buffering, dynamic memory timing generation, address multiplexing, and card-select decode logic.

Dynamic-memory refresh timing and address generation are functions performed on the system board and made available in the I/O channel for all devices.

To allow the system to address 32K, 64K, or 64/256K memory expansion options, refer to "Appendix G: Switch Settings" for the proper memory expansion option switch settings.

Operating Characteristics

The system board operates at a frequency of 4.77 MHz, which results in a clock cycle of 210 ns.

Normally four clock cycles are required for a bus cycle so that an 840-ns memory cycle time is achieved. Memory-write and memory-read cycles both take four clock cycles, or 840 ns.

General specifications for memory used on all cards are:

	16K by 1 Bit	32K by 1 Bit	64K by 1 Bit
Access	250 ns	250 ns	200 ns
Cycle	410 ns	410 ns	345 ns

Memory Module Description

Both the 32K and the 64K options contain 18 dynamic memory modules. The 32K memory expansion option utilizes 16K by 1 bit modules, and the 64K memory expansion option utilizes 32K by 1 bit modules.

The 64/256K option has four banks of 9 pluggable sockets. Each bank will accept a 64K memory module kit, consisting of 9 (64K by 1) modules. The kits must be installed sequentially into banks 1, 2, and 3. The base 64/256K option comes with modules installed in bank 0, providing 64K of memory. One, two, or three 64K bits may be added, upgrading the option to 128K, 192K, or 256K of memory.

The 16K by 1 and the 32K by 1 modules require three voltage levels: +5 Vdc, −5 Vdc, and +12 Vdc. The 64K by 1 modules require only one voltage level of +5 Vdc. All three memory modules require 128 refresh cycles every 2 ns. Absolute maximum access times are:

	16K by 1 Bit	32K by 1 Bit	64K by 1 Bit
From $\overline{RAS}$	250 ns	250 ns	200 ns
From $\overline{CAS}$	165 ns	165 ns	115 ns

Pin	16K by 1 Bit Module (used on 32K option and 16/64K system board)	32K by 1 Bit Module (used on 64K option)	64K by 1 Bit Module (used on 64/256K option and 64/256K system board)
1	-5 Vdc	-5 Vdc	N/C
2	Data In**	Data In**	Data In***
3	-Write	-Write	-Write
4	-RAS	-RAS 0	-RAS
5	A0	-RAS 1	A0
6	A2	A0	A2
7	A1	A2	A1
8	+12 Vdc	A1	+5 Vdc
9	+5 Vdc	+12 Vdc	A7
10	A5	+5 Vdc	A5
11	A4	A5	A4
12	A3	A4	A3
13	A6	A3	A6
14	Data Out**	A6	Data Out***
15	-CAS	Data Out**	-CAS
16	GND	-CAS 1	GND
17	*	-CAS 0	*
18	*	GND	*

*16K by 1 and 64K by 1 bit modules have 16 pins.
**Data In and Data Out are tied together (three-state bus).
***Data In and Data Out are tied together on Data Bits 0-7 (three-state bus).

Memory Module Pin Configuration

Switch-Configurable Start Address

Each card has a small DIP module, that contains eight switches. The switches are used to set the card start address as follows:

Number	32K and 64K Options	64/256K Options
1	ON: A19=0; OFF: A19=1	ON: A19=0; OFF: A19=1
2	ON: A18=0; OFF: A18=1	ON: A18=0; OFF: A18=1
3	ON: A17=0; OFF: A17=1	ON: A17=0; OFF: A17=1
4	ON: A16=0: OFF: A16=1	ON: A16=0; OFF: A16=1
5	ON: A15=0; OFF: A15=1*	ON: Select 64K
6	Not used	ON: Select 128K
7	Not used	ON: Select 192K
8	Used only in 64K RAM Card*	ON: Select 256K

*Switch 8 may be set on the 64K memory expansion option to use only half the memory on the card (that is, 32K). If switch 8 is on, all 64K is accessible. If switch 8 is off, address bit A15 (as set by switch 5) is used to determine which 32K are accessible, and the 64K option behaves as a 32K option.

DIP Module Start Address

Memory Option Switch Settings

Switch settings for all memory expansion options are located in "Appendix G: Switch Settings."

The following method can be used to determine the switch settings for the 32K memory expansion option.

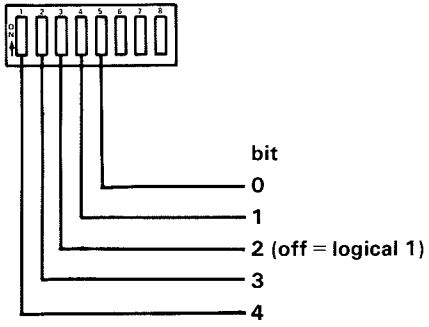
Starting Address = xxxK

32K ⌈xxxK⌉ =Decimal value

Convert decimal value to binary

Bit. 4 3 2 1 0
Bit value . . .16 8 4 2 1

Switch



The following method can be used to determine the switch settings for the 64K memory expansion option.

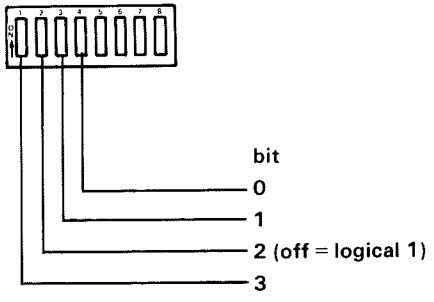
Starting Address = xxxK

64K ⌈xxxK⌉ =Decimal value

Convert decimal value to binary

Bit. 3 2 1 0
Bit value . . .8 4 2 1

Switch



The following method can be used to determine the switch settings for the 64/256K memory expansion option.

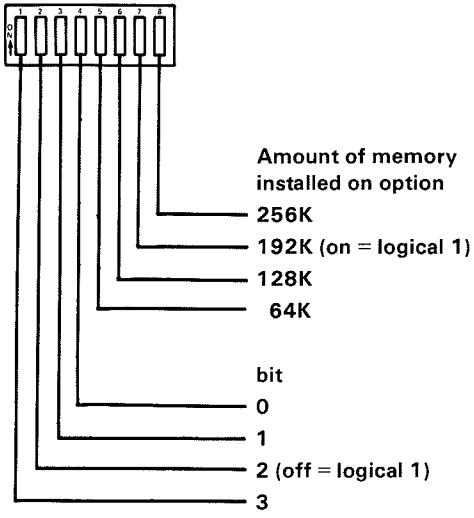
Starting Address = xxxK

64K ⌈xxxK⌉ =Decimal value

Convert decimal value to binary

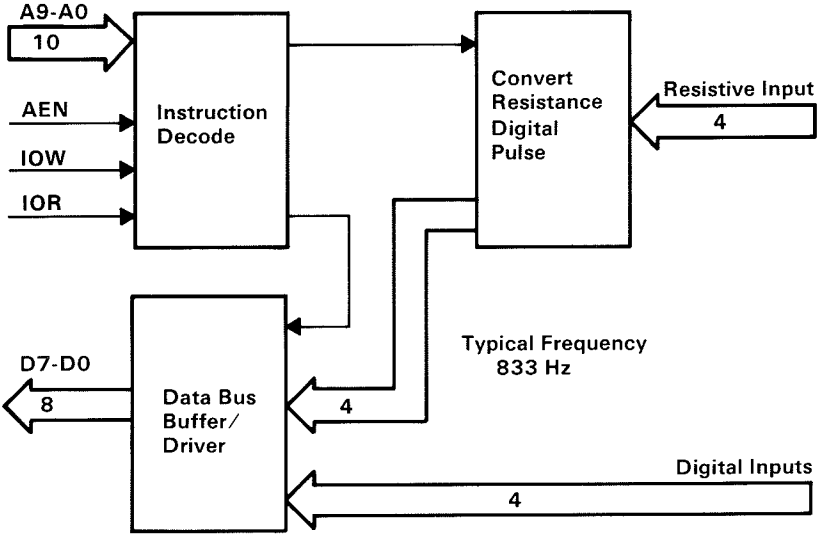
Bit. 3 2 1 0
Bit value. . .8 4 2 1

Switch



IBM Game Control Adapter

The game control adapter allows up to four paddles or two joy sticks to be attached to the system. This card fits into one of the system board's or expansion board's expansion slots. The game control interface cable attaches to the rear of the adapter. In addition, four inputs for switches are provided. Paddle and joy stick positions are determined by changing resistive values sent to the adapter. The adapter plus system software converts the present resistive value to a relative paddle or joy stick position. On receipt of an output signal, four timing circuits are started. By determining the time required for the circuit to time-out (a function of the resistance), the paddle position can be determined. This adapter could be used as a general purpose I/O card with four analog (resistive) inputs plus four digital input points.



Game Control Adapter Block Diagram

Functional Description

Address Decode

The select on the game control adapter is generated by two 74LS138s as an address decoder. AEN must be inactive while the address is hex 201 in order to generate the select. The select allows a write to fire the one-shots or a read to give the values of the trigger buttons and one-shot outputs.

Data Bus Buffer/Driver

The data bus is buffered by a 74LS244 buffer/driver. For an In from address hex 201, the game control adapter will drive the data bus; at all other times, the buffer is left in the high impedance state.

Trigger Buttons

The trigger button inputs are read by an In from address hex 201. A trigger button is on each joy stick or paddle. These values are seen on data bits 7 through 4. These buttons default to an open state and are read as "1." When a button is pressed, it is read as "0." Software should be aware that these buttons are not debounced in hardware.

Joy Stick Positions

The joy stick position is indicated by a potentiometer for each coordinate. Each potentiometer has a range from 0 to 100 k-ohms that varies the time constant for each of the four one-shots. As this time constant is set at different values, the output of the one-shot will be of varying durations.

All four one-shots are fired at once by an Out to address hex 201. All four one-shot outputs will go true after the fire pulse and will remain high for varying times depending on where each potentiometer is set.

These four one-shot outputs are read by an In from address hex 201 and are seen on data bits 3 through 0.

I/O Channel Description

A9-A0:	Address lines 9 through 0 are used to address the game control adapter.
D7-D0:	Data lines 7 through 0 are the data bus.
IOR, IOW:	I/O read and I/O write are used when reading from or writing to an adapter (In, Out).
AEN:	When active, the adapter must be inactive and the data bus driver inactive.
+5 Vdc:	Power for the game control adapter.
GND:	Common ground.
A19-A10:	Unused.
MEMR, MEMW:	Unused.
DACK0-DACK3:	Unused.
IRQ7-IRQ2:	Unused.
DRQ3-DRQ1:	Unused.
ALE, T/C:	Unused.
CLK, OSC:	Unused.
I/O CH CK:	Unused.
I/O CH RDY:	Unused.
RESET DRV:	Unused.
−5 Vdc, +12 Vdc, −12 Vdc:	Unused.

Interface Description

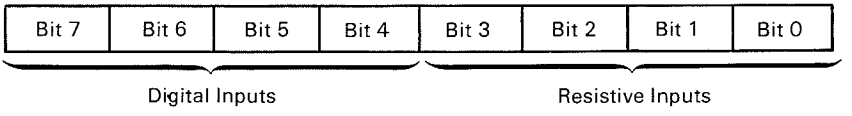
The game control adapter has eight input lines, four of which are digital inputs and 4 of which are resistive inputs. The inputs are read with one In from address hex 201.

The four digital inputs each have a 1 k-ohm pullup resistor +5 Vdc. With no drives on these inputs, a 1 is read. For a 0 reading, the inputs must be pulled to ground.

The four resistive pullups, measured to +5 Vdc, will be converted to a digital pulse with a duration proportional to the resistive load, according to the following equation:

$$\text{Time} = 24.2\ \mu\text{sec} + 0.011\ (\text{r})\ \mu\text{sec}$$

The user must first begin the conversation by an Out to address hex 201. An In from address hex 201 will show the digital pulse go high and remain high for the duration according to the resistance value. All four bits (bit 3-bit 0) function in the same manner; their digital pulse will all go high simultaneously and will reset independently according to the input resistance value.



The typical input to the game control adapter is a set of joy sticks or game paddles.

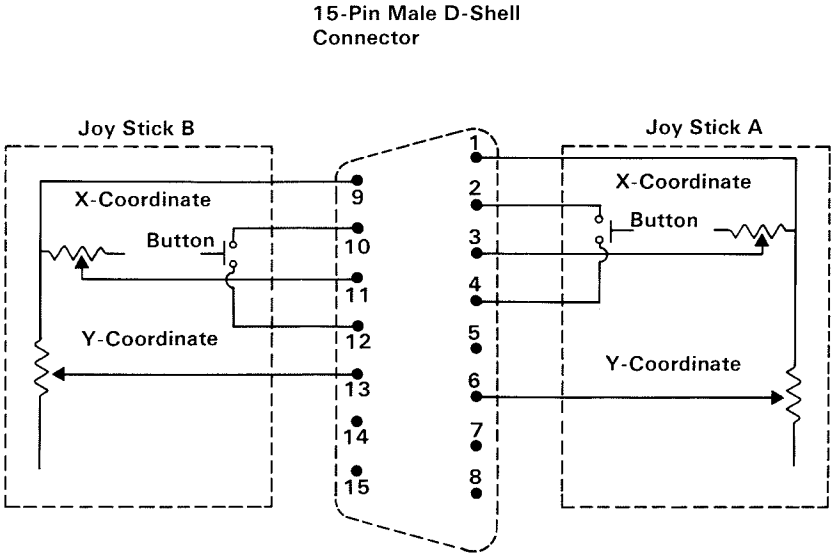
The joy sticks will typically be a set of two (A and B). These will have one or two buttons each with two variable resistances each, with a range from 0 to 100 k-ohms. One variable resistance will indicate the X-coordinate and the other variable resistance will indicate the Y-coordinate. This should be attached to give the following input data:

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
B-#2 Button	B-#1 Button	A-#2 Button	A-#1 Button	B-Y Coordinate	B-X Coordinate	A-Y Coordinate	A-X Coordinate

The game paddles will have a set of two (A and B) or four (A, B, C, and D) paddles. These will have one button each and one variable resistance each, with a range of 0 to 100 k-ohms. This should be attached to give the following input data:

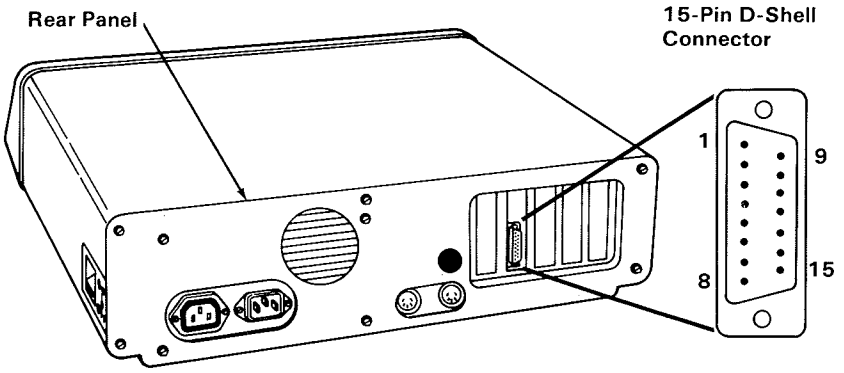
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
D Button	C Button	B Button	A Button	D Coordinate	C Coordinate	B Coordinate	A Coordinate

Refer to "Joy Stick Schematic Diagram" for attaching game controllers.



Note: Potentiometer for X- and Y-Coordinates has a range of 0 to 100 k-ohms. Button is normally open; closed when pressed.

Joy Stick Schematic Diagram



At Standard TTL Levels

Voltage	Adapter Pin No.
+5 Vdc	1
Button 4	2
Position 0	3
Ground	4
Ground	5
Position 1	6
Button 5	7
+5 Vdc	8
+5 Vdc	9
Button 6	10
Position 2	11
Ground	12
Position 3	13
Button 7	14
+5 Vdc	15

External Devices

Game Control Adapter

Connector Specifications

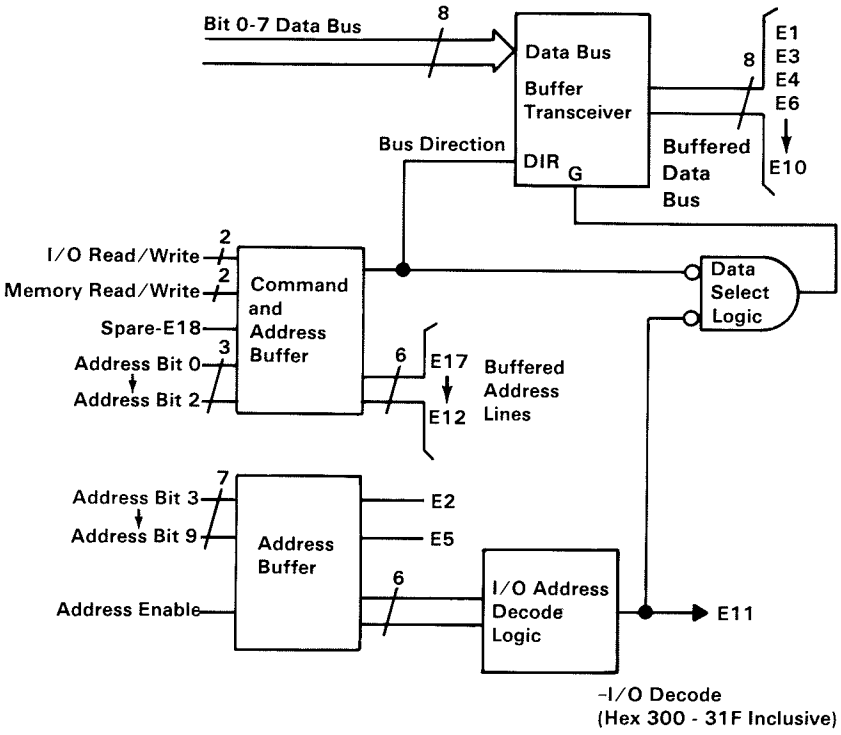
IBM Prototype Card

The prototype card is 4.2 inches (106.7 millimeters) high by 13.2 inches (335.3 millimeters) long and plugs into an expansion unit or system unit expansion slot. All system control signals and voltage requirements are provided through a 2 by 31 position card-edge tab.

The card contains a voltage bus (+5 Vdc) and a ground bus (0 Vdc). Each bus borders the card, with the voltage bus on the back (pin side) and the ground bus on the front (component side). A system interface design is also provided on the prototype card.

The prototype card can also accommodate a D-shell connector if it is needed. The connector size can range from a 9 to a 37 position connector.

Note: Install all components on the component side of the prototype card. The total width of the card including components should not exceed 0.500 inch (12.7 millimeters). If these specifications are not met, components on the prototype card may touch other cards plugged into adjacent slots.



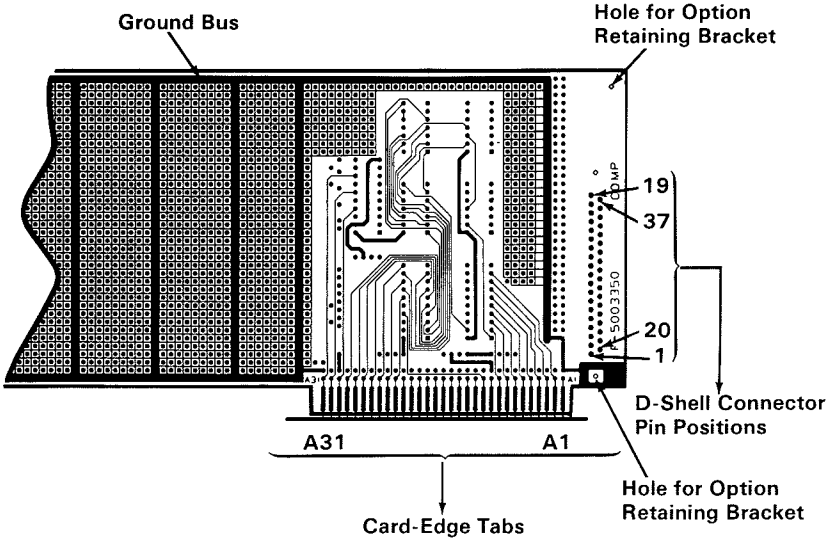
Prototype Card Block Diagram

I/O Channel Interface

The prototype card has two layers screened onto it (one on the front and one on the back). It also has 3,909 plated through-holes that are 0.040 inch (10.1 millimeters) in size and have a 0.060 inch (1.52 millimeters) pad, which is located on a 0.10 inch (2.54 millimeters) grid. There are 37 plated through-holes that are 0.048 inch (1.22 millimeters) in size. These holes are located at the rear of the card (viewed as if installed in the machine). These 37 holes are used for a 9 to 37 position D-shell connector. The card also has 5 holes that are 0.125 inch (3.18 millimeters) in size. One hole is located just above the two rows of D-shell connector holes, and the other four are located in the corners of the board (one in each corner).

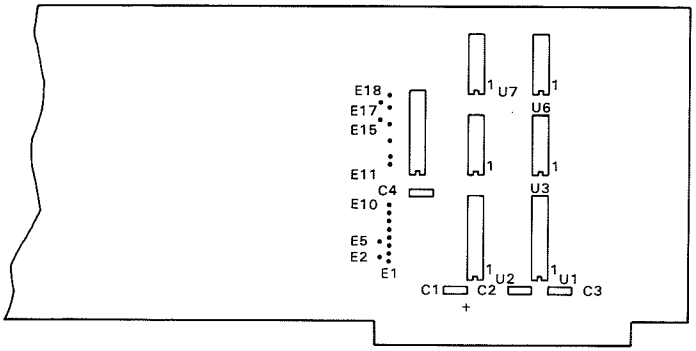
Prototype Card Layout

The component side has the ground bus [0.05 inch (1.27 millimeters) wide] screened on it and card-edge tabs that are labeled A1 through A31.



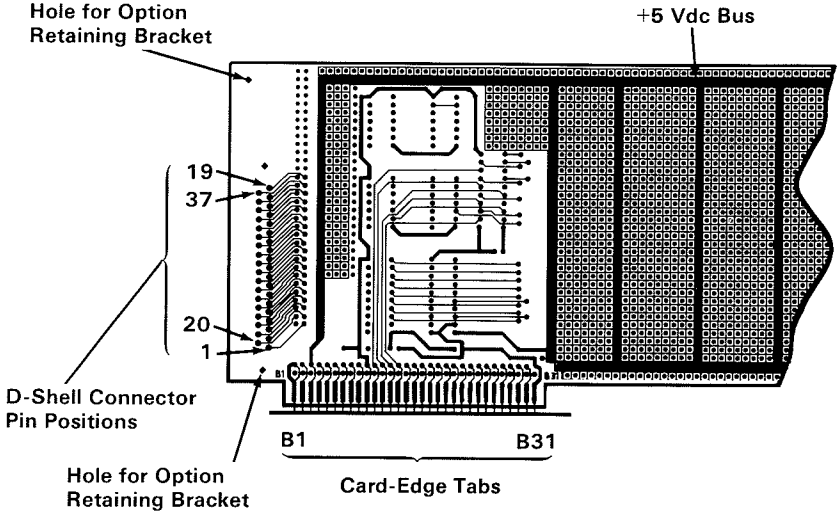
Component Side

The component side also has a silk screen printed on it that is used as a component guide for the I/O interface.



Component Side

The pin side has a +5 Vdc bus [0.05 inch (1.27 millimeters) wide] screened onto it and card-edge tabs that are labeled B1 through B31.



Pin Side

Each card-edged tab is connected to a plated through-hole by a 0.012-inch (0.3-millimeter) land. There are three ground tabs connected to the ground bus by three 0.012-inch (0.3-millimeter) lands. Also, there are two +5 Vdc tabs connected to the voltage bus by two 0.012-inch (0.3-millimeter) lands.

For additional interfacing information, refer to "I/O Channel Description" and "I/O Channel Diagram" in this manual. Also, the "Prototype Card Interface Logic Diagram" is in Appendix D of this manual. If the recommended interface logic is used, the list of TTL type numbers listed below will help you select the necessary components.

Component	TTL Number	Description
U1	74LS245	Octal Bus Transceiver
U2, U5	74LS244	Octal Buffers Line Driver/Line Receivers
U4	74LS04	Hex Inverters
U3	74LS08	Quadruple 2 - Input Positive - AND Gate
U6	74LS02	Quadruple 2 - Input Positive - NOR Gate
U7	74LS21	Dual 4 - Input Positive - AND Gate
C1		10.0 μF Tantalum Capacitor
C2, C3, C4		0.047 μF Ceramic Capacitor

System Loading and Power Limitations

Because of the number of options that may be installed in the system, the I/O bus loading should be limited to one Schottky TTL load. If the interface circuitry on the card is used, then this requirement is met.

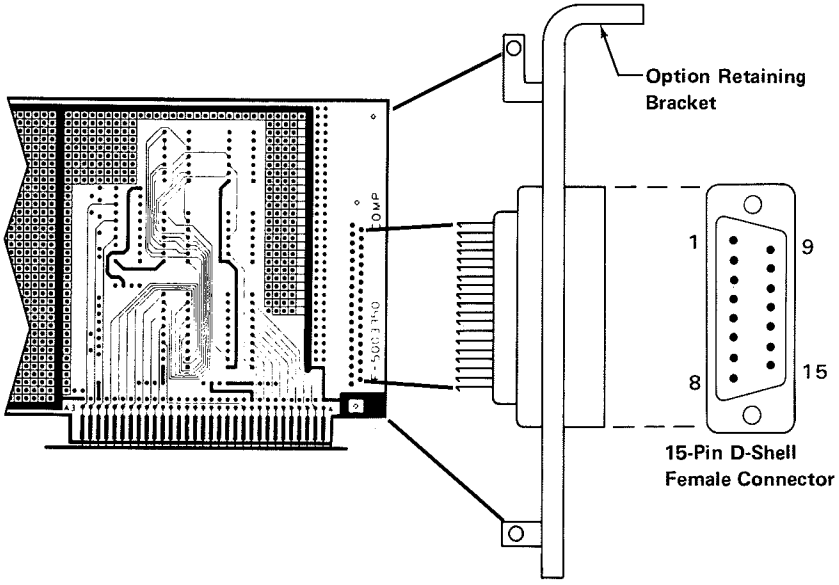
Refer to the power supply information in this manual for the power limitations to be observed.

Prototype Card External Interface

If a connector is required for the card function, then you should purchase one of the recommended connectors (manufactured by Amp) or equivalent listed below:

Connector Size	Part Number (Amp)
9-pin D-shell (Male)	205865-1
9-pin D-shell (Female)	205866-1
15-pin D-shell (Male)	205867-1
15-pin D-shell (Female)	205868-1
25-pin D-shell (Male	205857-1
25-pin D-shell (Female)	205858-1
37-pin D-shell (Male)	205859-1
37-pin D-shell (Female)	205860-1

The following example shows a 15-pin, D-shell, female connector attached to a prototype card.



Component Side

IBM Asynchronous Communications Adapter

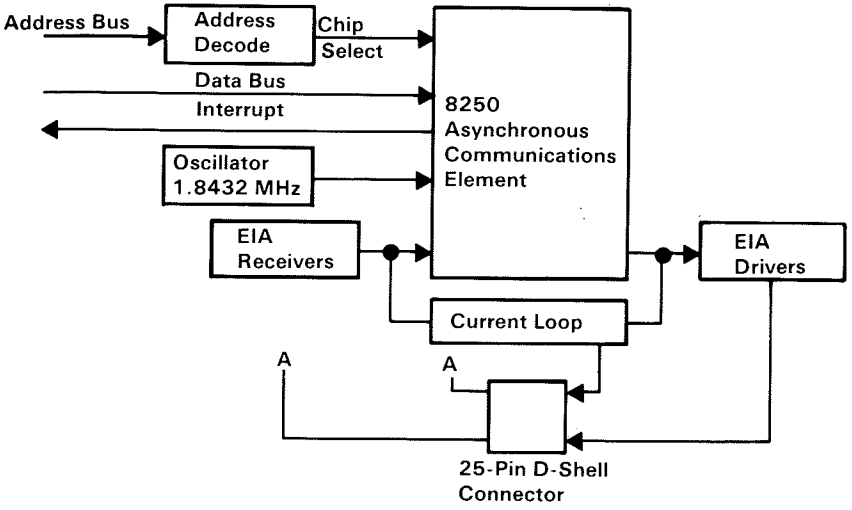
The asynchronous communications adapter system control signals and voltage requirements are provided through a 2 by 31 position card-edge tab. Two jumper modules are provided on the adapter. One jumper module selects either RS-232C or current-loop operation. The other jumper module selects one of two addresses for the adapter, so two adapters may be used in one system.

The adapter is fully programmable and supports asynchronous communications only. It will add and remove start bits, stop bits, and parity bits. A programmable baud rate generator allows operation from 50 baud to 9600 baud. Five, six, seven or eight bit characters with 1, 1-1/2, or 2 stop bits are supported. A fully prioritized interrupt system controls transmit, receive, error, line status and data set interrupts. Diagnostic capabilities provide loopback functions of transmit/receive and input/output signals.

The heart of the adapter is a INS8250 LSI chip or functional equivalent. Features in addition to those listed above are:

- Full double buffering eliminates need for precise synchronization.
- Independent receiver clock input.
- Modem control functions: clear to send (CTS), request to send (RTS), data set ready (DSR), data terminal ready (DTR), ring indicator (RI), and carrier detect.
- False-start bit detection.
- Line-break generation and detection.

All communications protocol is a function of the system microcode and must be loaded before the adapter is operational. All pacing of the interface and control signal status must be handled by the system software. The following figure is a block diagram of the asynchronous communications adapter.



Asynchronous Communications Adapter Block Diagram

Modes of Operation

The different modes of operation are selected by programming the 8250 asynchronous communications element. This is done by selecting the I/O address (hex 3F8 to 3FF primary, and hex 2F8 to 2FF secondary) and writing data out to the card. Address bits A0, A1, and A2 select the different registers that define the modes of operation. Also, the divisor latch access bit (bit 7) of the line control register is used to select certain registers.

I/O Decode (in Hex)			
Primary Adapter	Alternate Adapter	Register Selected	DLAB State
3F8	2F8	TX Buffer	DLAB=0 (Write)
3F8	2F8	RX Buffer	DLAB=0 (Read)
3F8	2F8	Divisor Latch LSB	DLAB=1
3F9	2F9	Divisor Latch MSB	DLAB=1
3F9	2F9	Interrupt Enable Register	
3FA	2FA	Interrupt Identification Registers	
3FB	2FB	Line Control Register	
3FC	2FC	Modem Control Register	
3FD	2FD	Line Status Register	
3FE	2FE	Modem Status Register	

I/O Decodes

Hex Address 3F8 to 3FF and 2F8 to 2FF											
A9	A8	A7	A6	A5	A4	A3	A2	A1	A0	DLAB	Register
1	1/0	1	1	1	1	1	x	x	x		
							0	0	0	0	Receive Buffer (read), Transmit Holding Reg. (write)
							0	0	1	0	Interrupt Enable
							0	1	0	x	Interrupt Identification
							0	1	1	x	Line Control
							1	0	0	x	Modem Control
							1	0	1	x	Line Status
							1	1	0	x	Modem Status
							1	1	1	x	None
							0	0	0	1	Divisor Latch (LSB)
							0	0	1	1	Divisor Latch (MSB)

Note: Bit 8 will be logical 1 for the adapter designated as primary or a logical 0 for the adapter designated as alternate (as defined by the address jumper module on the adapter).

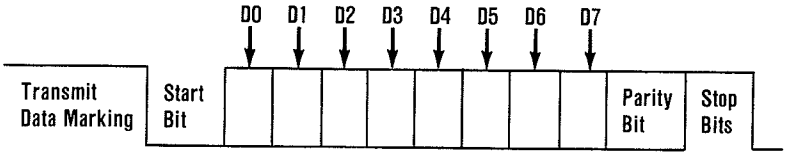
A2, A1 and A0 bits are "don't cares" and are used to select the different register of the communications chip.

Address Bits

Interrupts

One interrupt line is provided to the system. This interrupt is IRQ4 for a primary adapter or IRQ3 for an alternate adapter, and is positive active. To allow the communications card to send interrupts to the system, bit 3 of the modem control register must be set to 1 (high). At this point, any interrupts allowed by the interrupt enable register will cause an interrupt.

The data format will be as follows:



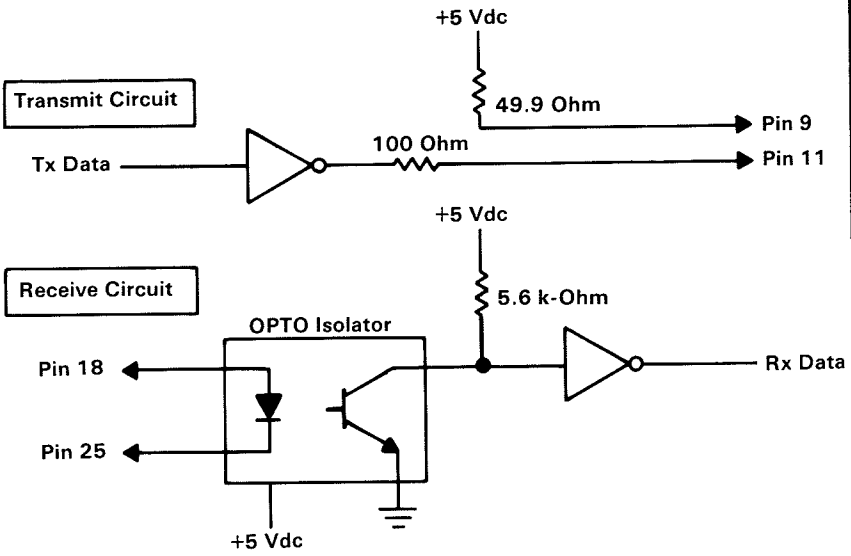
Data bit 0 is the first bit to be transmitted or received. The adapter automatically inserts the start bit, the correct parity bit if programmed to do so, and the stop bit (1, 1-1/2, or 2 depending on the command in the line-control register).

Interface Description

The communications adapter provides an EIA RS-232C-like interface. One 25-pin D-shell, male type connector is provided to attach various peripheral devices. In addition, a current loop interface is also located in this same connector. A jumper block is provided to manually select either the voltage interface, or the current loop interface.

The current loop interface is provided to attach certain printers provided by IBM that use this particular type of interface.

Pin 18 + receive current loop data
Pin 25 − receive current loop return
Pin 9 + transmit current loop return
Pin 11 − transmit current loop data



Current Loop Interface

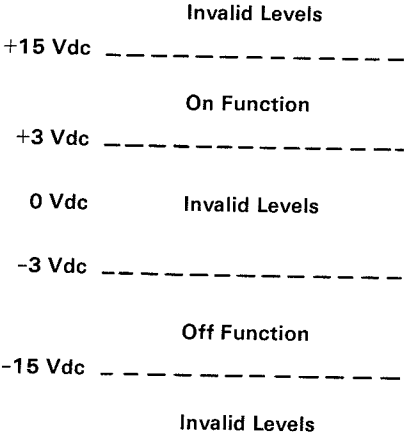
The voltage interface is a serial interface. It supports certain data and control signals, as listed below.

Pin 2	Transmitted Data
Pin 3	Received Data
Pin 4	Request to Send
Pin 5	Clear to Send
Pin 6	Data Set Ready
Pin 7	Signal Ground
Pin 8	Carrier Detect
Pin 20	Data Terminal Ready
Pin 22	Ring Indicator

The adapter converts these signals to/from TTL levels to EIA voltage levels. These signals are sampled or generated by the communications control chip. These signals can then be sensed by the system software to determine the state of the interface or peripheral device.

Voltage Interchange Information

Interchange Voltage	Binary State	Signal Condition	Interface Control Function
Positive Voltage =	Binary (0)	= Spacing	=On
Negative Voltage =	Binary (1)	= Marking	=Off



The signal will be considered in the "marking" condition when the voltage on the interchange circuit, measured at the interface point, is more negative than −3 Vdc with respect to signal ground. The signal will be considered in the "spacing" condition when the voltage is more positive than +3 Vdc with respect to signal ground. The region between +3 Vdc and −3 Vdc is defined as the transition region, and considered an invalid level. The voltage that is more negative than −15 Vdc or more positive than +15 Vdc will also be considered an invalid level.

During the transmission of data, the "marking" condition will be used to denote the binary state "1" and "spacing" condition will be used to denote the binary state "0."

For interface control circuits, the function is "on" when the voltage is more positive than +3 Vdc with respect to signal ground and is "off" when the voltage is more negative than −3 Vdc with respect to signal ground.

INS8250 Functional Pin Description

The following describes the function of all INS8250 input/output pins. Some of these descriptions reference internal circuits.

Note: In the following descriptions, a low represents a logical 0 (0 Vdc nominal) and a high represents a logical 1 (+2.4 Vdc nominal).

Input Signals

Chip Select (CS0, CS1, $\overline{CS2}$), Pins 12-14: When CS0 and CS1 are high and $\overline{CS2}$ is low, the chip is selected. Chip selection is complete when the decoded chip select signal is latched with an active (low) address strobe ($\overline{ADS}$) input. This enables communications between the INS8250 and the processor.

Data Input Strobe (DISTR, $\overline{DISTR}$) Pins 22 and 21: When DISTR is high or $\overline{DISTR}$ is low while the chip is selected, allows the processor to read status information or data from a selected register of the INS8250.

Note: Only an active DISTR or $\overline{DISTR}$ input is required to transfer data from the INS8250 during a read operation. Therefore, tie either the DISTR input permanently low or the $\overline{DISTR}$ input permanently high, if not used.

Data Output Strobe (DOSTR, $\overline{DOSTR}$), Pins 19 and 18: When DOSTR is high or $\overline{DOSTR}$ is low while the chip is selected, allows the processor to write data or control words into a selected register of the INS8250.

Note: Only an active DOSTR or $\overline{DOSTR}$ input is required to transfer data to the INS8250 during a write operation. Therefore, tie either the DOSTR input permanently low or the $\overline{DOSTR}$ input permanently high, if not used.

Address Strobe ($\overline{ADS}$), Pin 25: When low, provides latching for the register select (A0, A1, A2) and chip select (CS0, CS1, $\overline{CS2}$) signals.

Note: An active $\overline{ADS}$ input is required when the register select (A0, A1, A2) signals are not stable for the duration of a read or write operation. If not required, tie the $\overline{ADS}$ input permanently low.

Register Select (A0, A1, A2), Pins 26-28: These three inputs are used during a read or write operation to select an INS8250 register to read from or write to as indicated in the table below. Note that the state of the divisor latch access bit (DLAB), which is the most significant bit of the line control register, affects the selection of certain INS8250 registers. The DLAB must be set high by the system software to access the baud generator divisor latches.

DLAB	A2	A1	A0	Register
0	0	0	0	Receiver Buffer (Read), Transmitter Holding Register (Write)
0	0	0	1	Interrupt Enable
X	0	1	0	Interrupt Identification (Read Only)
X	0	1	1	Line Control
X	1	0	0	Modem Control
X	1	0	1	Line Status
X	1	1	0	Modem Control Status
X	1	1	1	None
1	0	0	0	Divisor Latch (Least Significant Bit)
1	0	0	1	Divisor Latch (Most Significant Bit)

Master Reset (MR), Pin 35: When high, clears all the registers (except the receiver buffer, transmitter holding, and divisor latches), and the control logic of the INS8250. Also, the state of various output signals (SOUT, INTRPT, $\overline{OUT\ 1}$, $\overline{OUT\ 2}$, $\overline{RTS}$, $\overline{DTR}$) are affected by an active MR input. Refer to the "Asynchronous Communications Reset Functions" table.

Receiver Clock (RCLK), Pin 9: This input is the 16 x baud rate clock for the receiver section of the chip.

Serial Input (SIN), Pin 10: Serial data input from the communications link (peripheral device, modem, or data set).

Clear to Send ($\overline{\text{CTS}}$), Pin 36: The $\overline{\text{CTS}}$ signal is a modem control function input whose condition can be tested by the processor by reading bit 4 (CTS) of the modem status register. Bit 0 (DCTS) of the modem status register indicates whether the $\overline{\text{CTS}}$ input has changed state since the previous reading of the modem status register.

Note: Whenever the CTS bit of the modem status register changes state, an interrupt is generated if the modem status interrupt is enabled.

Data Set Ready ($\overline{\text{DSR}}$), Pin 37: When low, indicates that the modem or data set is ready to establish the communications link and transfer data with the INS8250. The $\overline{\text{DSR}}$ signal is a modem-control function input whose condition can be tested by the processor by reading bit 5 (DSR) of the modem status register. Bit 1 (DDSR) of the modem status register indicates whether the $\overline{\text{DSR}}$ input has changed since the previous reading of the modem status register.

Note: Whenever the DSR bit of the modem status register changes state, an interrupt is generated if the modem status interrupt is enabled.

Received Line Signal Detect ($\overline{\text{RLSD}}$), Pin 38: When low, indicates that the data carrier had been detected by the modem or data set. The $\overline{\text{RLSD}}$ signal is a modem-control function input whose condition can be tested by the processor by reading bit 7 (RLSD) of the modem status register. Bit 3 (DRLSD) of the modem status register indicates whether the $\overline{\text{RLSD}}$ input has changed state since the previous reading of the modem status register.

Note: Whenever the RLSD bit of the modem status register changes state, an interrupt is generated if the modem status interrupt is enabled.

Ring Indicator ($\overline{RI}$), Pin 39: When low, indicates that a telephone ringing signal has been received by the modem or data set. The $\overline{RI}$ signal is a modem-control function input whose conditon can be tested by the processor by reading bit 6 (RI) of the modem status register. Bit 2 (TERI) of the modem status register indicates whether the $\overline{RI}$ input has changed from a low to high state since the previous reading of the modem status register.

Note: Whenever the RI bit of the modem status register changes from a high to a low state, an interrupt is generated if the modem status register interrupt is enabled.

VCC, Pin 40: +5 Vdc supply.

VSS, Pin 20: Ground (0 Vdc) reference.

Output Signals

Data Terminal Ready ($\overline{DTR}$), Pin 33: When low, informs the modem or data set that the INS8250 is ready to communicate. The DTR output signal can be set to an active low by programming bit 0 (DTR) of the modem control register to a high level. The $\overline{DTR}$ signal is set high upon a master reset operation.

Request to Send ($\overline{RTS}$), Pin 32: When low, informs the modem or data set that the INS8250 is ready to transmit data. The $\overline{RTS}$ output signal can be set to an active low by programming bit 1 (RTS) of the modem control register. The $\overline{RTS}$ signal is set high upon a master reset operation.

Output 1 ($\overline{OUT\ 1}$), Pin 34: User-designated output that can be set to an active low by programming bit 2 (OUT 1) of the modem control register to a high level. The $\overline{OUT\ 1}$ signal is set high upon a master reset operation.

Output 2 ($\overline{OUT\ 2}$), Pin 31: User-designated output that can be set to an active low by programming bit 3 (OUT 2) of the modem control register to a high level. The $\overline{OUT\ 2}$ signal is set high upon a master reset operation.

Chip Select Out (CSOUT), Pin 24: When high, indicates that the chip has been selected by active CS0, CS1, and $\overline{CS2}$ inputs. No data transfer can be initiated until the CSOUT signal is a logical 1.

Driver Disable (DDIS), Pin 23: Goes low whenever the processor is reading data from the INS8250. A high-level DDIS output can be used to disable an external transceiver (if used between the processor and INS8250 on the D7-D0 data bus) at all times, except when the processor is reading data.

Baud Out ($\overline{BAUDOUT}$), Pin 15: 16 x clock signal for the transmitter section of the INS8250. The clock rate is equal to the main reference oscillator frequency divided by the specified divisor in the baud generator divisor latches. The $\overline{BAUDOUT}$ may also be used for the receiver section by typing this output to the RCLK input of the chip.

Interrupt (INTRPT), Pin 30: Goes high whenever any one of the following interrupt types has an active high condition and is enabled through the IER: receiver error flag, received data available, transmitter holding register empty, or modem status. The INTRPT signal is reset low upon the appropriate interrupt service or a master reset operation.

Serial Output (SOUT), Pin 11: Composite serial data output to the communications link (peripheral, modem, or data set). The SOUT signal is set to the marking (logical 1) state upon a master reset operation.

Input/Output Signals

Data Bus (D7-D0), Pins 1-8: This bus comprises eight tri-state input/output lines. The bus provides bidirectional communications between the INS8250 and the processor. Data, control words, and status information are transferred through the D7-D0 data bus.

External Clock Input/Output (XTAL1, XTAL2), Pins 16 and 17: These two pins connect the main timing reference (crystal or signal clock) to the INS8250.

Programming Considerations

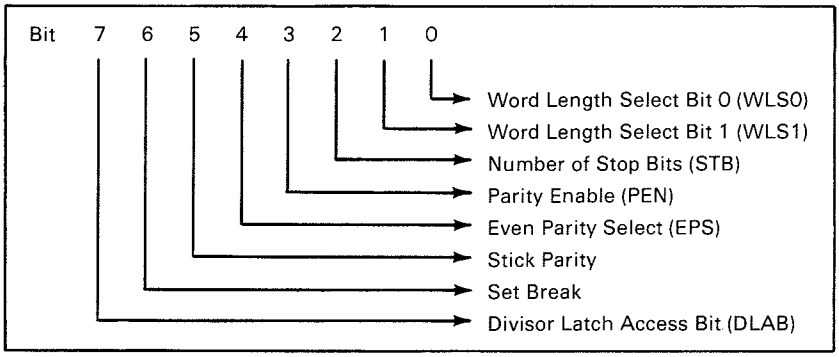
The INS8250 has a number of accessible registers. The system programmer may access or control any of the INS8250 registers through the processor. These registers are used to control INS8250 operations and to transmit and receive data. A table listing and description of the accessible registers follows.

Register/Signal	Reset Control	Reset State
Interrupt Enable Register	Master Reset	All Bits Low (0-3 Forced and 4-7 Permanent)
Interrupt Identification Register	Master Reset	Bit 0 is High, Bits 1 and 2 Low Bits 3-7 are Permanently Low
Line Control Register	Master Reset	All Bits Low
Modem Control Register	Master Reset	All Bits Low
Line Status Register	Master Reset	Except Bits 5 and 6 are High
Modem Status Register	Master Reset	Bits 0-3 Low Bits 4-7 - Input Signal
SOUT	Master Reset	High
INTRPT (RCVR Errors)	Read LSR/MR	Low
INTRPT (RCVR Data Ready)	Read RBR/MR	Low
INTRPT (RCVR Data Ready)	Read IIR/ Write THR/MR	Low
INTRPT (Modem Status Changes)	Read MSR/MR	Low
OUT 2	Master Reset	High
RTS	Master Reset	High
DTR	Master Reset	High
OUT 1	Master Reset	High

Asynchronous Communications Reset Functions

Line-Control Register

The system programmer specifies the format of the asynchronous data communications exchange through the line-control register. In addition to controlling the format, the programmer may retrieve the contents of the line-control register for inspection. This feature simplifies system programming and eliminates the need for separate storage in system memory of the line characteristics. The contents of the line-control register are indicated and described below.



Line-Control Register (LCR)

Bits 0 and 1: These two bits specify the number of bits in each transmitted or received serial character. The encoding of bits 0 and 1 is as follows:

Bit 1	Bit 0	Word Length
0	0	5 Bits
0	1	6 Bits
1	0	7 Bits
1	1	8 Bits

Bit 2: This bit specifies the number of stop bits in each transmitted or received serial character. If bit 2 is a logical 0, one stop bit is generated or checked in the transmit or receive data, respectively. If bit 2 is logical 1 when a 5-bit word length is selected through bits 0 and 1, 1-1/2 stop bits are generated or checked. If bit 2 is logical 1 when either a 6-, 7-, or 8-bit word length is selected, two stop bits are generated or checked.

Bit 3: This bit is the parity enable bit. When bit 3 is a logical 1, a parity bit is generated (transmit data) or checked (receive data) between the last data word bit and stop bit of the serial data. (The parity bit is used to produce an even or odd number of 1's when the data word bits and the parity bit are summed.)

Bit 4: This bit is the even parity select bit. When bit 3 is a logical 1 and bit 4 is a logical 0, an odd number of logical 1's is transmitted or checked in the data word bits and parity bit. When bit 3 is a logical 1 and bit 4 is a logical 1, an even number of bits is transmitted or checked.

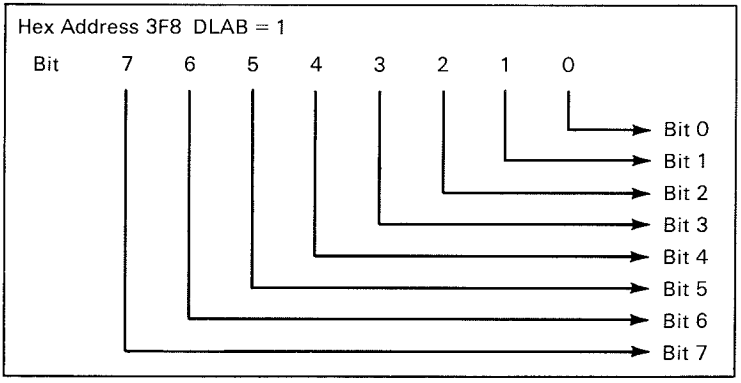
Bit 5: This bit is the stick parity bit. When bit 3 is a logical 1 and bit 5 is a logical 1, the parity bit is transmitted and then detected by the receiver as a logical 0 if bit 4 is a logical 1, or as a logical 1 if bit 4 is a logical 0.

Bit 6: This bit is the set break control bit. When bit 6 is a logical 1, the serial output (SOUT) is forced to the spacing (logical 0) state and remains there regardless of other transmitter activity. The set break is disabled by setting bit 6 to a logical 0. This feature enables the processor to alert a terminal in a computer communications system.

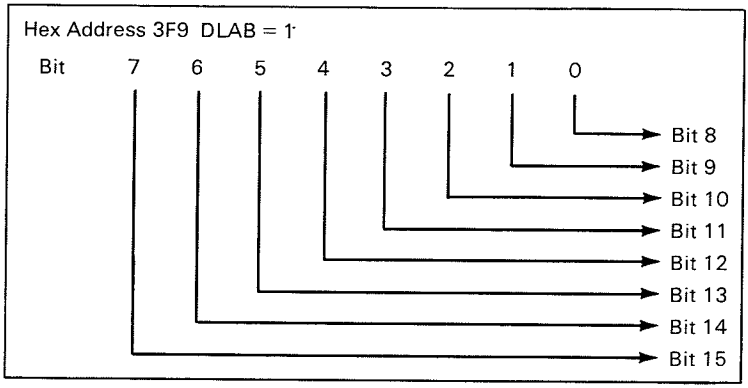
Bit 7: This bit is the divisor latch access bit (DLAB). It must be set high (logical 1) to access the divisor latches of the baud rate generator during a read or write operation. It must be set low (logical 0) to access the receiver buffer, the transmitter holding register, or the interrupt enable register.

Programmable Baud Rate Generator

The INS8250 contains a programmable baud rate generator that is capable of taking the clock input (1.8432 MHz) and dividing it by any divisor from 1 to ($2^{16}-1$). The output frequency of the baud generator is 16 x the baud rate [divisor # = (frequency input)/(baud rate x 16)]. Two 8-bit latches store the divisor in a 16-bit binary format. These divisor latches must be loaded during initialization in order to ensure desired operation of the baud rate generator. Upon loading either of the divisor latches, a 16-bit baud counter is immediately loaded. This prevents long counts on initial load.



Divisor Latch Least Significant Bit (DLL)



Divisor Latch Most Significant Bit (DLM)

The following figure illustrates the use of the baud rate generator with a frequency of 1.8432 MHz. For baud rates of 9600 and below, the error obtained is minimal.

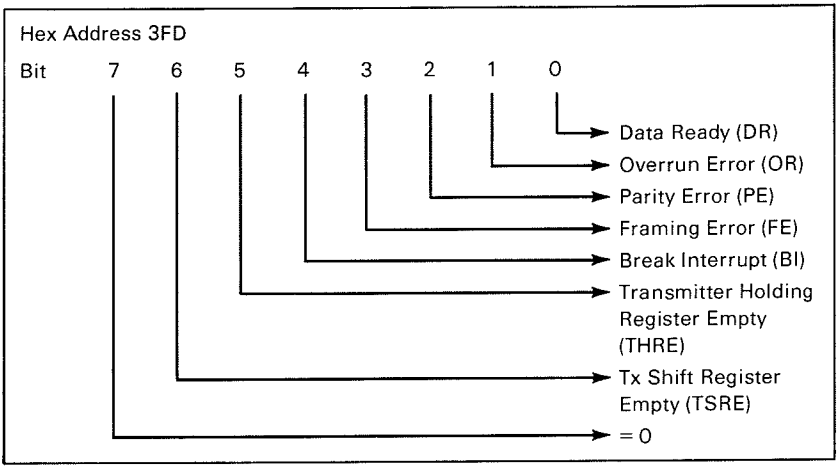
Note: The maximum operating frequency of the baud generator is 3.1 MHz. In no case should the data rate be greater than 9600 baud.

Desired Baud Rate	Divisor Used to Generate 16x Clock (Decimal)	(Hex)	Percent Error Difference Between Desired and Actual
50	2304	900	—
75	1536	600	—
110	1047	417	0.026
134.5	857	359	0.058
150	768	300	—
300	384	180	—
600	192	0C0	—
1200	96	060	—
1800	64	040	—
2000	58	03A	0.69
2400	48	030	—
3600	32	020	—
4800	24	018	—
7200	16	010	—
9600	12	00C	—

Baud Rate at 1.843 MHz

Line Status Register

This 8-bit register provides status information on the processor concerning the data transfer. The contents of the line status register are indicated and described below:



Line Status Register (LSR)

Bit 0: This bit is the receiver data ready (DR) indicator. Bit 0 is set to a logical 1 whenever a complete incoming character has been received and transferred into the receiver buffer register. Bit 0 may be reset to a logical 0 either by the processor reading the data in the receiver buffer register or by writing a logical 0 into it from the processor.

Bit 1: This bit is the overrun error (OE) indicator. Bit 1 indicates that data in the receiver buffer register was not read by the processor before the next character was transferred into the receiver buffer register, thereby destroying the previous character. The OE indicator is reset whenever the processor reads the contents of the line status register.

Bit 2: This bit is the parity error (PE) indicator. Bit 2 indicates that the received data character does not have the correct even or odd parity, as selected by the even parity-select bit. The PE bit is set to a logical 1 upon detection of a parity error and is reset to a logical 0 whenever the processor reads the contents of the line status register.

Bit 3: This bit is the framing error (FE) indicator. Bit 3 indicates that the received character did not have a valid stop bit. Bit 3 is set to a logical 1 whenever the stop bit following the last data bit or parity is detected as a zero bit (spacing level).

Bit 4: This bit is the break interrupt (BI) indicator. Bit 4 is set to a logical 1 whenever the received data input is held in the spacing (logical 0) state for longer than a full word transmission time (that is, the total time of start bit + data bits + parity +stop bits).

Note: Bits 1 through 4 are the error conditions that produce a receiver line status interrupt whenever any of the corresponding conditions are detected.

Bit 5: This bit is the transmitter holding register empty (THRE) indicator. Bit 5 indicates that the INS8250 is ready to accept a new character for transmission. In addition, this bit causes the INS8250 to issue an interrupt to the processor when the transmit holding register empty interrupt enable is set high. The THRE bit is set to a logical 1 when a character is transferred from the transmitter holding register into the transmitter shift register. The bit is reset to logical 0 concurrently with the loading of the transmitter holding register by the processor.

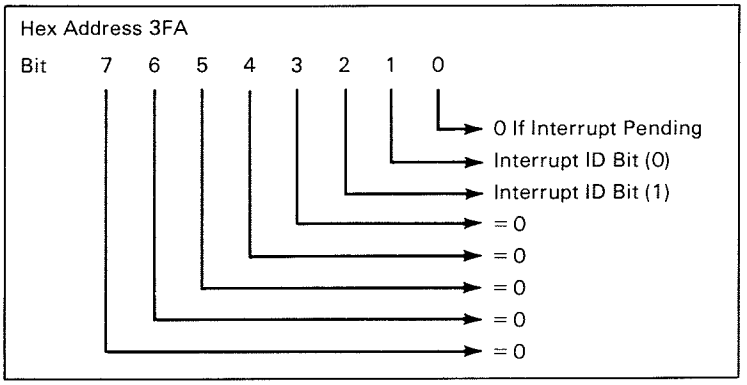
Bit 6: This bit is the transmitter shift register empty (TSRE) indicator. Bit 6 is set to a logical 1 whenever the transmitter shift register is idle. It is reset to logical 0 upon a data transfer from the transmitter holding register to the transmitter shift register. Bit 6 is a read-only bit.

Bit 7: This bit is permanently set to logical 0.

Interrupt Identification Register

The INS8250 has an on-chip interrupt capability that allows for complete flexibility in interfacing to all the popular microprocessors presently available. In order to provide minimum software overhead during data character transfers, the INS8250 prioritizes interrupts into four levels: receiver line status (priority 1), received data ready (priority 2), transmitter holding register empty (priority 3), and modem status (priority 4).

Information indicating that a prioritized interrupt is pending and the type of prioritized interrupt is stored in the interrupt identification register. Refer to the "Interrupt Control Functions" table. The interrupt identification register (IIR), when addressed during chip-select time, freezes the highest priority interrupt pending, and no other interrupts are acknowledged until that particular interrupt is serviced by the processor. The contents of the IIR are indicated and described below.



Interrupt Identification Register (IIR)

Bit 0: This bit can be used in either a hard-wired prioritized or polled environment to indicate whether an interrupt is pending and the IIR contents may be used as a pointer to the appropriate interrupt service routine. When bit 0 is a logical 1, no interrupt is pending and polling (if used) is continued.

Bits 1 and 2: These two bits of the IIR are used to identify the highest priority interrupt pending as indicated in the "Interrupt Control Functions" table.

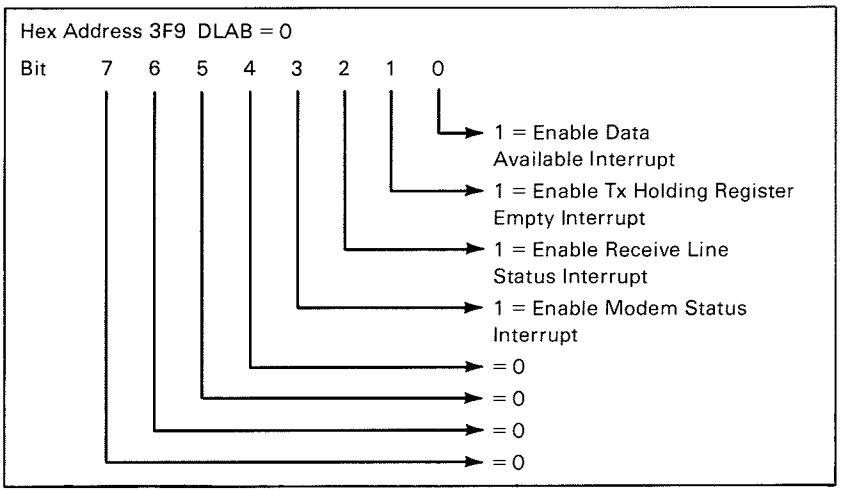
Bits 3 through 7: These five bits of the IIR are always logical 0.

Interrupt ID Register			Interrupt Set and Reset Functions			
Bit 2	Bit 1	Bit 0	Priority Level	Interrupt Type	Interrupt Source	Interrupt Reset Control
0	0	1	—	None	None	—
1	1	0	Highest	Receiver Line Status	Overrun Error or Parity Error or Framing Error or Break Interrupt	Reading the Line Status Register
1	0	0	Second	Received Data Available	Receiver Data Available	Reading the Receiver Buffer Register
0	1	0	Third	Transmitter Holding Register Empty	Transmitter Holding Register Empty	Reading the IIR Register (if source of interrupt) or Writing into the Transmitter Holding Register
0	0	0	Fourth	Modem Status	Clear to Send or Data Set Ready or Ring Indicator or Received Line Signal Direct	Reading the Modem Status Register

Interrupt Control Functions

Interrupt Enable Register

This eight-bit register enables the four types of interrupt of the INS8250 to separately activate the chip interrupt (INTRPT) output signal. It is possible to totally disable the interrupt system by resetting bits 0 through 3 of the interrupt enable register. Similarly, by setting the appropriate bits of this register to a logical 1, selected interrupts can be enabled. Disabling the interrupt system inhibits the interrupt identification register and the active (high) INTRPT output from the chip. All other system functions operate in their normal manner, including the setting of the line status and modem status registers. The contents of the interrupt enable register are indicated and described below:



Interrupt Enable Register (IER)

Bit 0: This bit enables the received data available interrupt when set to logical 1.

Bit 1: This bit enables the transmitter holding register empty interrupt when set to logical 1.

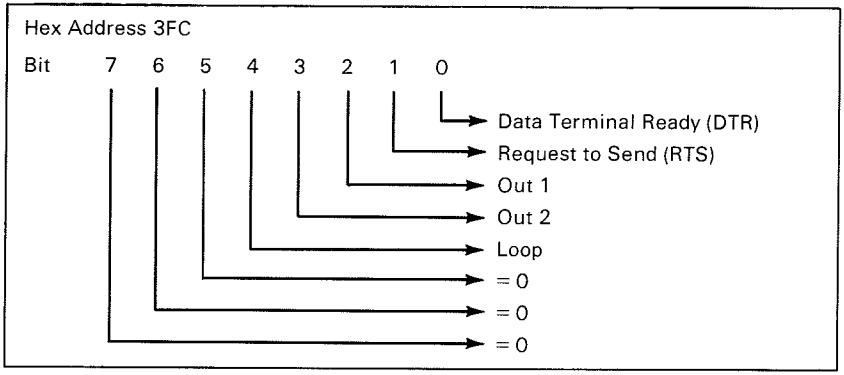
Bit 2: This bit enables the receiver line status interrupt when set to logical 1.

Bit 3: This bit enables the modem status interrupt when set to logical 1.

Bits 4 through 7: These four bits are always logical 0.

Modem Control Register

This eight-bit register controls the interface with the modem or data set (or peripheral device emulating a modem). The contents of the modem control register are indicated and described below:



Modem Control Register (MCR)

Bit 0: This bit controls the data terminal ready ($\overline{\text{DTR}}$) output. When bit 0 is set to logical 1, the $\overline{\text{DTR}}$ output is forced to a logical 0. When bit 0 is reset to a logical 0, the $\overline{\text{DTR}}$ output is forced to a logical 1.

Note: The $\overline{\text{DTR}}$ output of the INS8250 may be applied to an EIA inverting line driver (such as the DS1488) to obtain the proper polarity input at the succeeding modem or data set.

Bit 1: This bit controls the request to send ($\overline{\text{RTS}}$) output. Bit 1 affects the $\overline{\text{RTS}}$ output in a manner identical to that described above for bit 0.

Bit 2: This bit controls the output 1 ($\overline{OUT\ 1}$) signal, which is an auxiliary user-designated output. Bit 2 affects the $\overline{OUT\ 1}$ output in a manner identical to that described above for bit 0.

Bit 3: This bit controls the output 2 ($\overline{OUT\ 2}$) signal, which is an auxiliary user-designated output. Bit 3 affects the $\overline{OUT\ 2}$ output in a manner identical to that described above for bit 0.

Bit 4: This bit provides a loopback feature for diagnostic testing of the INS8250. When bit 4 is set to logical 1, the following occurs: the transmitter serial output (SOUT) is set to the marking (logical 1) state; the receiver serial input (SIN) is disconnected; the output of the transmitter shift register is "looped back" into the receiver shift register input; the four modem control inputs ($\overline{CTS}$, $\overline{DRS}$, $\overline{RLSD}$, and $\overline{RI}$) are disconnected; and the four modem control outputs ($\overline{DTR}$, $\overline{RTS}$, $\overline{OUT\ 1}$, and $\overline{OUT\ 2}$) are internally connected to the four modem control inputs. In the diagnostic mode, data that is transmitted is immediately received. This feature allows the processor to verify the transmit- and receive-data paths of the INS8250.

In the diagnostic mode, the receiver and transmitter interrupts are fully operational. The modem control interrupts are also operational but the interrupts' sources are now the lower four bits of the modem control register instead of the four modem control inputs. The interrupts are still controlled by the interrupt enable register.

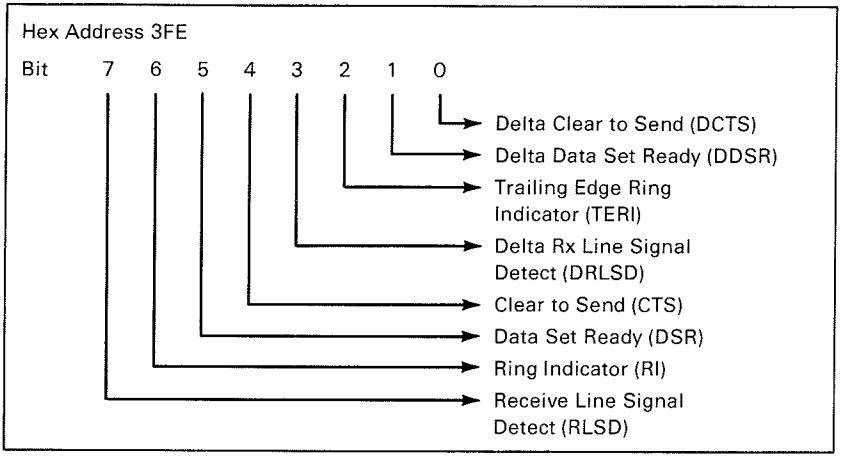
The INS8250 interrupt system can be tested by writing into the lower four bits of the modem status register. Setting any of these bits to a logical 1 generates the appropriate interrupt (if enabled). The resetting of these interrupts is the same as in normal INS8250 operation. To return to normal operation, the registers must be reprogrammed for normal operation and then bit 4 of the modem control register must be reset to logical 0.

Bits 5 through 7: These bits are permanently set to logical 0.

Modem Status Register

This eight-bit register provides the current state of the control lines from the modem (or peripheral device) to the processor. In addition to this current-state information, four bits of the modem status register provide change information. These bits are set to a logical 1 whenever a control input from the modem changes state. They are reset to logical 0 whenever the processor reads the modem status register.

The content of the modem status register are indicated and described below:



Modem Status Register (MSR)

Bit 0: This bit is the delta clear to send (DCTS) indicator. Bit 0 indicates that the $\overline{CTS}$ input to the chip has changed state since the last time it was read by the processor.

Bit 1: This bit is the delta data set ready (DDSR) indicator. Bit 1 indicates that the $\overline{DRS}$ input to the chip has changed since the last time it was read by the processor.

Bit 2: This bit is the trailing edge of ring indicator (TERI) detector. Bit 2 indicates that the $\overline{RI}$ input to the chip has changed from an on (logical 1) to an off (logical 0) condition.

Bit 3: This bit is the delta received line signal detector (DRLSD) indicator. Bit 3 indicates that the $\overline{\text{RLSD}}$ input to the chip has changed state.

Note: Whenever bit 0, 1, 2, or 3 is set to a logical 1, a modem status interrupt is generated.

Bit 4: This bit is the complement of the clear to send ($\overline{\text{CTS}}$) input. If bit 4 (LOOP) of the MCR is set to a logical 1, this is equivalent to RTS in the MCR.

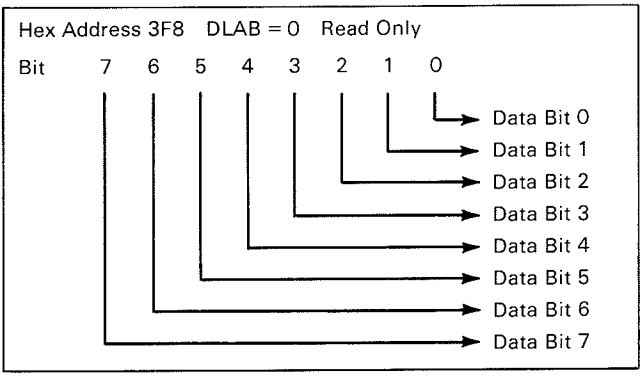
Bit 5: This bit is the complement of the data set ready ($\overline{\text{DSR}}$) input. If bit 4 of the MCR is set to a logical 1, this bit is equivalent to DTR in the MCR.

Bit 6: This bit is the complement of the ring indicator ($\overline{\text{RI}}$) input. If bit 4 of the MCR is set to a logical 1, this bit is equivalent to OUT 1 in the MCR.

Bit 7: This bit is the complement of the received line signal detect ($\overline{\text{RLSD}}$) input. If bit 4 of the MCR is set to a logical 1, this bit is equivalent to OUT 2 of the MCR.

Receiver Buffer Register

The receiver buffer register contains the received character as defined below:

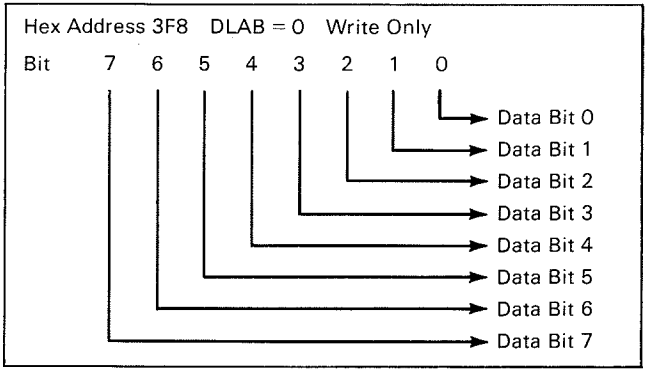


Receiver Buffer Register (RBR)

Bit 0 is the least significant bit and is the first bit serially received.

Transmitter Holding Register

The transmitter holding register contains the character to be serially transmitted and is defined below:

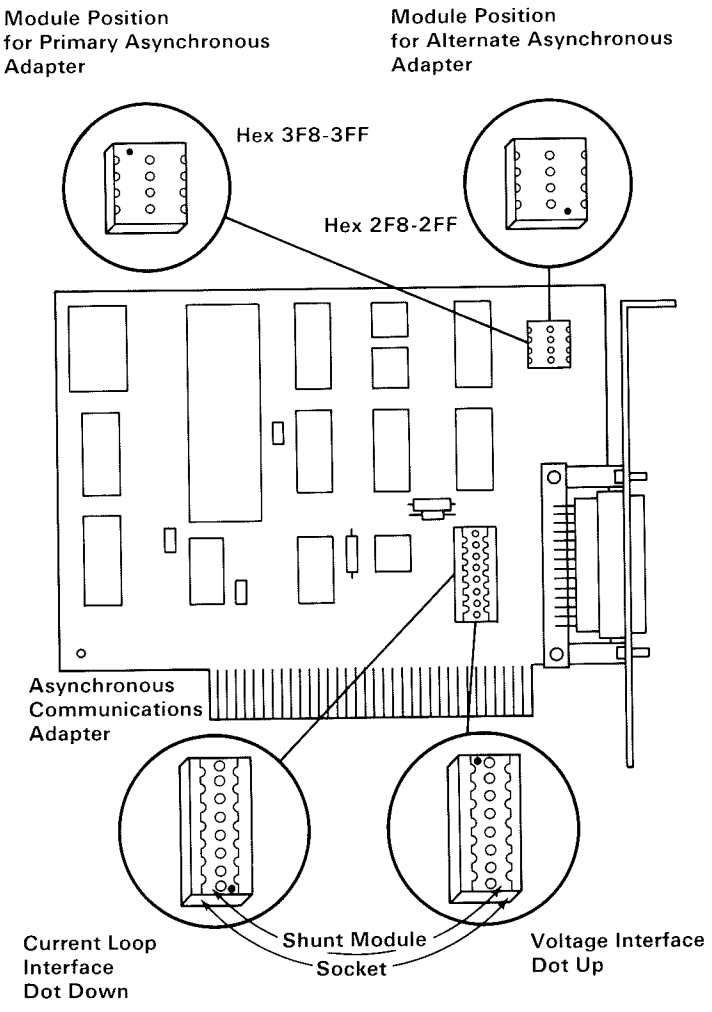


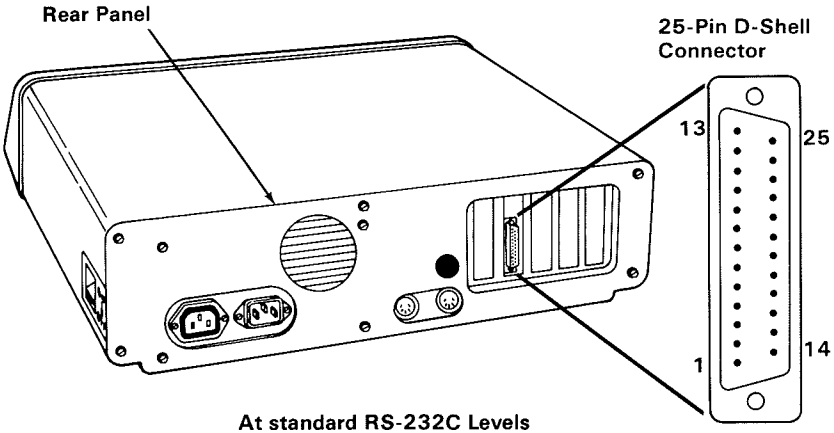
Transmitter Holding Register (THR)

Bit 0 is the least significant bit and is the first bit serially transmitted.

Selecting the Interface Format and Adapter Address

The voltage or current loop interface and adapter address are selected by plugging the programmed shunt modules with the locator dots up or down. See the figure below for the configurations.





At standard RS-232C Levels
(with exception of current loops)

	Description	Pin	
	NC	1	
←	Transmitted Data	2	
→	Received Data	3	
←	Request to Send	4	
→	Clear to Send	5	
→	Data Set Ready	6	
	Signal Ground	7	
→	Received Line Signal Detector	8	
←	+Transmit Current Loop Data	9	
	NC	10	
←	-Transmit Current Loop Data	11	
	NC	12	Asynchronous Communications Adapter (RS-232C)
	NC	13	
	NC	14	
	NC	15	
	NC	16	
	NC	17	
→	+Receive Current Loop Data	18	
	NC	19	
←	Data Terminal Ready	20	
	NC	21	
→	Ring Indicator	22	
	NC	23	
	NC	24	
→	-Receive Current Loop Return	25	

External Device

Note: To avoid inducing voltage surges on interchange circuits, signals from interchange circuits shall be used to drive inductive devices, such as relay coils.

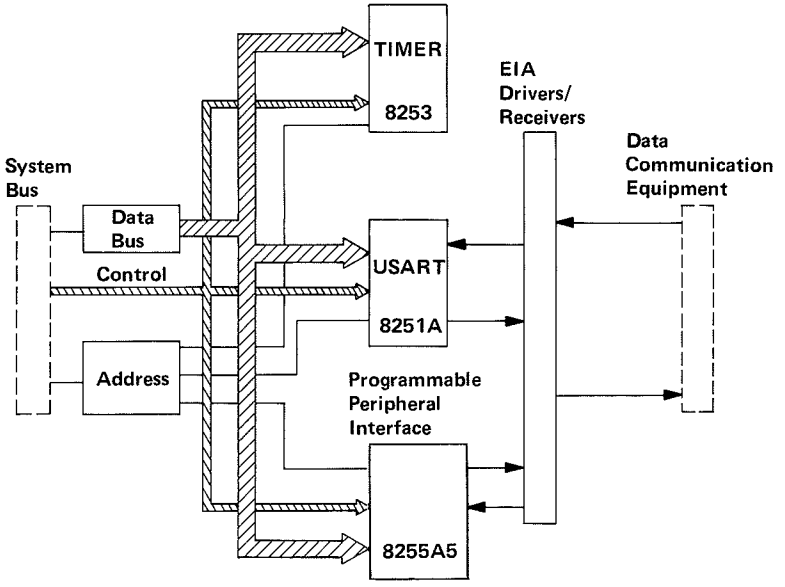
Connector Specifications

Binary Synchronous Communications Adapter

The binary synchronous communication (BSC) adapter is a 4-inch high by 7.5-inch wide card that provides an RS232C-compatible communication interface for the IBM Personal Computer. All system control, voltage, and data signals are provided through a 2- by 31-position card-edge tab. External interface is in the form of EIA drivers and receivers connected to an RS232C, standard 25-pin, D-shell connector.

The adapter is programmed by communication software to operate in binary synchronous mode. Maximum transmission rate is 9600 bits per second (bps). The heart of the adapter is an Intel 8251A Universal Synchronous/Asynchronous Receiver/Transmitter (USART). An Intel 8255A-5 programmable peripheral interface (PPI) is also used for an expanded modem interface, and an Intel 8253-5 programmable interval timer provides time-outs and generates interrupts.

The following is a block diagram of the BSC adapter.



BSC Adapter Block Diagram

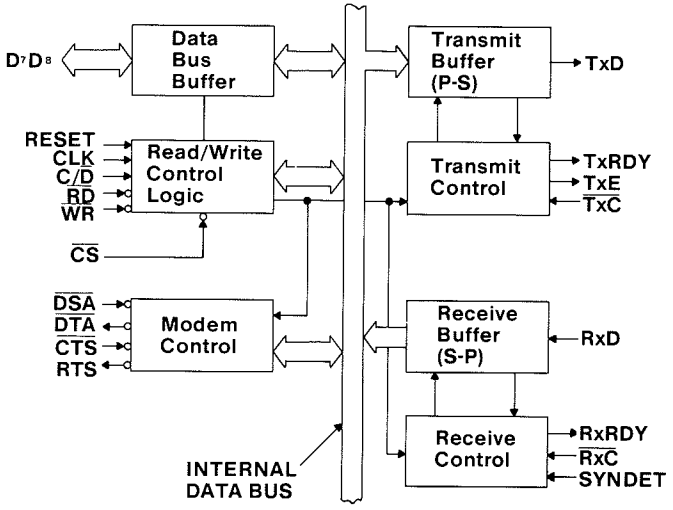
Functional Description

8251A Universal Synchronous/Asynchronous Receiver/Transmitter

The 8251A operational characteristics are programmed by the system unit's software, and it can support virtually any form of synchronous data technique currently in use. In the configuration being described, the 8251A is used for IBM's binary synchronous communications (BSC) protocol in half-duplex mode.

Operation of the 8251A is started by programming the communications format, then entering commands to tell the 8251A what operation is to be performed. In addition, the 8251A can pass device status to the system unit by doing a Status Read operation. The sequence of events to accomplish this are mode instruction, command instruction, and status read. Mode instruction must follow a master reset operation. Commands can be issued in the data block at any time during operation of the 8251A.

A block diagram of the 8251A follows:



8251A Block Diagram

Data Bus Buffer

The system unit's data bus interfaces the 8251A through the data bus buffer. Data is transferred or received by the buffer upon execution of input or output instructions from the system unit. Control words, command words, and status information are also transferred through the data bus buffer.

Read/Write Control Logic

The read/write control logic controls the transfer of information between the system unit and the 8251A. It consists of pins designated as RESET, CLK, WR, RD, C/D, and CS.

RESET: The Reset pin is gated by Port B, bit 4 of the 8255, and performs a master reset of the 8251A. The minimum reset pulse width is 6 clock cycles. Clock-cycle duration is determined by the oscillator speed of the processor.

CLK (Clock): The clock generates internal device timing. No external inputs or outputs are referenced to CLK. The input is the system board's bus clock of 4.77 MHz.

WR (Write): An input to WR informs the 8251A that the system unit is writing data or control words to it. The input is the WR signal from the system-unit bus.

RD (Read): An input to RD informs the 8251A that the processing unit is reading data or status information from it. The input is the RD signal from the system-unit bus.

C/D (Control/Data): An input on this pin, in conjunction with the WR and RD inputs, informs the 8251A that the word on the data bus is either a data character, a control word, or status information. The input is the low-order address bit from the system board's address bus.

CS (Chip Select): A low on the input selects the 8251A. No reading or writing will occur unless the device is selected. An input is decoded at the adapter from the address information on the system-unit bus.

Modem Control

The 8251A has the following input and output control signals which are used to interface the transmission equipment selected by the user.

DSR (Data Set Ready): The DSR input port is a general-purpose, 1-bit, inverting input port. The 8251A can test its condition with a Status Read operation.

CTS (Clear to Send): A low on this input enables the 8251A to transfer serial data if the TxEnable bit in the command byte is set to 1. If either a TxEnable off or CTS off condition occurs while the transmitter is in operation, the transmitter will send all the data in the USART that was written prior to the TxDisable command, before shutting down.

DTR (Data Terminal Ready): The DTR output port is a general-purpose, 1-bit, inverting output port. It can be set low by programming the appropriate bit in the command instruction word.

RTS (Request to Send): The RTS output signal is a general-purpose, 1-bit, inverting output port. It can be set low by programming the appropriate bit in the Command Instruction word.

Transmitter Buffer

The transmitter buffer accepts parallel data from the data-bus buffer, converts it to a serial bit stream, and inserts the appropriate characters or bits for the BSC protocol. The output from the transmit buffer is a composite serial stream of data on the falling edge of Transmit Clock. The transmitter will begin transferring data upon being enabled, if CTS = 0 (active). The transmit data (TxD) line will be set in the marking state upon receipt of a master reset, or when transmit enable/CTS is off and the transmitter is empty (TxEmpty).

Transmitter Control

Transmitter control manages all activities associated with the transfer of serial data. It accepts and issues the following signals, both externally and internally, to accomplish this function:

TxRDY (Transmitter Ready): This output signals the system unit that the transmitter is ready to accept a data character. The TxRDY output pin is used as an interrupt to the system unit (Level 4) and is masked by turning off Transmit Enable. TxRDY is automatically reset by the leading edge of a WR input signal when a data character is loaded from the system unit.

TxE (Transmitter Empty): This signal is used only as a status register input.

TxC (Transmit Clock): The Transmit Clock controls the rate at which the character is to be transmitted. In synchronous mode, the bit-per-second rate is equal to the TxC frequency. The falling edge of TxC shifts the serial data out of the 8251A.

Receiver Buffer

The receiver accepts serial data, converts it to parallel format, checks for bits or characters that are unique to the communication technique, and sends an "assembled" character to the system unit. Serial data input is received on the RxD (Receive Data) pin, and is clocked in on the rising edge of RxC (Receive Clock).

Receiver Control

This control manages all receiver-related activites. The parity-toggle and parity-error flip-flop circuits are used for parity-error detection, and set the corresponding status bit.

RxRDY (Receiver Ready): This output indicates that the 8251A has a character that is ready to be received by the system unit. RxRDY is connected to the interrupt structure of the system unit (Interrupt Level 3). With Receive Enable off, RxRDY is masked and held in the reset mode. To set RxRDY, the receiver must be enabled, and a character must finish assembly and be transferred to the data output register. Failure to read the received character from the RxData output register before the assembly of the next RxData character will set an overrun-condition error, and the previous character will be lost.

RxC (Receiver Clock): The receiver clock controls the rate at which the character is to be received. The bit rate is equal to the actual frequency of RxC.

SYNDET (Synchronization Detect): This pin is used for synchronization detection and may be used as either input or output, programmable through the control word. It is reset to output-mode-low upon reset. When used as an output (internal synchronization mode), the SYNDET pin will go to 1 to indicate that the 8251A has found the synchronization character in the receive mode. If the 8251A is programmed to use double synchronization characters (bisynchronization as in this application), the SYNDET pin will go to 1 in the middle of the last bit of the second synchronization character. SYNDET is automatically reset for a Status Read operation.

8255A-5 Programmable Peripheral Interface

The 8255A-5 is used on the BSC adapter to provide an expanded modem interface and for internal gating and control functions. It has three 8-bit ports, which are defined by the system during initialization of the adapter. All levels are considered plus active unless otherwise indicated. A detailed description of the ports is in "Programming Considerations" in this section.

8253-5 Programmable Interval Timer

The 8253-5 is driven by a divided-by-two system-clock signal. Its outputs are used as clocking signals and to generate inactivity timeout interrupts. These level 4 interrupts occur when either of the timers reaches its programmed terminal counts. The 8253-5 has the following outputs:

Timer 0: Not used for synchronous-mode operation.

Timer 1: Connected to port A, bit 7 of the 8255 and Interrupt Level 4.

Timer 2: Connected to port A, bit 6 of the 8255 and Interrupt Level 4.

Operation

The complete functional definition of the BSC adapter is programmed by the system software. Initialization and control words are sent out by the system to initialize the adapter and program the communications format in which it operates. Once programmed, the BSC Adapter is ready to perform its communication functions.

Transmit

In synchronous transmission, the TxD output is continuously at a mark level until the system sends its first character, which is a synchronization character to the 8251A. When the CTS line goes on, the first character is serially transmitted. All bits are shifted out on the falling edge of TxC. When the 8251A is ready to receive another character from the system for transmission, it raises TxRDY, which causes a level-4 interrupt.

Once transmission has started, the data stream at the TxD output must continue at the TxC rate. If the system does not provide the 8251A with a data character before the 8251A transmit buffers become empty, the synchronization characters will be automatically inserted in the TxD data stream. In this case, the TxE bit in the status register is raised high to signal that the 8251A is empty and that synchronization characters are being sent out. (Note that this TxE bit is in the status register, and is not the TxE pin on the 8251A). TxE does not go low when SYNC is being shifted out. The TxE status bit is internally reset by a data character being written to the 8251A.

Receive

In synchronous reception, the 8251A will achieve character synchronization, because the hardware design of the BSC adapter is intended for internal synchronization. Therefore, the SYNDET pin on the 8251A is not connected to the adapter circuits. For internal synchronization, the Enter Hunt command should be included in the first command instruction word written. Data on the RxD pin is then sampled in on the rising edge of RxC. The content of the RxD buffer is compared at every bit boundary with the first SYNC character until a match occurs. Because the 8251A has been programmed for two synchronization characters (bisynchronization), the next received character is also compared. When both SYNC characters have been detected, the 8251A ends the hunt mode and is in character synchronization. The SYNDET bit in the status register (not the SYNDET pin) is then set high, and is reset automatically by a Status Read.

Once synchronization has occurred, the 8251A begins to assemble received data bytes. When a character is assembled and ready to be transferred to memory from the 8251A, it raises RxRDY, causing an interrupt level 3 to the system.

If the system has not fetched a previous character by the time another received character is assembled (and an interrupt-level 3 issued by the adapter), the old character will be overwritten, and the overrun error flag will be raised. All error flags can be reset by an error reset operation.

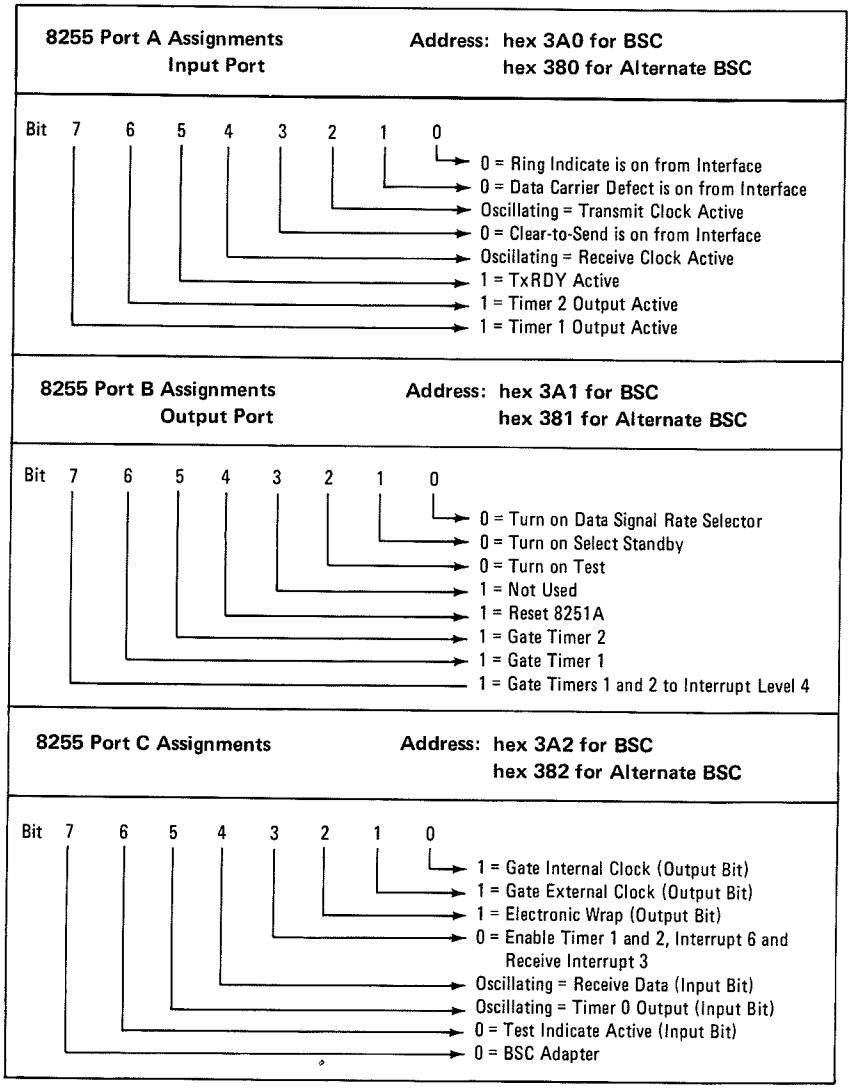
Programming Considerations

Before starting data transmission or reception, the BSC adapter is programmed by the system unit to define control and gating ports, timer functions and counts, and the communication environment in which it is to operate.

Typical Programming Sequence

The 8255A-5 programmable peripheral interface (PPI) is initialized for the proper mode by selecting address hex 3A3 and writing the control word. This defines port A as an input, port B as an output for modem control and gating, and port C for 4-bit input and 4-bit output. The bit descriptions for the 8255A-5 are shown in the following figures. Using an output to port C, the adapter is then set to wrap mode, disallow interrupts, and gate external clocks (address=3A2H, data=0DH). The adapter is now isolated from the communication interface, and initialization continues.

Through bit 4 of 8255 Port B, the 8251A reset pin is brought high, held, then dropped. This resets the internal registers of the 8251A.



The 8253-5 programmable interval timer is used in the synchronous mode to provide inactivity time-outs to interrupt the system unit after a preselected period of time has elapsed from the start of a communication operation. Counter 0 is not used for synchronous operation. Counters 1 and 2 are connected to interrupt-level 4, and are programmed to terminal-count values, which will provide the desired time delay before a level-4 interrupt is generated. These interrupts will indicate to the system software that a predetermined period of time has elapsed without a TxRDY (level 4) or RxRDY (level 3) interrupt being sent to the system unit.

The modes for each counter are programmed by selecting each timer-register address and writing the correct control word for counter operation to the adapter. The mode for counters 1 and 2 is set to 0. The terminal-count values are loaded using control-word bits D4 and D5 to select "load." The 8253-5 Control Word format is shown in the following chart.

Control Word Format **Address hex 3A7**

D_7	D_6	D_5	D_4	D_3	D_2	D_1	D_0
SC1	SC0	RL1	RL0	M2	M1	M0	BCD

Definition of Control

SC – Select Counter:

SC1	SC0	
0	0	Select Counter 0
0	1	Select Counter 1
1	0	Select Counter 2
1	1	Illegal

RL – Read/Load:

RL1	RL0	
0	0	Counter Latching operation
1	0	Read/Load most significant byte only
0	1	Read/Load least significant byte only
1	1	Read/Load least significant byte first, then most significant byte

M – Mode:

M2	M1	M0	
0	0	0	Mode 0

Terminal Count Interrupt

BCD:

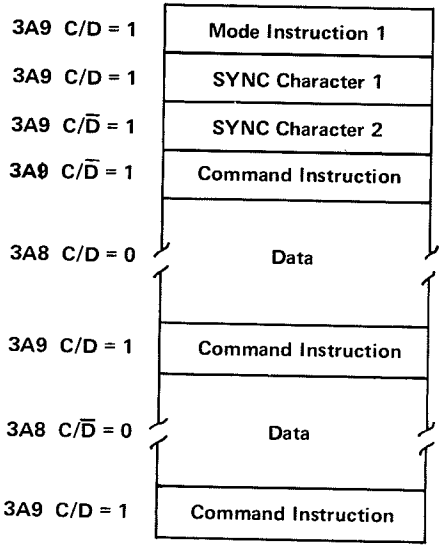
0	Binary Counter 16-bits
1	Binary Coded Decimal (BCD) Counter (4 Decades)

8253-5 Control Word Format

8251A Programming Procedures

After the support devices on the BSC adapter are programmed, the 8251A is loaded with a set of control words that define the communication environment. The control words are split into two formats, mode instruction, and command instruction.

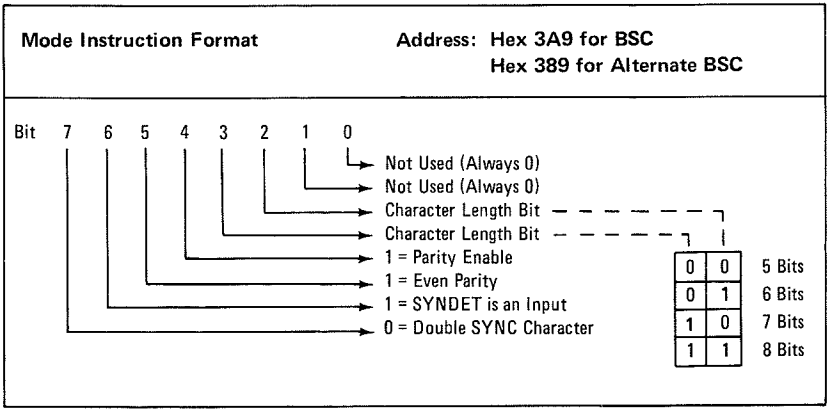
Both the mode and command instructions must conform to a specified sequence for proper device operation. The mode instruction must be inserted immediately after a reset operation, before using the 8251A for data communications. The required synchronization characters for the defined communications technique are next loaded into the 8251A (usually hex 32 for BSC). All control words written to the 8251A after the mode instruction will load the command instruction. Command instructions can be written to the 8251A at any time in the data block during the operation of the 8251A. To return to the mode instruction format, the master reset bit in the command instruction word can be set to start an internal reset operation which automatically places the 8251A back into the mode instruction format. Command instructions must follow the mode instructions or synchronization characters. The following diagram is a typical data block, showing the mode instruction and command instruction.



Typical Data Block

Mode Instruction Definition

The mode instruction defines the general operational characteristics of the 8251A. It follows a reset operation (internal or external). Once the mode instruction has been written to the 8251A by the system unit, synchronization characters or command instructions may be written to the device. The following figure shows the format for the mode instruction.



Bit 0 — Not used; always = 0

Bit 1 — Not used; always = 0

Bit 2 and Bit 3 — These two bits are used together to define the character length. With 0 and 1 as inputs on bits 2 and 3, character lengths of 5, 6, 7, and 8 bits can be established, as shown in the preceding figure.

Bit 4 — In the synchronous mode, parity is enabled from this bit. A 1 on this bit sets parity enable.

Bit 5 — The parity generation/check is set from this bit. For BSC, even parity is used by having bit 5 = 1.

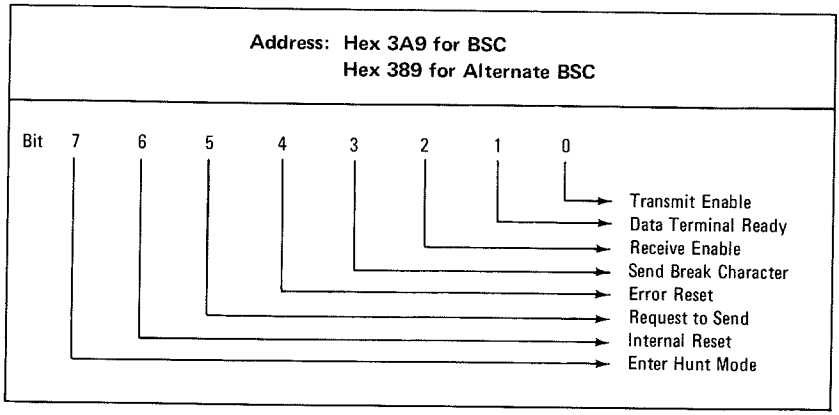
Bit 6 — External synchronization is set by this bit. A 1 on this bit establishes synchronization detection as an input.

Bit 7 — This bit establishes the mode of character synchronization. A 0 is set on this bit to give double character synchronization.

Command-Instruction Format

The command-instruction format defines a status word that is used to control the actual operation of the 8251A. Once the mode instruction has been written to the 8251A, and SYNC characters loaded, all further "Control Writes" to I/O address hex 3A9 or hex 389 will load a command instruction.

Data is transferred by accessing two I/O ports on the 8251A, ports 3A8 and 388. A byte of data can be read from port 3A8 and can be written to port 388.



Command Instruction Format

Bit 0 The Transmit Enable bit sets the function of the 8251A to either enabled (1) or disabled (0).

Bit 1 The Data Terminal Ready bit, when set to 1 will force the data terminal output to 0. This is a one-bit inverting output port.

Bit 2 The Receive Enable bit sets the function to either enable the bit (1), or to disable the bit (0).

Bit 3 The Send Break Character bit is set to 0 for normal BSC operation.

Bit 4 The Error Reset bit is set to 1 to reset error flags from the command instruction.

Bit 5 A 1 on the Request to Send bit will set the output to 0. This is a one-bit inverting output port.

Bit 6 The Internal Reset bit when set to 1 returns the 8251A to mode-instruction format.

Bit 7 The Enter Hunt bit is set to 1 for BSC to enable a search for synchronization characters.

Status Read Definition

In telecommunication systems, the status of the active device must often be checked to determine if errors or other conditions have occurred that require the processor's attention. The 8251A has a status read facility that allows the system software to read the status of the device at anytime during the functional operation. A normal read command is issued by the processor with I/O address hex 3A9 for BSC, and hex 389 for Alternate BSC to perform a status read operation.

The format for a status read word is shown in the figure below. Some of the bits in the status read format have the same meanings as external output pins so the 8251A can be used in a completely polled environment or in an interrupt-driven environment.

Address: Hex 3A9 for BSC Hex 389 for Alternate BSC	
Bits	0 → TxRDY (See Note Below)
	1 → RxRDY
	2 → TxEmpty
	3 → Parity Error (PE Flag On when a Parity Error Occurs)
	4 → Overrun Error (OE Flag On when Overrun Error Occurs)
	5 → Framing Error (Not Used for Synchronous Communications)
	6 → SYNDET
	7 → Data Set Ready (Indicates that DSR is at 0 Level)
Note: TxRDY status bit does not have the same meaning as the 8251A TxRDY output pin. The former is not conditioned by CTS and TxEnable. The latter is conditioned by both CTS and TxEnable.	

Status Read Format

Bit 0 See the Note in the preceding chart.

Bit 1 An output on this bit means a character is ready to be received by the computers 8088 microprocessor.

Bit 2 A 1 on this bit indicates the 8251A has no characters to transmit.

Bit 3 The Parity Error bit sets a flag when errors are detected. It is reset by the error reset in the command instruction.

Bit 4 This bit sets a flag when the computers 8088 microprocessor does not read a character before another one is presented. The 8251A operation is not inhibited by this flag, but the overrun character will be lost.

Bit 5 Not used

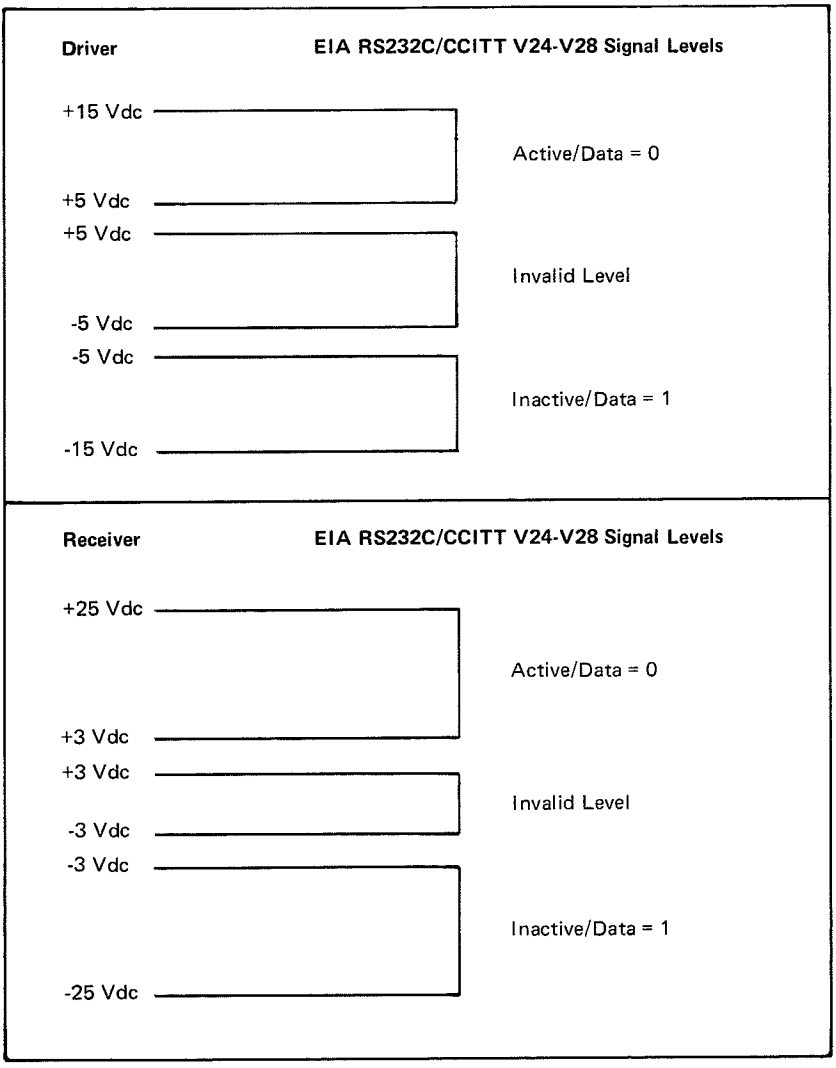
Bit 6 SYNDET goes to 1 when the synchronization character is found in receive mode. For BSC, SYNDET goes high in the middle of the last bit of the second synchronization character.

Bit 7 The Data Set Ready bit is a one bit inverting input. It is used to check modem conditions, such as data-set ready.

Interface Signal Information

The BSC adapter conforms to interface signal levels standardized by the Electronics Industry Association (EIA) RS232C Standard. These levels are shown in the following figure.

Additional lines, not standardized by the EIA, are pins 11, 18, and 25 on the interface connector. These lines are designated as Select Standby, Test, and Test Indicate. Select Standby is used to support the switched network backup facility of a modem that provides this option. Test and Test Indicate support a modem wrap function on modems that are designated for business-machine, controlled-modem wraps.



Interface Voltage Levels

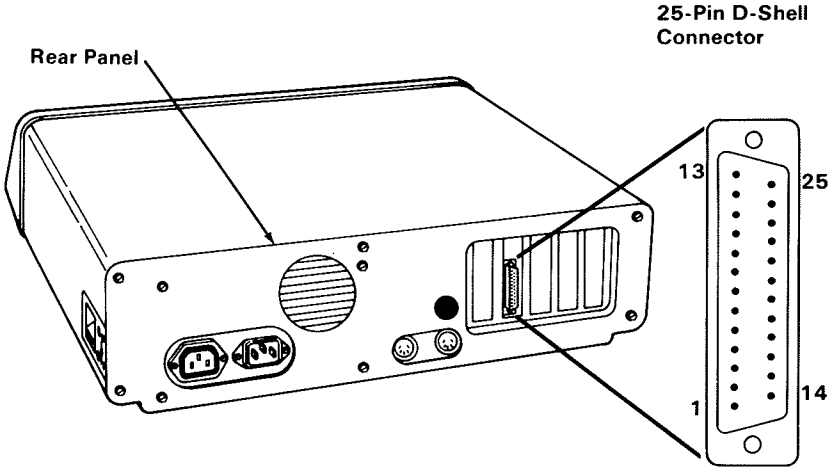
Interrupt Information

Interrupt Level 4: Transmitter Ready
Counter 1
Counter 2

Interrupt Level 3: Receiver Ready

Hex Address		Device	Register Name	Function
Primary	Alternate			
3A0	380	8255	Port A Data	Internal/External Sensing
3A1	381	8255	Port B Data	External Modem Interface
3A2	382	8255	Port C Data	Internal Control
3A3	383	8255	Mode Set	8255 Mode Initialization
3A4	384	8253	Counter 0 LSB	Not Used in Synch Mode
3A4	384	8253	Counter 0 MSB	Not Used in Synch Mode
3A5	385	8253	Counter 1 LSB	Inactivity Time-Outs
3A5	385	8253	Counter 1 MSB	Inactivity Time-Outs
3A6	386	8253	Counter 2 LSB	Inactivity Time-Outs
3A6	386	8253	Counter 2 MSB	Inactivity Time-Outs
3A7	387	8253	Mode Register	8253 Mode Set
3A8	388	8251	Data Select	Data
3A9	389	8251	Command/Status	Mode/Command USART Status

Device Address Summary



Signal Name — Description	Pin
No Connection	1
Transmitted Data	2
Received Data	3
Request to Send	4
Clear to Send	5
Data Set Ready	6
Signal Ground	7
Received Line Signal Detector	8
No Connection	9
No Connection	10
Select Standby*	11
No Connection	12
No Connection	13
No Connection	14
Transmitter Signal Element Timing	15
No Connection	16
Receiver Signal Element Timing	17
Test (IBM Modems Only)*	18
No Connection	19
Data Terminal Ready	20
No Connection	21
Ring Indicator	22
Data Signal Rate Selector	23
No Connection	24
Test Indicate (IBM Modems Only)*	25

External Device

Binary Synchronous Communications Adapter

*Not standardized by EIA (Electronics Industry Association).

Connector Specifications

Notes:

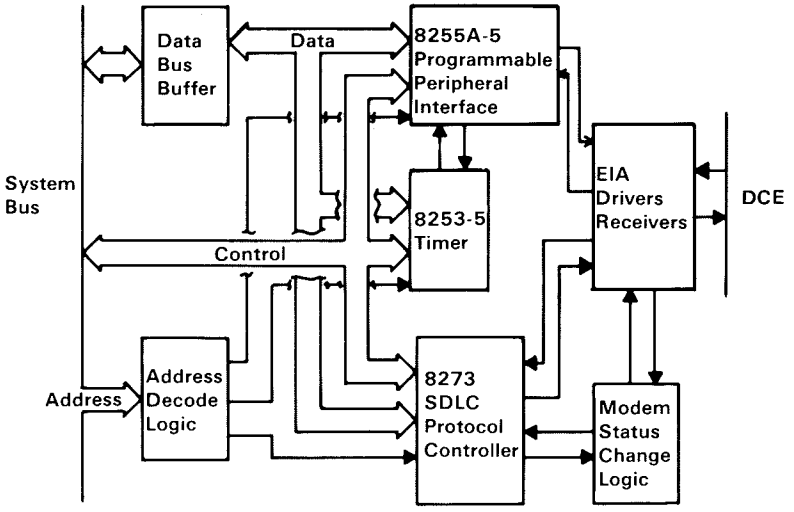
IBM Synchronous Data Link Control (SDLC) Communications Adapter

The SDLC communications adapter system control, voltage, and data signals are provided through a 2 by 31 position card edge tab. Modem interface is in the form of EIA drivers and receivers connecting to an RS232C standard 25-pin, D-shell, male connector.

The adapter is programmed by communications software to operate in a half-duplex synchronous mode. Maximum transmission rate is 9600 bits per second, as generated by the attached modem or other data communication equipment.

The SDLC adapter utilizes an Intel 8273 SDLC protocol controller and an Intel 8255A-5 programmable peripheral interface for an expanded external modem interface. An Intel 8253 programmable interval timer is also provided to generate timing and interrupt signals. Internal test loop capability is provided for diagnostic purposes.

The figure below is a block diagram of the SDLC communications adapter.



SDLC Communications Adapter Block Diagram

The 8273 SDLC protocol control module has the following key features:

- Automatic frame check sequence generation and checking.
- Automatic zero bit insertion and deletion.
- TTL compatibility.
- Dual internal processor architecture, allowing frame level command structure and control of data channel with minimal system processor intervention.

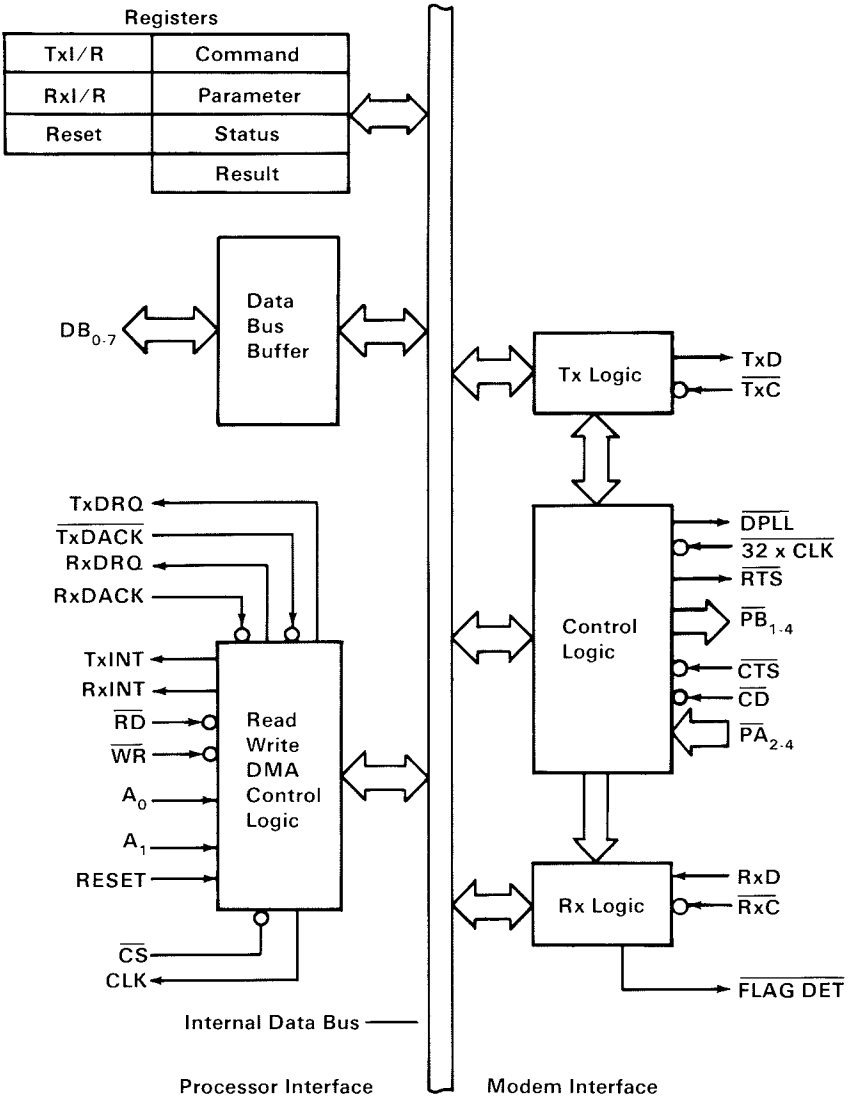
The 8273 SDLC protocol controller operations, whether transmission, reception, or port read, are each comprised of three phases:

Command	Commands and/or parameters for the required operation are issued by the processor.
Execution	Executes the command, manages the data link, and may transfer data to or from memory utilizing direct memory access (DMA), thus freezing the processor except for minimal interruptions.
Result	Returns the outcome of the command by returning interrupt results.

Support of the controller operational phases is through internal registers and control blocks of the 8273 controller.

8273 Protocol Controller Structure

The 8273 module consists of two major interfaces: the processor interface and the modem interface. A block diagram of the 8273 protocol controller module follows.



8273 SDLC Protocol Control Block Diagram

Processor Interface

The processor interface consists of four major blocks: the control/read/write logic (C/R/W), internal registers, data transfer logic, and data bus buffers.

Control/Read/Write Logic

The control/read/write logic is used by the processor to issue commands to the 8273. Once the 8273 receives and executes a command, it returns the results using the C/R/W logic. The logic is supported by seven registers which are addressed by A0, A1, RD, and WR, in addition to CS. A0 and A1 are the two low-order bits of the adapter address-byte. RD and WR are the processor read and write signals present on the system control bus. CS is the chip select, also decoded by the adapter address logic. The table below shows the address of each register using the C/R/W logic.

Address Inputs		Control Inputs			Register
A0	A1	CS	WR	RD	
0	0	0	0	1	Command
0	0	0	1	0	Status
0	1	0	0	1	Parameter
0	1	0	1	0	Result
1	0	0	0	1	Reset
1	0	0	1	0	TxI/R
1	1	0	0	1	None
1	1	0	1	0	RxI/R

8273 SDLC Protocol Controller Register Selection

8273 Control/Read/Write Registers

Command	Operations are initialized by writing the appropriate command byte into this register.
Status	This register provides the general status of the 8273. The status register supplies the processor/adapter handshaking necessary during various phases of the 8273 operation.
Parameter	Additional information that is required to process the command is written into this register. Some commands require more than one parameter.
Immediate Result (Result)	Commands that execute immediately produce a result byte in this register, to be read by the processor.
Transmit Interrupt Results (TxI/R)	Results of transmit operations are passed to the processor from this register. This result generates an interrupt to the processor when the result becomes available.
Receiver Interrupt Results (Rx/I/R)	Results of receive operations are passed to the processor from this register. This result generates an interrupt to the processor when the result becomes available.
Reset	This register provides a software reset function for the 8273.

The other elements of the C/R/W logic are the interrupt lines (RxINT and TxINT). Interrupt priorities are listed in the "Interrupt Information" table in this section. These lines signal the processor that either the transmitter or the receiver requires service (results should be read from the appropriate register), or a data transfer is required. The status of each interrupt line is also reflected by a bit in the status register, so non-interrupt driven operation is also possible by the communication software examining these bits periodically.

Data Interfaces

The 8273 supports two independent data interfaces through the data transfer logic: received data and transmitted data. These interfaces are programmable for either DMA or non-DMA data transfers. Speeds below 9600 bits-per-second may or may not require DMA, depending on the task load and interrupt response time of the processor. The processor DMA controller is used for management of DMA data transfer timing and addressing. The 8273 handles the transfer requests and actual counts of data-block lengths. DMA level 1 is used to transmit and receive data transfers. Dual DMA support is not provided.

Elements of Data Transfer Interface

TxDRQ/RxDRQ	This line requests a DMA to or from memory and is asserted by the 8273.
TxDACK/RxDACK	This line notifies the 8273 that a request has been granted and provides access to data regions. This line is returned by the DMA controller (DACK1 on the system unit control bus is connected to TxDACK/RxDACK on the 8273).
RD (Read)	This line indicates data is to be read from the 8273 and placed in memory. It is controlled by the processor DMA controller.
WR (Write)	This line indicates if data is to be written to the 8273 from memory and is controlled by the processor DMA controller.

To request a DMA transfer, the 8273 raises the DMA request line. Once the DMA controller obtains control of the system bus, it notifies the 8273 that the DRQ is granted by returning DACK, and WR or RD, for a transmit or receive operation, respectively. The DACK and WR or RD signals transfer data between the 8273 and memory, independent of the 8273 chip-select pin (CS). This "hard select" of data into the transmitter or out of the receiver alleviates the need for the normal transmit and receive data registers, addressed by a combination of address lines, CS, and WR or RD.

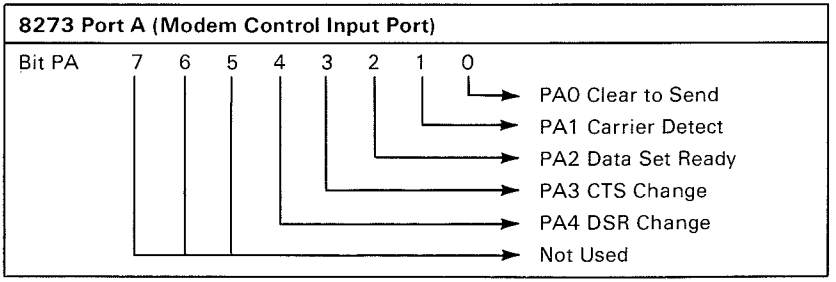
Modem Interface

The modem interface of the 8273 consists of two major blocks: the modem control block and the serial data timing block.

Modem Control Block

The modem control block provides both dedicated and user-defined modem control function. EIA inverting drivers and receivers are used to convert TTL levels to EIA levels.

Port A is a modem control input port. Bits PA0 and PA1 have dedicated functions.



Bit PA0 — This bit reflects the logical state of the clear to send (CTS) pin. The 8273 waits until CTS is active before it starts transmitting a frame. If CTS goes inactive while transmitting, the frame is aborted and the processor is interrupted. A CTS failure will be indicated in the appropriate interrupt-result register.

Bit PA1 — This bit reflects the logical state of the carrier detect pin (CD). CD must be active in sufficient time for reception of a frame's address field. If CD is lost (goes inactive) while receiving a frame, an interrupt is generated with a CD failure result.

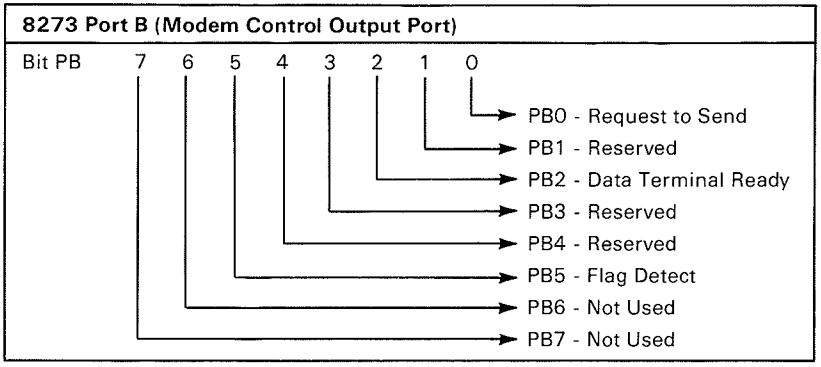
Bit PA2 — This bit is a sense bit for data set ready (DSR).

Bit PA3 — This bit is a sense bit to detect a change in CTS.

Bit PA4 This bit is a sense bit to detect a change in data set ready.

Bits PA5 to PA7 These bits are not used and each is read as a 1 for a read port A command.

Port B is a modem control output port. Bits PB0 and PB5 are dedicated function pins.



Bit PB0 This bit represents the logical state of request to send (RTS). This function is handled automatically by the 8273.

Bit PB1 Reserved.

Bit PB2 Used for data terminal ready.

Bit PB3 Reserved.

Bit PB4 Reserved.

Bit PB5 This bit reflects the state of the flag detect pin. This pin is activated whenever an active receiver sees a flag character.

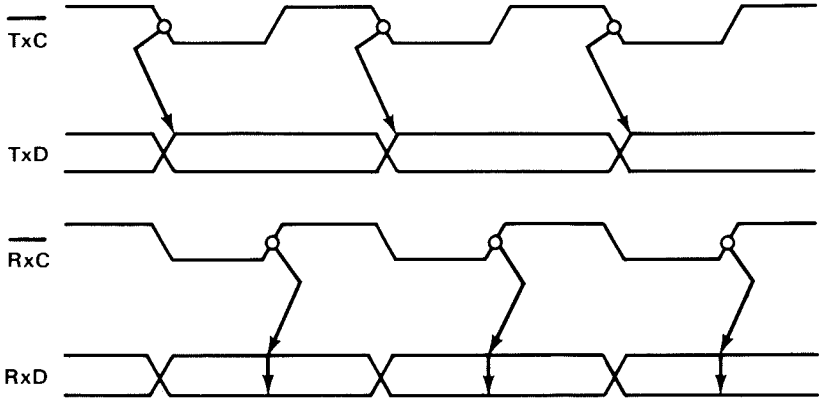
Bit PB6 Not used.

Bit PB7 Not used.

Serial Data Timing Block

The serial data timing block is comprised of two sections: the serial data logic and the digital phase locked loop (DPLL).

Elements of the serial data logic section are the data pins TxD (transmitted data output) and RxD (received data input), and the respective clocks. The leading edge of TxC generates new transmitted data and the trailing edge of RxC is used to capture the received data. The figure below shows the timing for these signals.



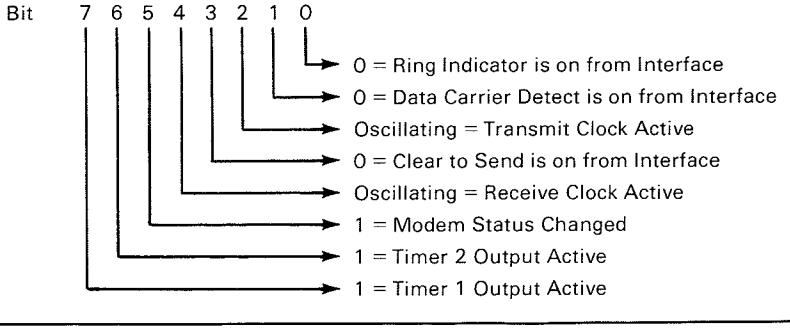
8273 SDLC Protocol Controller Transmit/Receive Timing

The digital phase locked loop provided on the 8273 controller module is utilized to capture looped data in proper synchronization during wrap operations performed by diagnostics.

8255A-5 Programmable Peripheral Interface

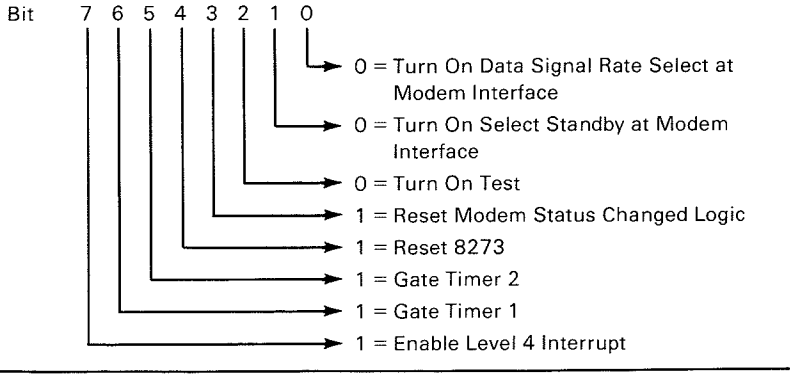
The 8255A-5 contains three 8-bit ports. Descriptions of each bit of these ports are as follows:

8255A-5 Port A Assignments* **Hex Address 380**

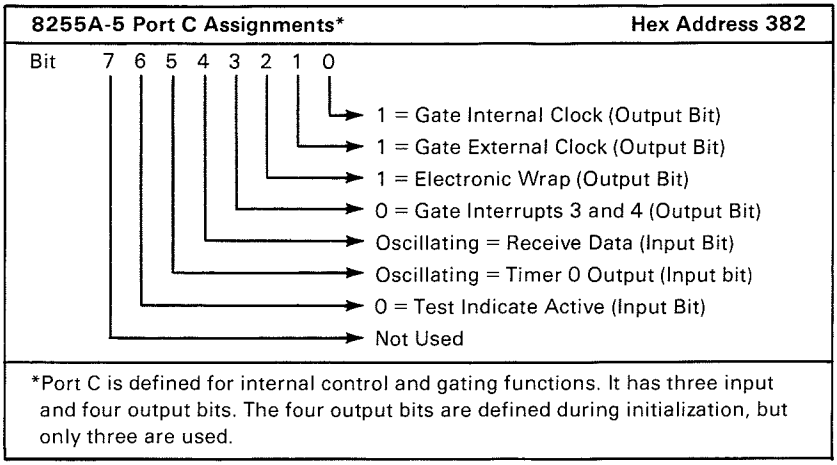


*Port A is defined as an input port

8255A-5 Port B Assignments* **Hex Address 381**



*Port B is defined as an output port



8253-5 Programmable Interval Timer

The 8253-5 is driven by a processor clock signal divided by two. It has the following output:

Timer 0 Programmed to generate a square wave signal, used as an input to timer 2. Also connected to 8253 port C, bit 5.

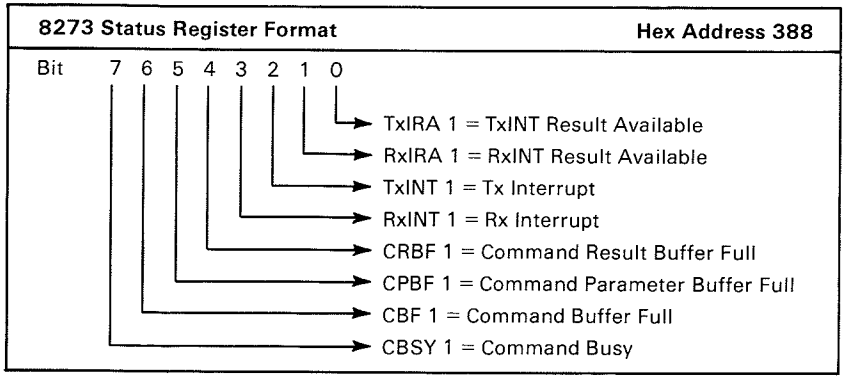
Timer 1 Connected to 8255 port A, bit 7, and interrupt level 4.

Timer 2 Connected to 8255 port A, bit 6, and interrupt level 4.

Programming Considerations

The software aspects of the 8273 involve the communication of both commands from the processor to the 8273 and the return of results of those commands from the 8273 to the processor. Due to the internal processor architecture of the 8273, this system unit/8273 communication is basically a form of interprocessor communication, and must be considered when programming for the SDLC communications adapter.

The protocol for this interprocessor communication is implemented through use of handshaking supplied in the 8273 status register. The bit defintions of this register are shown below.



Bit 0 This bit is the transmitter interrupt result available (TxIRA) bit. This bit is set when the 8273 places an interrupt-result byte in the TxI/R register, and reset when the processor reads the TxI/R register.

Bit 1 This bit is the receiver interrupt result available (RxIRA) bit. It is the corresponding result-available bit for the receiver. It is set when the 8273 places an interrupt-result byte in the RxI/R register and reset when the processor reads the register.

Bit 2 This bit is the transmitter interrupt (TxINT) bit and reflects the state of the TxINT pin. TxINT is set by the 8273 whenever the transmitter needs servicing, and reset when the processor reads the result or performs the data transfer.

Bit 3 This bit is the receiver interrupt (RxINT) bit and is identical to the TxINT, except action is initiated based on receiver interrupt-sources.

Bit 4 This bit is the command result buffer full (CRBF) bit. It is set when the 8273 places a result from an immediate-type command in the result register, and reset when the processor reads the result or performs the data transfer.